



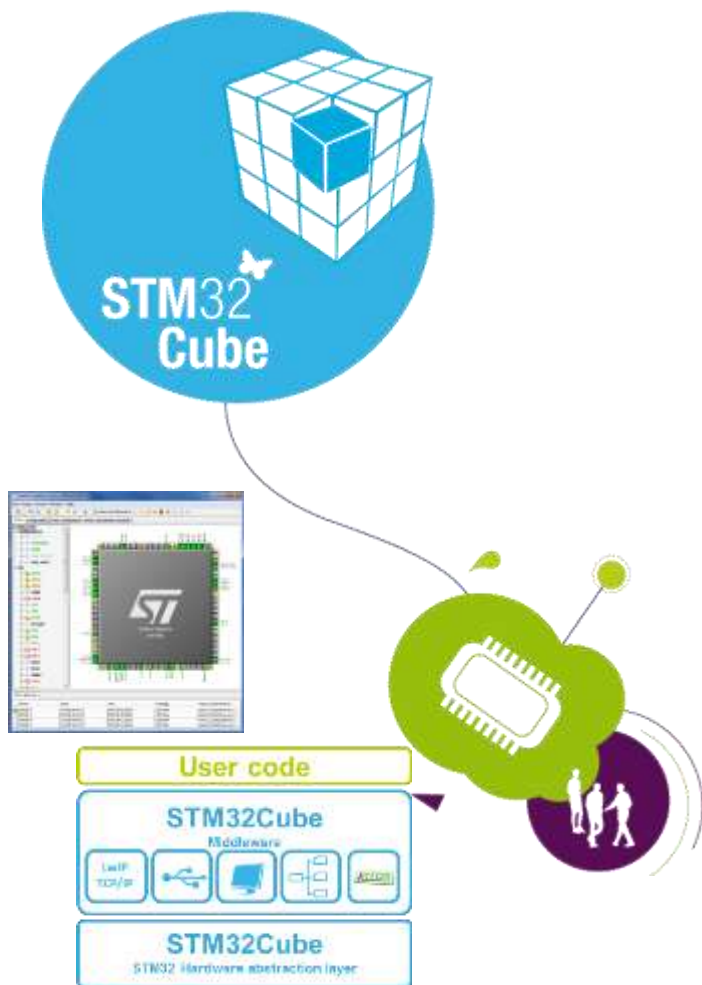
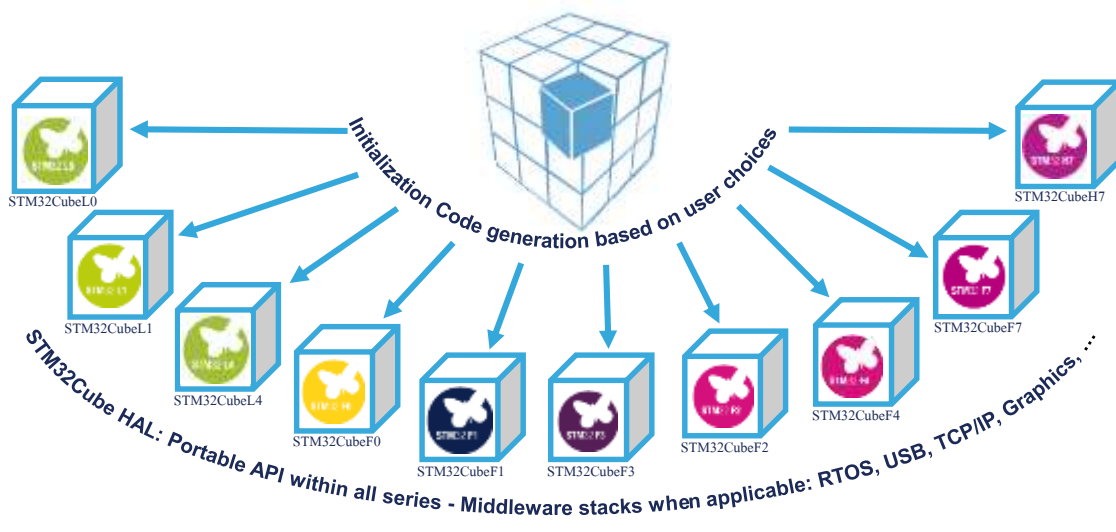
STM32Cube Overview

STM32Cube™ Introduction

2

- STM32Cube™ is an STMicroelectronics original initiative to ease developers life
 - By reducing development efforts
 - By reducing development time
 - By reducing development cost, with free solutions
- STM32Cube™ applies on STM32 portfolio

STM32CubeMX

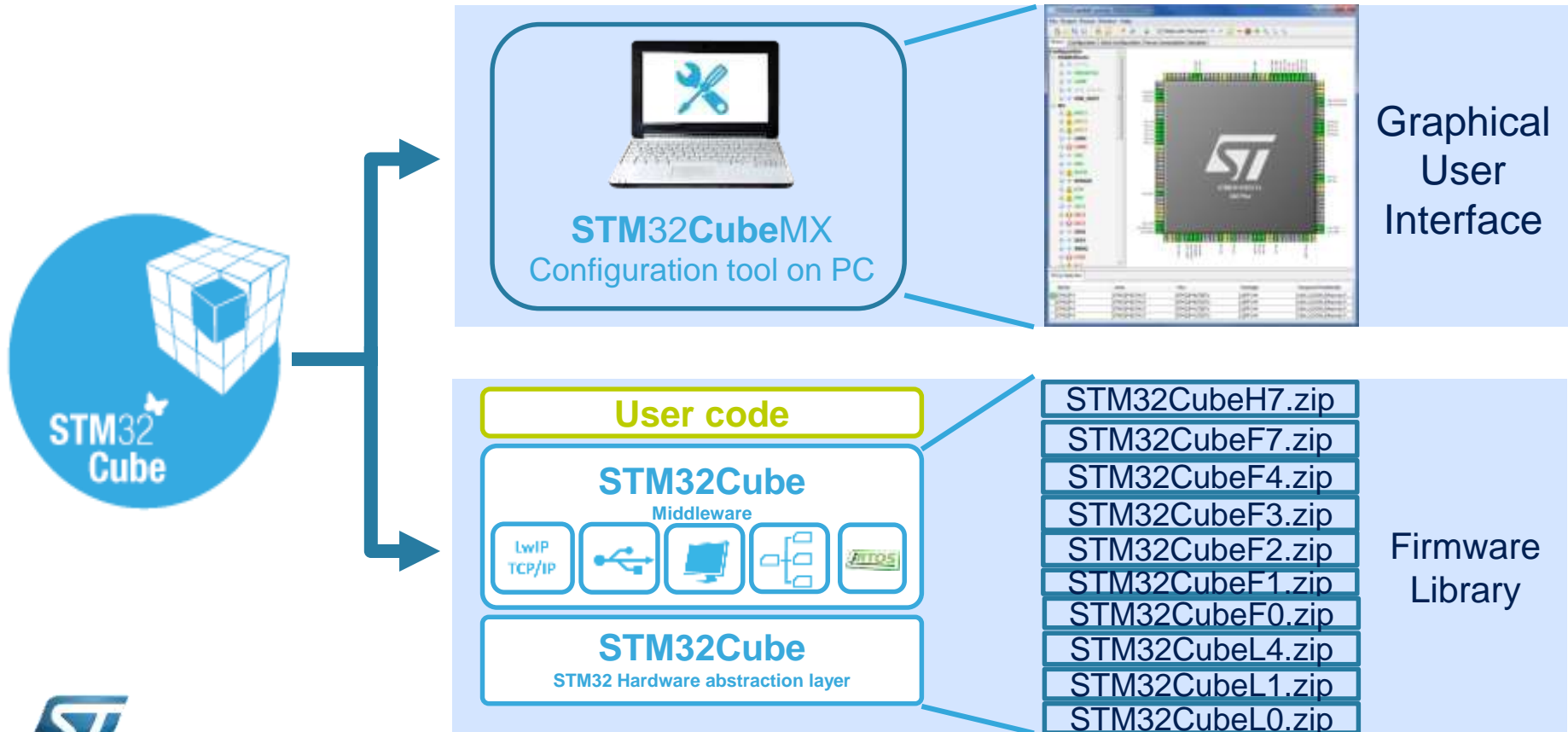


www.st.com/stm32cube

STM32Cube™ Overview

3

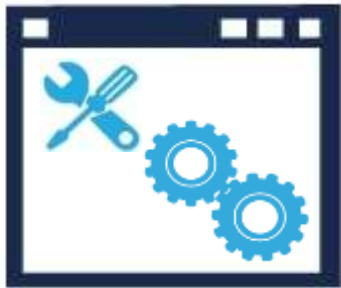
- STM32Cube™ is a software development platform that combines
 - A *PC software configuration tool* called **STM32CubeMX**
 - *STM32 embedded software* bricks called **STM32CubeFx/Lx**



STM32Cube Work Flow

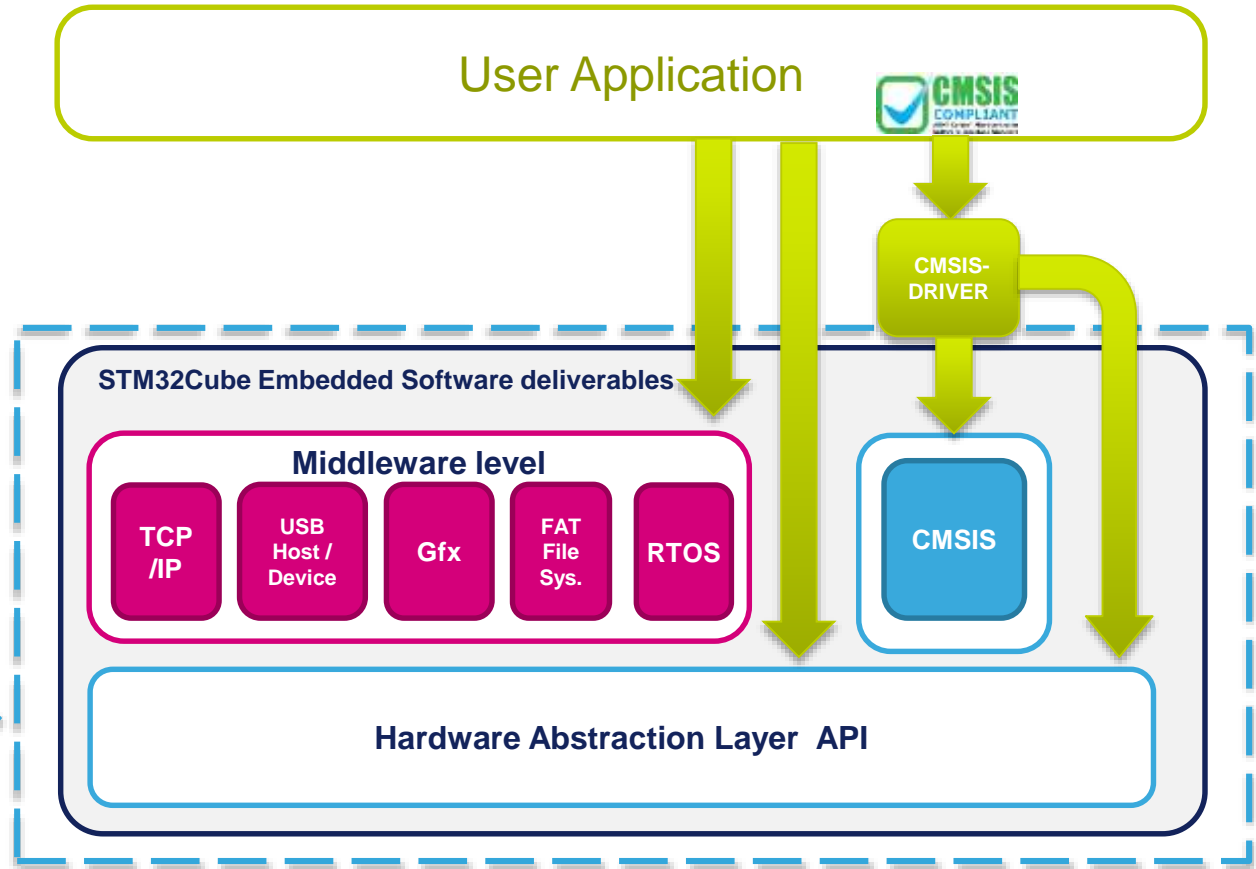
4

STM32CubeMX
Configuration tool on PC



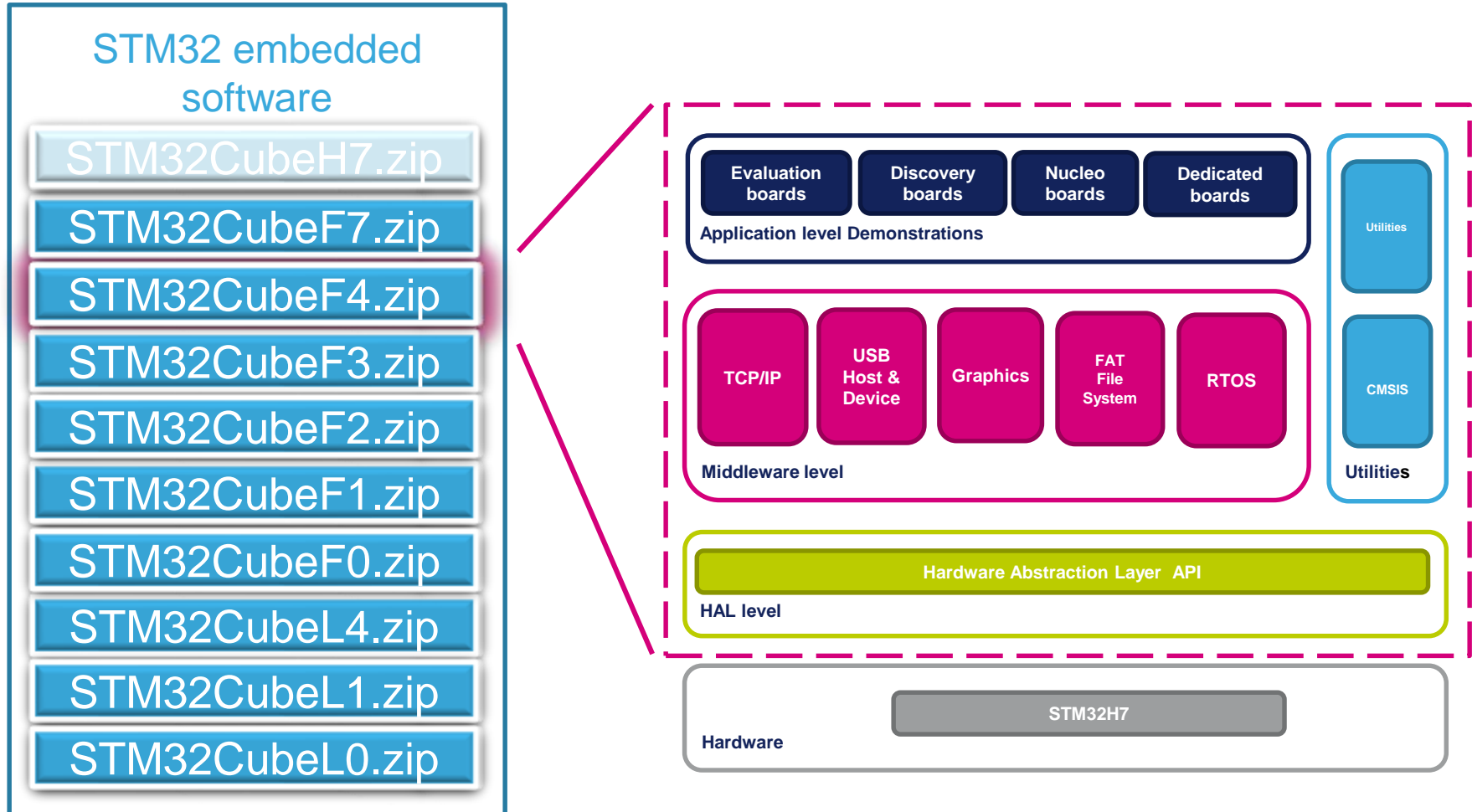
STM32F0	STM32F1	STM32F2
STM32F3	STM32F4	STM32F7
STM32H0	STM32L0	STM32L1
STM32L4		

C code generation
for initialization,
depending on user
choices



STM32CubeFx/Lx FW Package

5

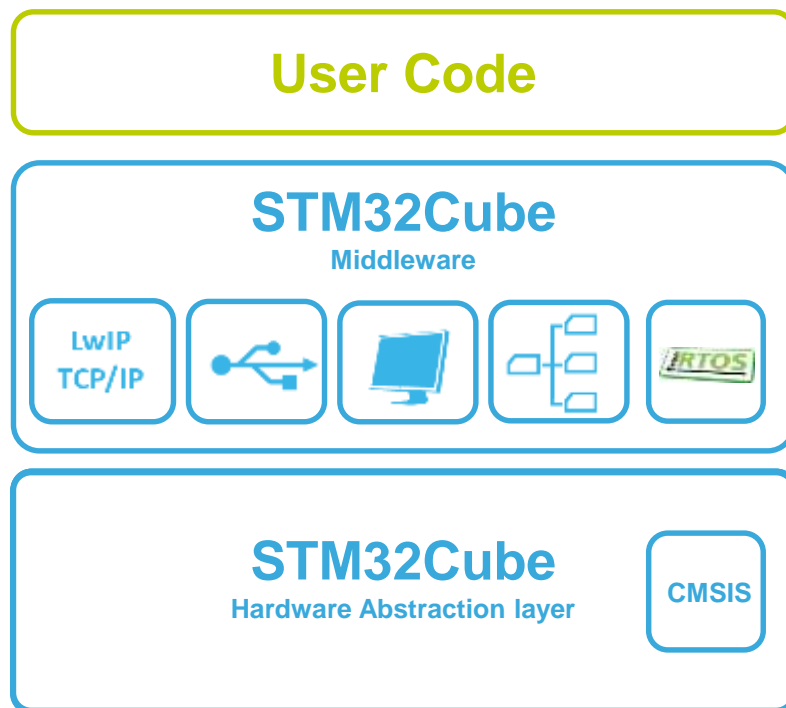


Downloadable manually from www.st.com/stm32cube
or via **STM32CubeMX** download libraries menu

STM32Cube V1

STM32CubeFx/Lx FW Package

6

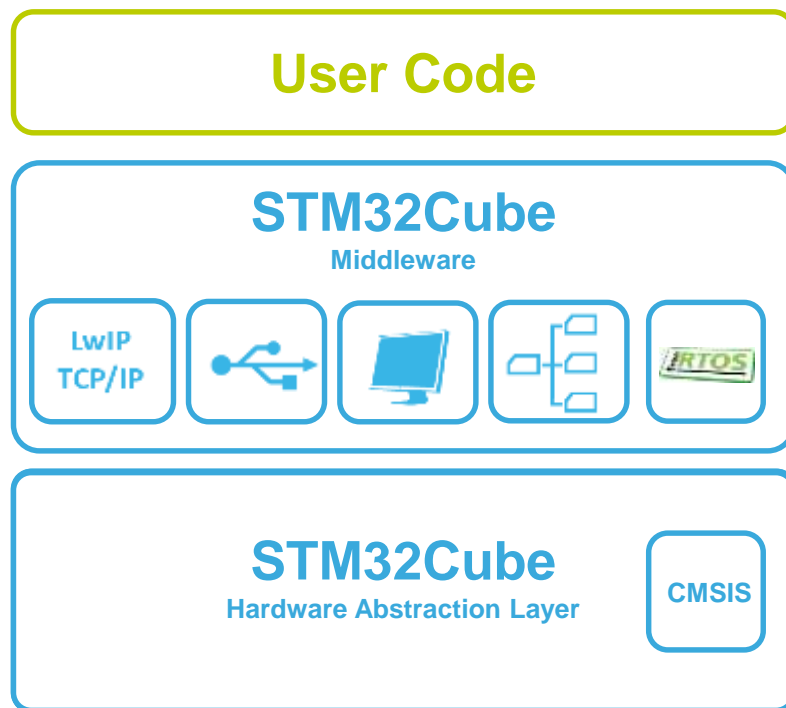


- Abstraction of STM32
 - Through portable APIs
- High STM32 coverage
 - Most of peripherals covered
- Production Ready
 - Quality: CodeSonar™
- Complete
 - **>150 peripheral examples!**
- Permissive terms
 - Open source BSD license

STM32Cube V1

STM32CubeFx/Lx FW Package

7

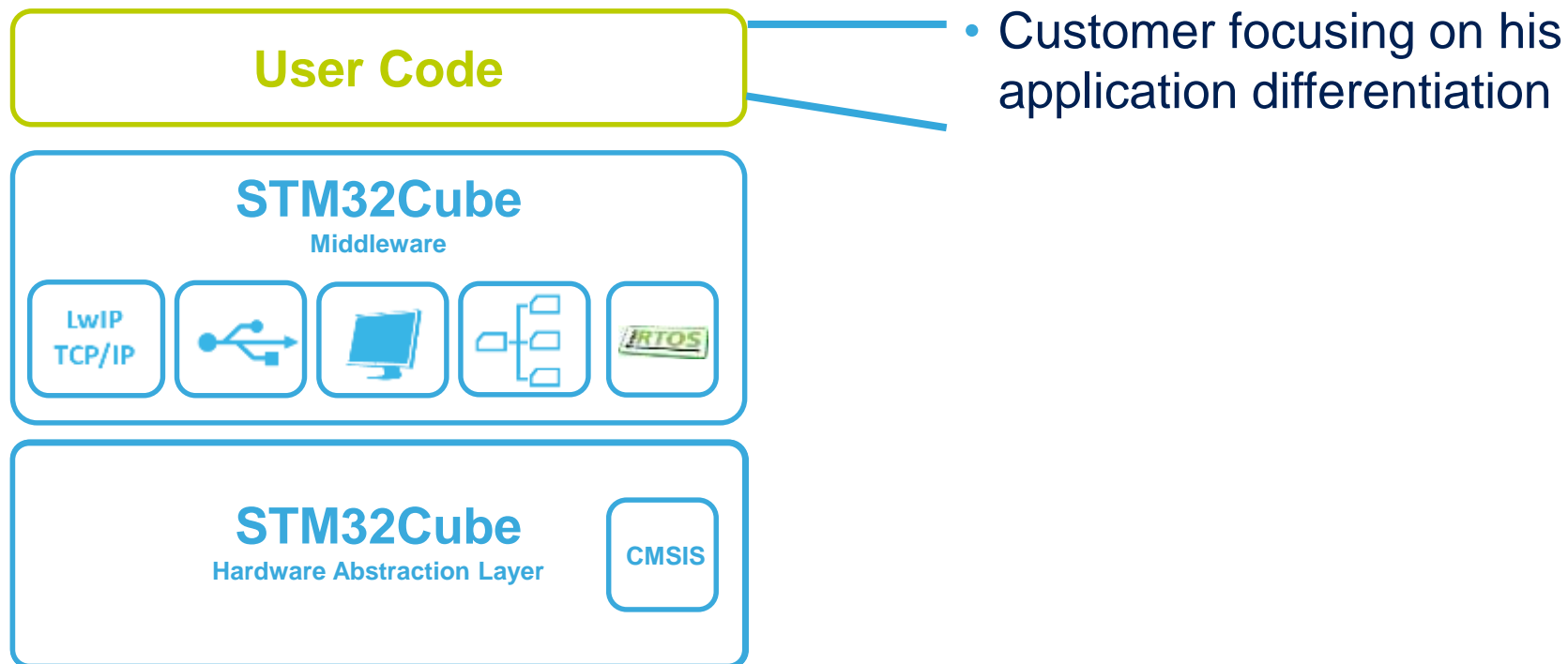


- TCP/IP stack
 - LwIP open source standard
- USB Library
 - Host & Device made by ST
- Graphics
 - STemWin from ST and SEGGER
- File System
 - FatFS open source standard
- RTOS
 - FreeRTOS open source standard (with CMSIS-RTOS abstraction)
- **>40 examples !**

STM32Cube V1

STM32CubeFx/Lx FW Package

8

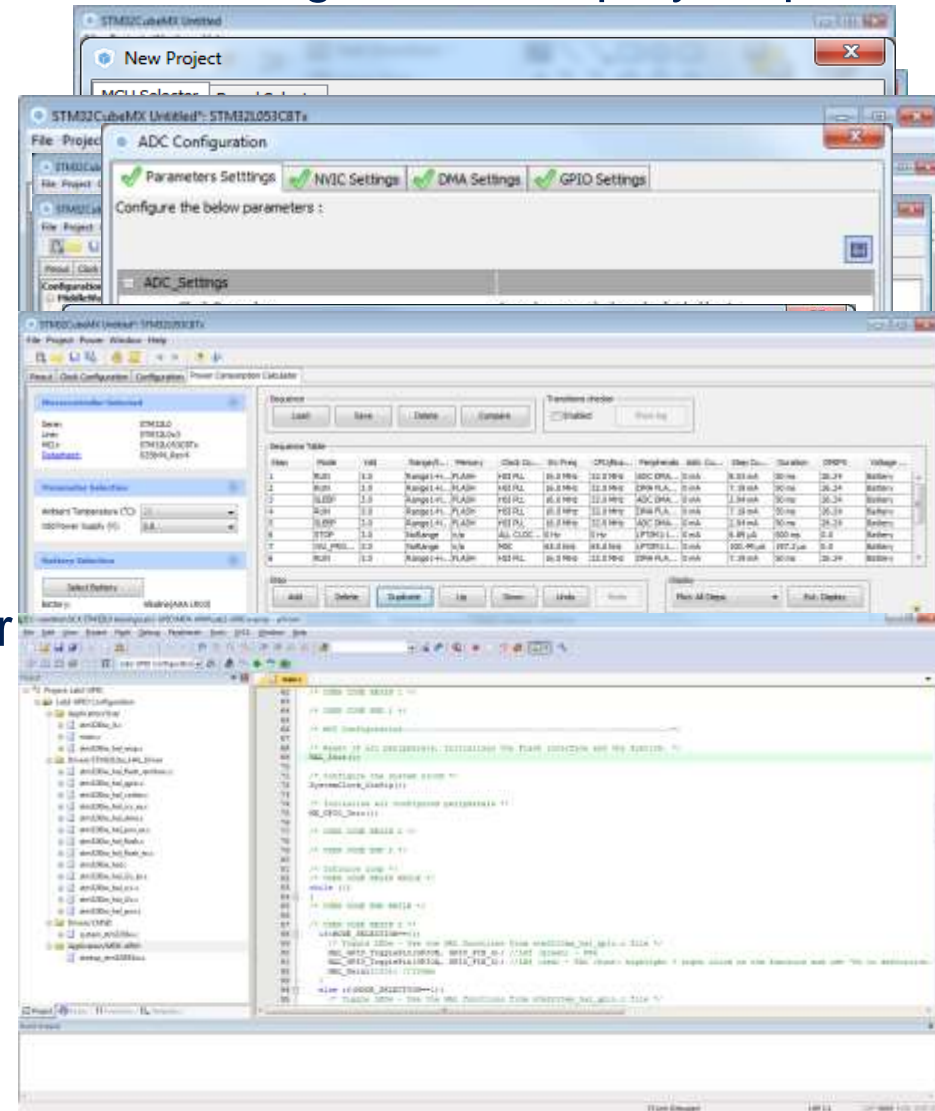


STM32Cube V1 – STM32CubeMX

9

Microcontroller configuration, step by step

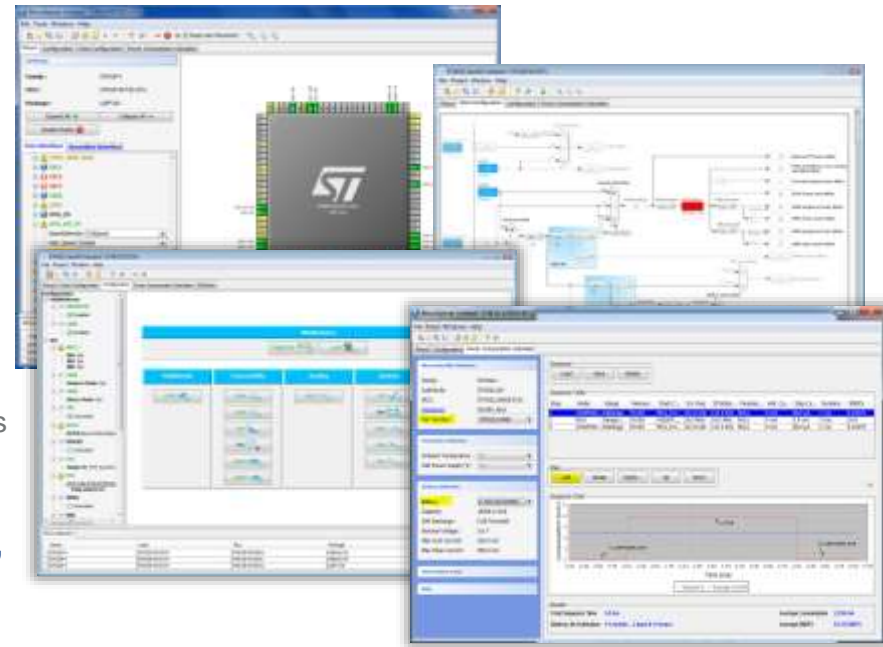
- STM32Cube includes the *STM32CubeMX* which is a graphical software configuration tool that allows generating C initialization code using graphical wizards.
- **Step 1: Select the microcontroller**
 - Through easy filtering capabilities
- **Step 2: Configure the microcontroller**
 - Pin out wizard
 - Clock tree wizard
 - Peripherals and Middlewares wizards
 - Power consumption wizard
- **Step 3: Initialization code generation**
 - Generates code for your favorite IDE !



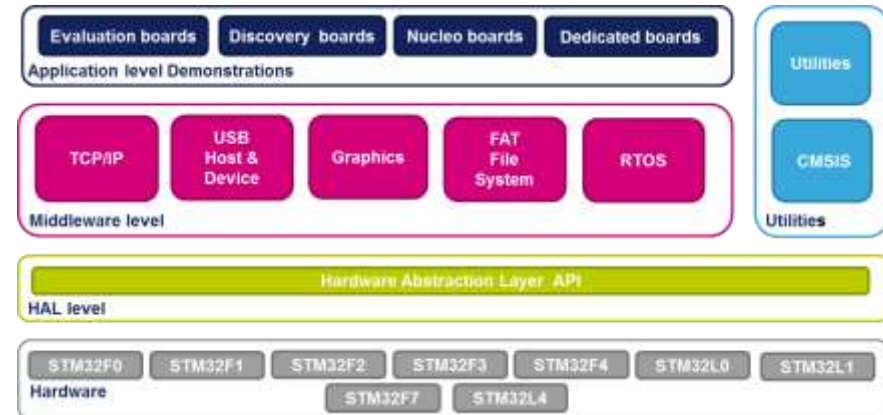
STM32Cube™ V1 – Key Benefits

10

- **Simplify and Speed up Application Development for STM32!**
 - Through STM32CubeMX:
 - MCU Selector
 - Graphical Peripheral Configuration
 - Power Consumption Wizard
 - Peripheral Initialization Code Generation
 - With automatic updater feature
 - Ensuring the developer is aware of new versions and fixes, as well as new components
 - Through extensive set of “**ready-to-run**” peripheral examples and application examples, with **ready project files** for IAR, Keil and GCC included in the STM32CubeFx/Lx packages
- **More than Cost-friendly !**
 - **100% FREE** embedded software!
 - **100% FREE** software tool !
 - ST-branded, ST-supported !
 - **Users gain time** with initialization code generation, and remain focused on their key application code



User Application





STM32CubeMX Overview

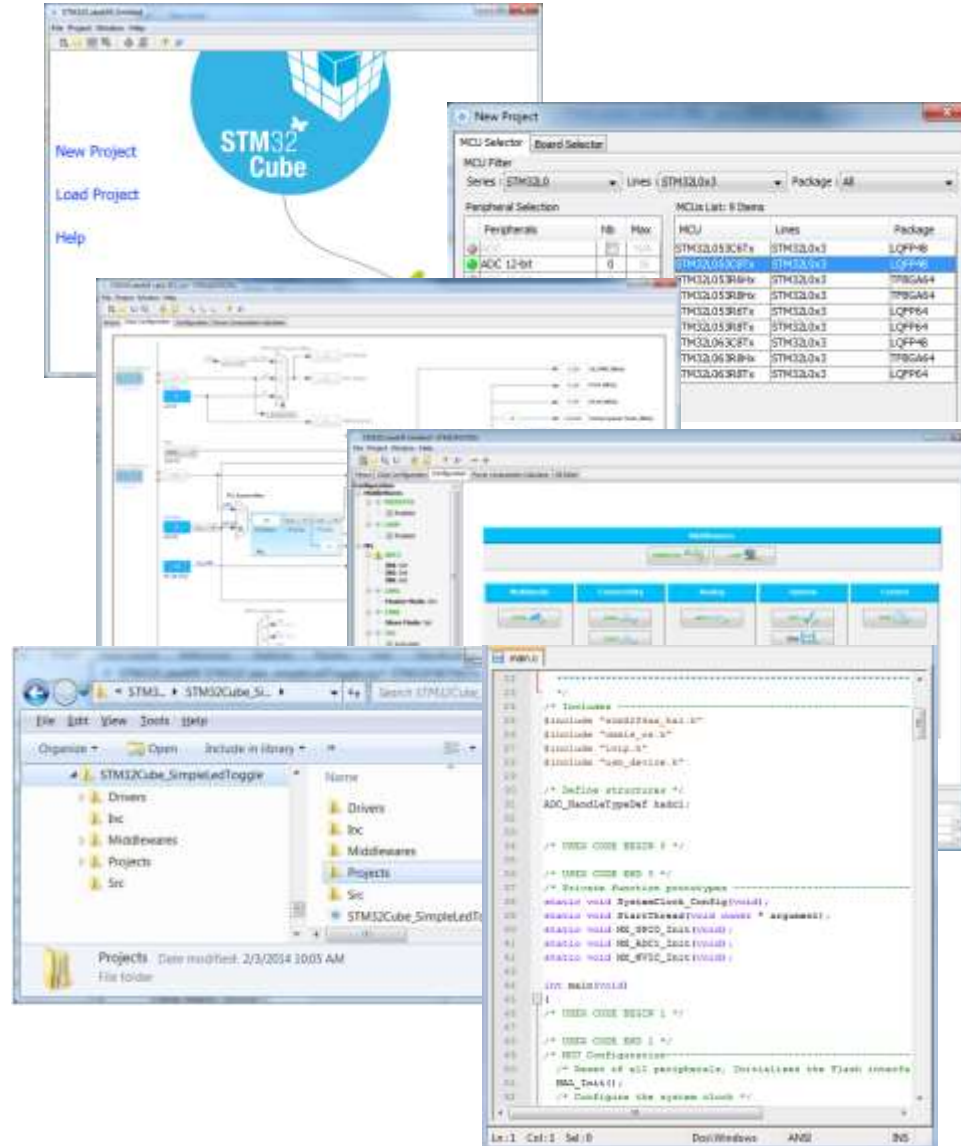
STM32CubeMX for STM32 configuration and initialization C code generation

12

- The STM32CubeMX, a graphical software configuration tool that allows to generate C initialization C code using graphical wizards.
- STM32CubeMX has the following key features:
 - Easy microcontroller selection covering whole STM32 portfolio.
 - Board selection from a list of STMicroelectronics boards.
 - Easy microcontroller configuration (pins, clock tree, peripherals, middleware) and generation of the corresponding initialization C code.
 - Generation of configuration reports.
 - Generation of IDE ready projects for a selection of integrated development environment tool chains.

STM32CubeMX projects include the generated initialization C code, STM32 HAL drivers, the middleware stacks required for the user configuration, and all the relevant files needed to open and build the project in the selected IDE.

- Power consumption calculation for a user-defined application sequence.
- Self-updates allowing the user to keep the STM32CubeMX up-to-date.
- Downloading and updating STM32Cube™ firmware packages allowing the download from www.st.com of the MCU firmware package required for the development of the user application



STM32CubeMX C Code generation overview

13

- During the C code generation process, STM32CubeMX performs the following actions:
 - It downloads the relevant STM32Cube firmware package if it is missing from the STM32CubeMX repository.
 - It copies from the firmware package, the relevant files in Drivers/CMSIS and Drivers/STM32xx_HAL_Driver folders and in the Middleware folder if a middleware was selected.
 - It generates a *Projects* folder that contains the toolchain specific files that match the user project settings.
 - It generates the initialization C code (.c/.h files) corresponding to the user MCU configuration and stores it in the Inc and Src folders. By default, the following files are included:

Files	Description
stm32f4xx_hal_conf.h	this file defines the enabled HAL modules and sets some parameters (e.g. External High Speed oscillator frequency) to pre-defined default values or according to user configuration (clock tree).
stm32f4xx_hal_msp.c (MSP=MCU Support package)	this file defines all initialization functions to configure the IP instances according to the user configuration (pin allocation, enabling of clock, use of DMA and Interrupts).
main.c	is in charge of: <ul style="list-style-type: none">- Resetting the MCU to a known state by calling the HAL_init() function that resets all peripherals, initializes the Flash memory interface and the SysTick.- Configuring and initializing the system clock.- Configuring and initializing the GPIOs that are not used by IPs.- Defining and calling, for each configured IP, an IP initialization function that defines a handle structure that will be passed to the corresponding IP HAL init function which in turn will call the IP HAL MSP initialization function.

STM32CubeMX Repository

14

- Downloaded software and firmware releases will be stored in the Repository folder. The Default folder is defined in STM32CubeMX->Help->Updater Settings->Repository Folder.

The image displays the STM32CubeMX software interface. The main window shows the 'File' menu with 'Updater Settings ...' highlighted. A red arrow points from this menu item to the 'Updater Settings' dialog box. The dialog box has two tabs: 'Updater Settings' and 'Connection Parameters'. The 'Updater Settings' tab is active, showing the 'Repository Folder' set to 'C:/Users/user name/STM32Cube/Repository/'. Below this, the 'Check and Update Settings' section shows 'Automatic Check' selected with an interval of 5 days. The 'Data Auto-Refresh' section shows 'Auto-Refresh Data-only at Application start' selected with an interval of 3 days. To the right of the dialog box, a file explorer view shows the 'Repository (18)' folder structure, listing various firmware packages like 'STM32Cube_FW_F0_V1.0.0' through 'STM32Cube_FW_F1_V1.6.0'. In the bottom left, a 'New Libraries Manager' window is visible, showing a table of 'STM32CubeF0 Releases' with columns for 'Set', 'Description', 'Installed Version', and 'Available Version'.

Set	Description	Installed Version	Available Version
STM32CubeF0 Releases			
FW_Pack_F0	Firmware Package for Family STM32F0	1.8.0	1.8.0
FW_Pack_F0	Firmware Package for Family STM32F0	1.7.0	1.7.0
FW_Pack_F0	Firmware Package for Family STM32F0	1.6.0	1.6.0
FW_Pack_F0	Firmware Package for Family STM32F0	1.5.0	1.5.0
FW_Pack_F0	Firmware Package for Family STM32F0	1.4.0	1.4.0
FW_Pack_F0	Firmware Package for Family STM32F0	1.3.0	1.3.0
FW_Pack_F0	Firmware Package for Family STM32F0	1.2.1	1.2.1
FW_Pack_F0	Firmware Package for Family STM32F0	1.1.0	1.1.0
FW_Pack_F0	Firmware Package for Family STM32F0	1.0.0	1.0.0

STM32CubeMX Documentation


15

Technical Documentation


Product Specifications

Description	Version	Size
 DB2163: STM32 configuration and initialization C code generation	3.0	250 KB

Technical Notes & Articles

Description	Version	Size
 TN0072: Software toolchains and STM32 features	2.4	98 KB

User Manual

Description	Version	Size
 UM1718: STM32CubeMX for STM32 configuration and initialization C code generation	8.0	12,438 KB

Release Notes

Description	Version	Size
 RN0094: STM32CubeMX release 4.8.0	11.0	245 KB

Related Tools and Software

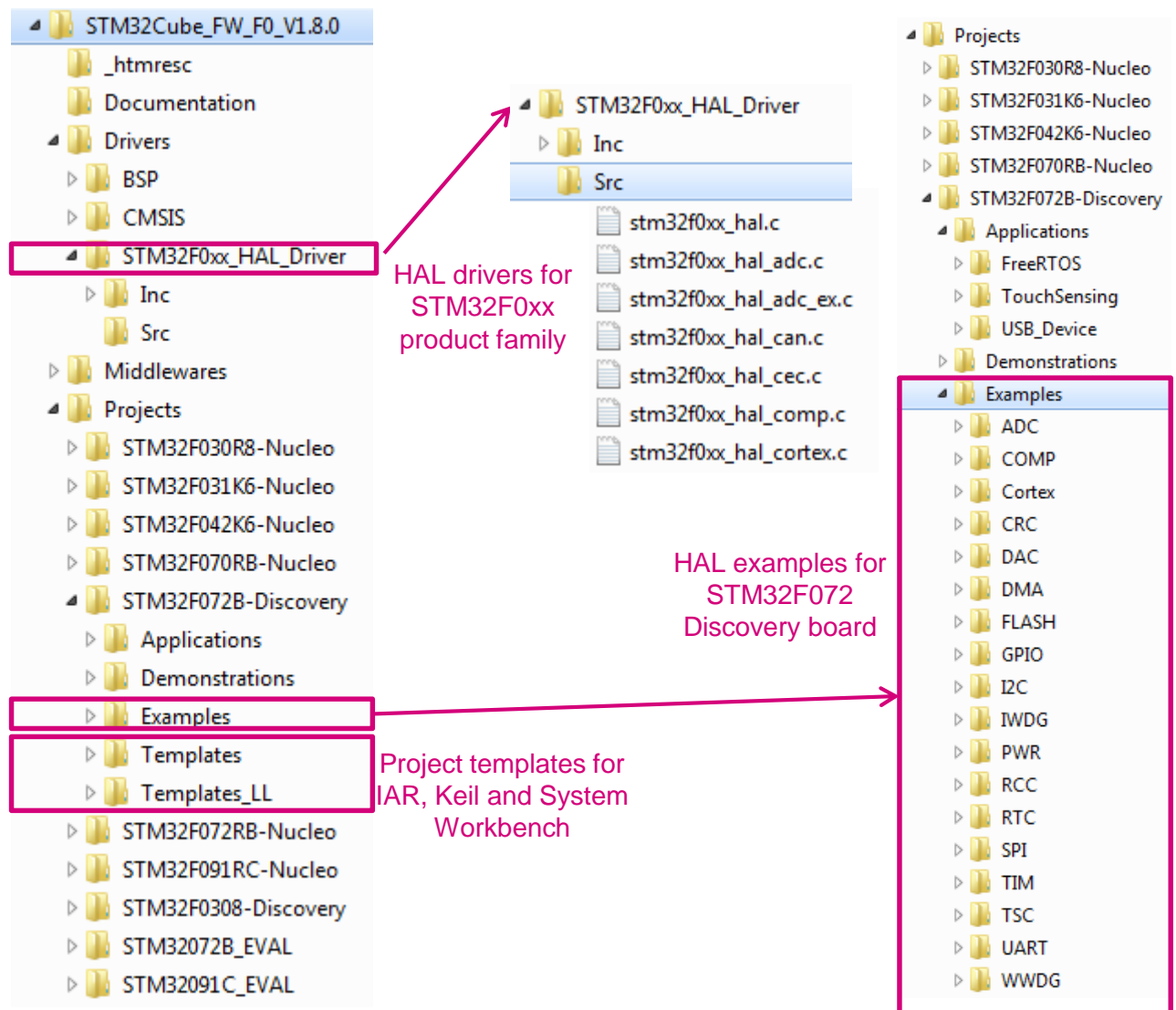
Related Tools and Software

Part Number	Description
STM32CubeF3	Embedded RTOS, Tr
STM32CubeF1	Embedded system, I
STM32CubeL1	Embedded RTOS, Tr
STM32CubeF7	Embedded system, I
STSW-STM32095	STM32CubeMX Eclipse p
STM32CubeL0	Embedded RTOS, Tr
STM32CubeF2	Embedded system, I
STM32CubeF4	Embedded system, I
STM32CubeF0	Embedded system, I

Links to various STM32Cube offering

STM32Cube: STM32CubeF0 Firmware Package

16



HAL drivers for
STM32F0xx
product family

HAL examples for
STM32F072
Discovery board

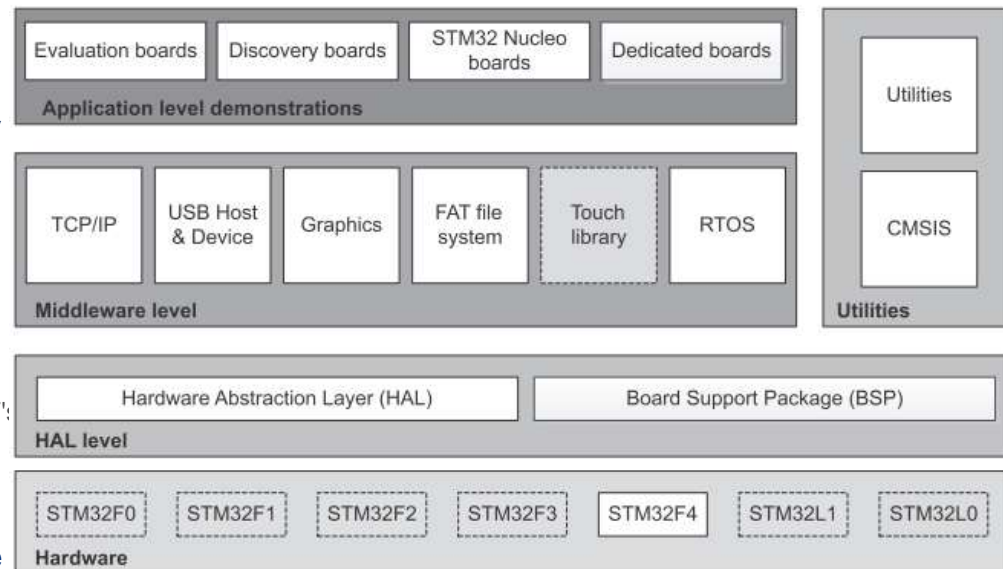
Project templates for
IAR, Keil and System
Workbench

- Browse to
- C:\users\your
name\STM32Cube\Repository\
STM32Cube\STM32Cube_FW
_V1.8.0 or later

STM32Cube FW Package Features

17

- STM32Cube gathers together, in a single package, all the generic and highly portable embedded software components required to develop an application on STM32 microcontrollers.
- The package includes a low level hardware abstraction layer (HAL) that covers the microcontroller hardware, together with an extensive set of examples running on STMicroelectronics boards.
- It also contains a set of middleware components (*) with the corresponding examples. They come with very permissive license terms:
 - Full USB Host and Device stack supporting many classes.
 - Host Classes: HID, MSC, CDC, Audio, MTP
 - Device Classes: HID, MSC, CDC, Audio, DFU
 - Graphics
 - STemWin, a professional graphical stack solution available in binary format and based on the emWin solution from ST partner SEGGER
 - LibJPEG, an open source implementation on STM32 for JPEG images encoding and decoding.
 - CMSIS-RTOS implementation with FreeRTOS open source solution
 - FAT File system based on open source FatFS solution
 - TCP/IP stack based on open source LwIP solution
 - SSL/TLS secure layer based on open source PolarSSL
- A demonstration implementing all these middleware components is also provided



(*) middleware components availability depends on STM32 Series

STM32CubeF0 Documentation

18

- The STM32Cube documentation vary from one STM32 series to another.
- More high-end MCUs(e.g. STM32F4) are supported by more middleware libraries, like for STemWin graphics library and LwIP TCP/IP Stack.







Product Specifications

Description	Version	Size
 DB2347: STM32Cube embedded software for STM32F0 series including HAL drivers, USB, File System, RTOS and Touch sensing	2.0	219 KB

Application Notes

Description	Version	Size
 AN4735: STM32Cube firmware examples for STM32F0 Series	2.0	281 KB

User Manual

Description	Version	Size
 UM1779: Getting started with STM32CubeF0 firmware package for STM32F0 series	4.0	387 KB
 UM1785: Description of STM32F0xx HAL drivers	2.0	10,604 KB
 UM1787: STM32CubeF0 Nucleo demonstration firmware	3.0	803 KB
 UM1819: Demonstration firmware for STM32091C-EVAL board	1.0	4,247 KB
 UM1913: Developing applications on STM32Cube with Touch Sensing	1.0	3,416 KB

<http://www.st.com/web/en/catalog/tools/PF260612>



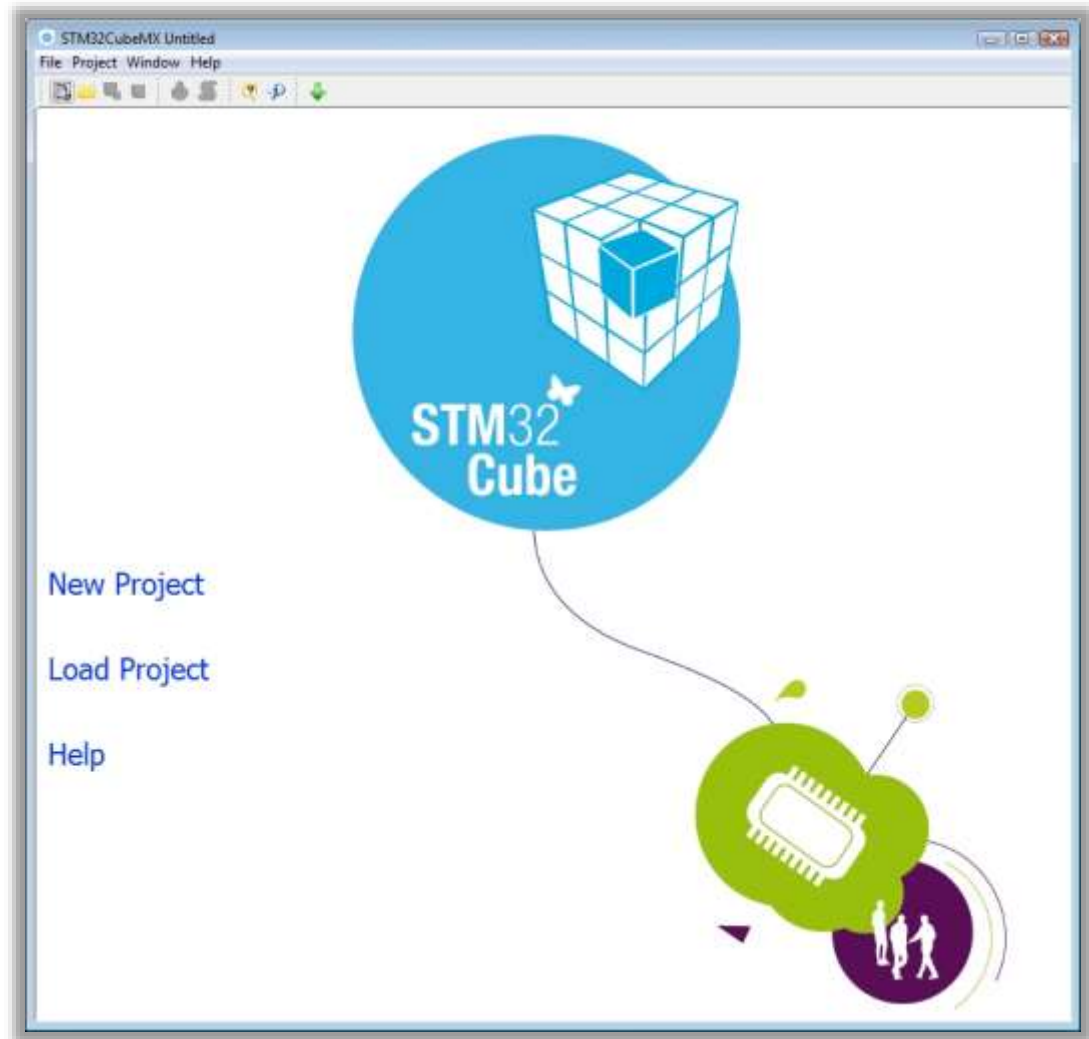
Demo: STM32CubeMX Overview

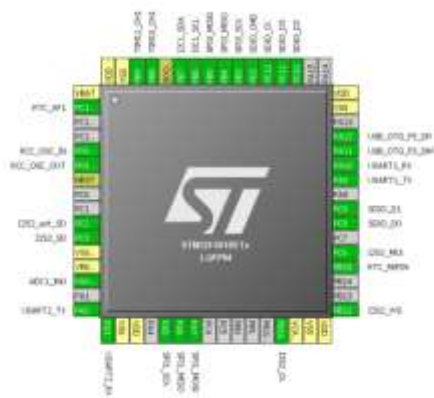
STM32Cube: STM32CubeMX

20

Step by step:

- MCU selector
- Pinout configuration
- Clock tree initialization
- Peripherals and middleware parameters
- Code generation
- Power consumption calculator





Pinout Wizard

STM32CubeMX



Peripherals & Middleware Wizard

Basic Parameters	
Baud Rate	115200 Bits/s
Word Length	8 Bits (including Parity)
Parity	None
Stop Bits	1
Advanced Parameters	
Data Direction	Receive and Transmit
Over Sampling	16 Samples

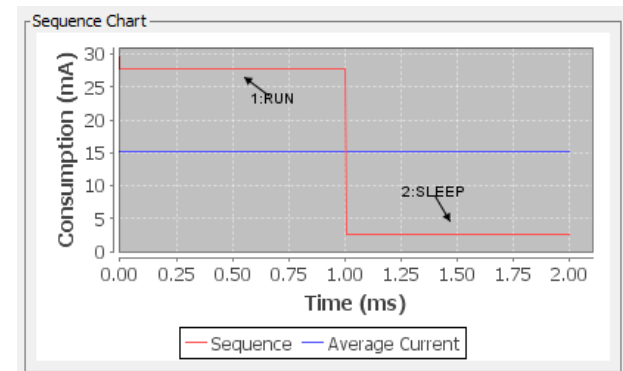
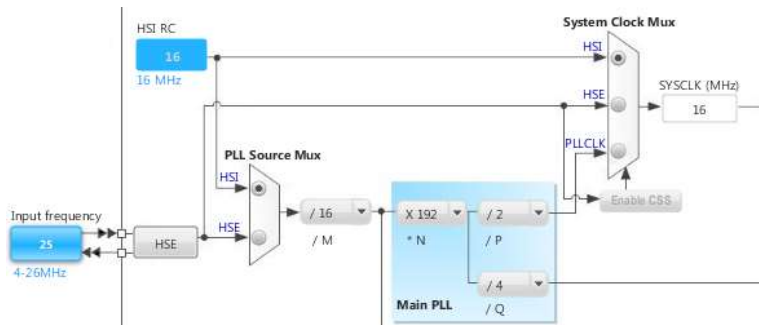
Baud Rate
BaudRate must be between **110 Bits/s** and **10.5 MBits/s**.

21

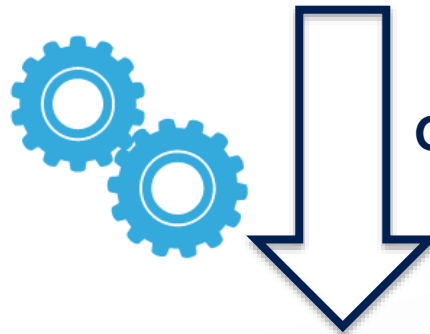


Power Consumption Wizard

Clock Tree wizard



STM32CubeMX



**Generates Initialization C Code
based on user choices !**



STM32CubeMX: MCU Selector

23

Easy Optional filtering:

- Core
- Series
- Line
- Package
- Advanced choices...
- Peripherals choices...

MCU Selector | Board Selector

MCU Filters

Part Number Search

Core

Series

Line

Package

Advanced Choice

Price: From 0.0 to 12.21

30 From 11 to 268

11

368

Eprom: From 0 to 16384 (Bytes)

0

16384

Flash: From 8 to 2048 (kBytes)

8

2048

Ram: From 2 to 1024 (kBytes)

2

1024

Freq: From 0 to 400 (MHz)

0

400

Peripheral Choice

Peripherals

Nb

Max

ADC 12-bit

1

10

New STM32L4 ultra-low-power MCUs
advanced audio and energy efficiency

STM32L45x

- 256 to 512KB Flash
- Up to 160KB RAM

Features

Block Diagram

Datasheet

Doc & Resources

Buy

Start Project

MCU List: 1079 items

+ Display 10 items

Part No	Reference	Marketing Status	Unit Price for 10K/100 from US\$	Package	Flash	RAM	IO	Freq
STM32F030C6	STM32F030C6Tx	Active	0.59	LQFP48	32 kbytes	4 kbytes	39	48 MHz
STM32F030C8	STM32F030C8Tx	Active	0.72	LQFP48	64 kbytes	8 kbytes	39	48 MHz
STM32F030CC	STM32F030CCTx	Active	1.1	LQFP48	256 kbytes	32 kbytes	37	48 MHz
STM32F030F4	STM32F030F4Tx	Active	0.42	TSSOP20	16 kbytes	4 kbytes	15	48 MHz
STM32F030K6	STM32F030K6Tx	Active	0.51	LQFP32	32 kbytes	4 kbytes	25	48 MHz
STM32F030R8	STM32F030R8Tx	Active	0.75	LQFP64	64 kbytes	8 kbytes	55	48 MHz
STM32F030RC	STM32F030RCTx	Active	1.21	LQFP64	256 kbytes	32 kbytes	51	48 MHz
STM32F031C4	STM32F031C4Tx	Active	0.97	LQFP48	16 kbytes	4 kbytes	39	48 MHz
STM32F031C6	STM32F031C6Tx	Active	1.01	LQFP48	32 kbytes	4 kbytes	39	48 MHz
STM32F031E6	STM32F031E6Tx	Active	0.77	WLCSP25	32 kbytes	4 kbytes	20	48 MHz
STM32F031F4	STM32F031F4Tx	Active	0.71	TSSOP20	16 kbytes	4 kbytes	15	48 MHz
STM32F031F6	STM32F031F6Tx	Active	0.75	TSSOP20	32 kbytes	4 kbytes	15	48 MHz

MCU selector continued

- Second tab provides shortcuts to predefined boards equipped with STM32 MCU.
- Predefined boards come with pinouts already assigned to use the connections and features of the particular board.
- Alternative board configurations are not covered.

MCU Selection

Board Selection

Board Filter

Vendor :

Type of Board :

MCU Series :

STMicroelectronics

AI

AI

☐ Initialize all peripherals with their default mode

Peripheral Selection

Peripherals

Id

Mac

☒

 Accelerometer

☒

 Analog I/O

☒

 Auto Gain Factor

☒

 Audio Line In

☒

 Audio Line Out

☒

 Button

☒

 CAN

☒

 Camera

☒

 Compass

☒

 Custom Form Factor

☒

 Digital I/O

☒

 Display

☒

 Ethernet

☒

 Flash Memory

☒

 GPS/GNSS

☒

 I2C

☒

 Joystick

☒

 LCD Display (Graphics)

☒

 LCD Display (Segment)

☒

 LED

☒

 Light Sensor

☒

 Memory Card

☒

 Microphone

☒

 Pictometer

☒

 Pressure Sensor

☒

 RS-232

☒

 RS-485

☒

 SRAM/DRAM

☒

 Speaker

☒

 Temperature Sensor

☒

 Touch Key Sensing

☒

 USB

Boards List: 80 Items

Type

Reference

MCU

Nodes144

NUCLEO-F401RE

STM32F401RET6

Nodes144

NUCLEO-F401VE

STM32F401VET6

Nodes144

NUCLEO-F429ZI

STM32F429ZIT6

Nodes144

NUCLEO-F446ZE

STM32F446ZET6

Nodes144

NUCLEO-F746ZI

STM32F746ZIT6

Nodes144

NUCLEO-F767ZI

STM32F767ZIT6

Nodes144

NUCLEO-F412RE

STM32F412RET6

Nodes144

NUCLEO-F413H

STM32F413HET6

Nodes144

NUCLEO-L496QG

STM32L496ZGT6

Nodes144

NUCLEO-L496ZG-P

STM32L496ZGT6P

Nodes144

NUCLEO-F722ZE

STM32F722ZET6

Nodes144

NUCLEO-H743I

STM32H743IET6

Nodes32

NUCLEO-P0408

STM32P0408ET6

Nodes32

NUCLEO-F0334K

STM32F0334ET6

Nodes32

NUCLEO-F3038K

STM32F3038ET6

Nodes32

NUCLEO-L0314S

STM32L0314ET6

Nodes32

NUCLEO-L0314K

STM32L0314ET6

Nodes32

NUCLEO-L433K

STM32L433KUN

Nodes64

NUCLEO-F0308K

STM32F0308ET6

Nodes64

NUCLEO-F0708K

STM32F0708ET6

Nodes64

NUCLEO-F0728K

STM32F0728ET6

Nodes64

NUCLEO-P0538C

STM32P0538ET6

Nodes64

NUCLEO-F3038T

STM32F3038ET6

Nodes64

NUCLEO-F3038T

STM32F3038ET6

Nodes64

NUCLEO-F3038T

STM32F3038ET6

Nodes64

NUCLEO-F401RE

STM32F401RET6

Nodes64

NUCLEO-F411RE

STM32F411RET6

Nodes64

NUCLEO-L496ZG

STM32L496ZGT6

Nodes64

NUCLEO-F446ZE

STM32F446ZET6

Nodes64

NUCLEO-L496AG

STM32L496AGT6

Nodes64

NUCLEO-F413H

STM32F413HET6

Nodes64

NUCLEO-L073KZ

STM32L073KZT6

Nodes64

NUCLEO-L4628E

STM32L4628ET6

Nodes64

NUCLEO-L433K-P

STM32L433KCT6P

Nodes64

NUCLEO-L4628E-P

STM32L4628ET6P

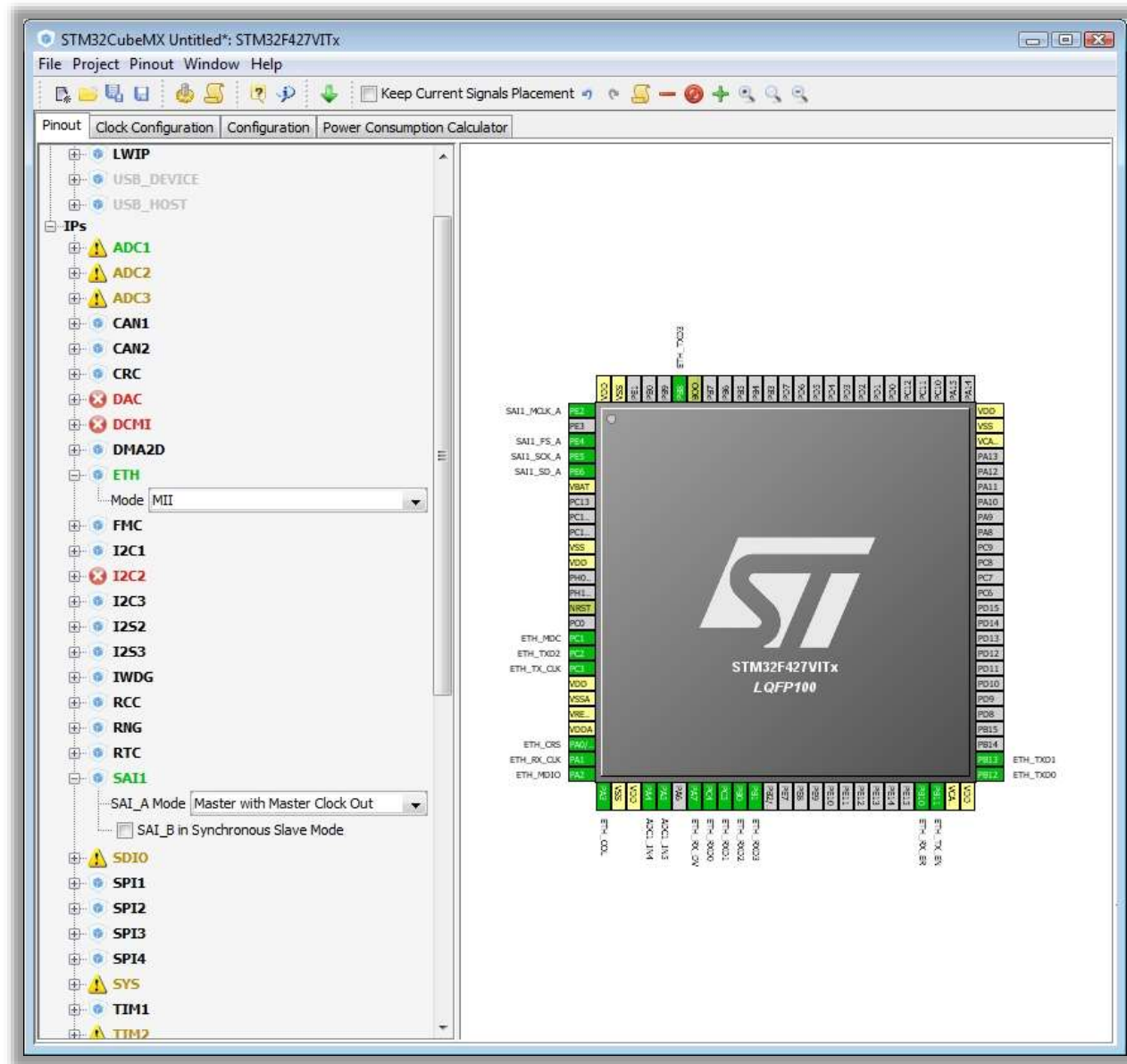
Discovery

STM32F030C8DISCOVERY

STM32CubeMX: Pinout configuration

25

- Pinout from:
 - Peripheral tree
 - Manually
- Automatic signal remapping
- Management of dependencies between peripherals and/or middleware (FatFS, LWIP, FREERTOS, USB etc)



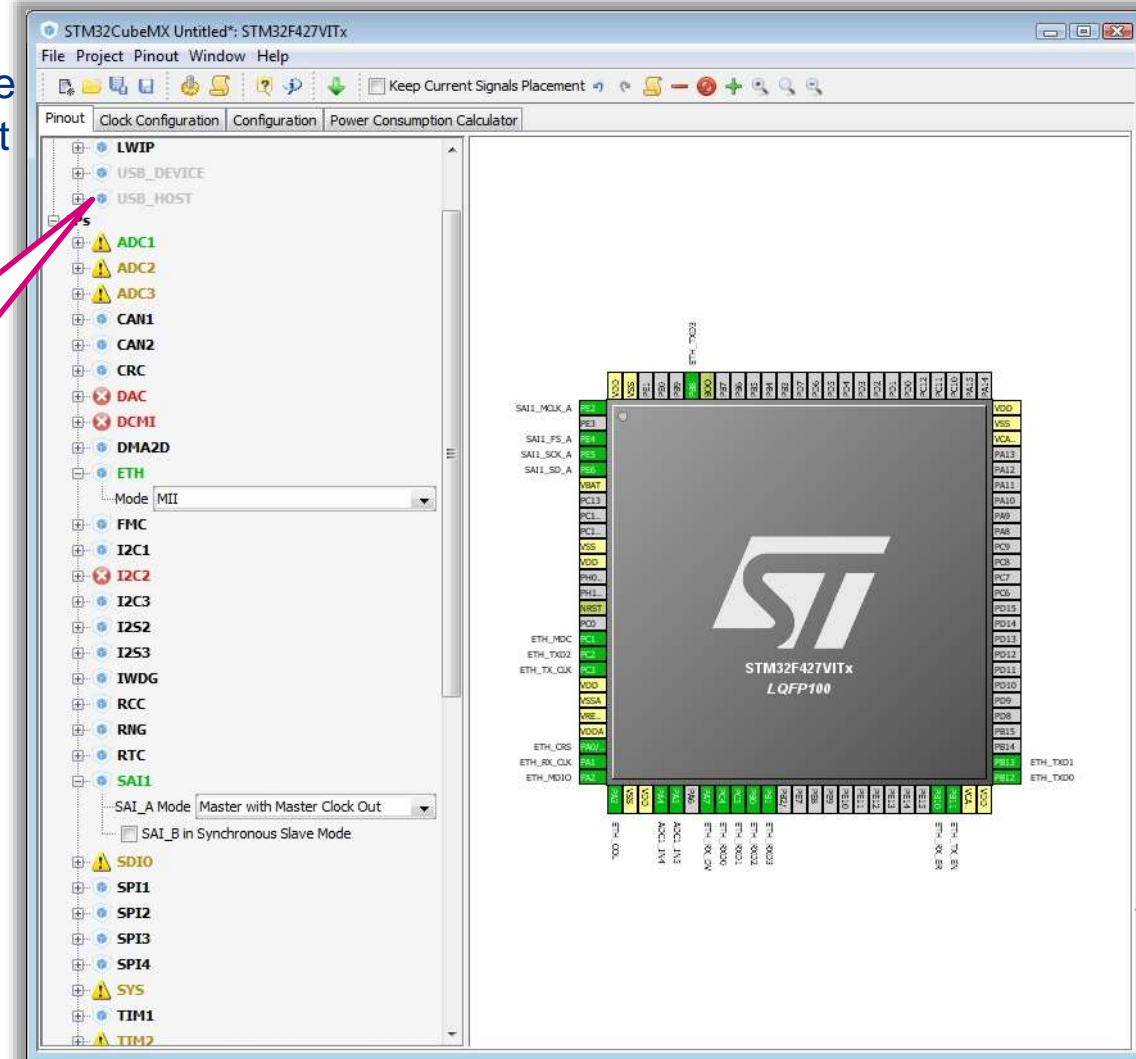
STM32CubeMX: Pinout configuration

26

- Different possible states for a peripheral modes

- Dimmed:
the mode is not available because
it requires another mode to be set
(just put the mouse on top of the
dimmed mode to see why)

Dimmed:
The additional
periphery must
be selected

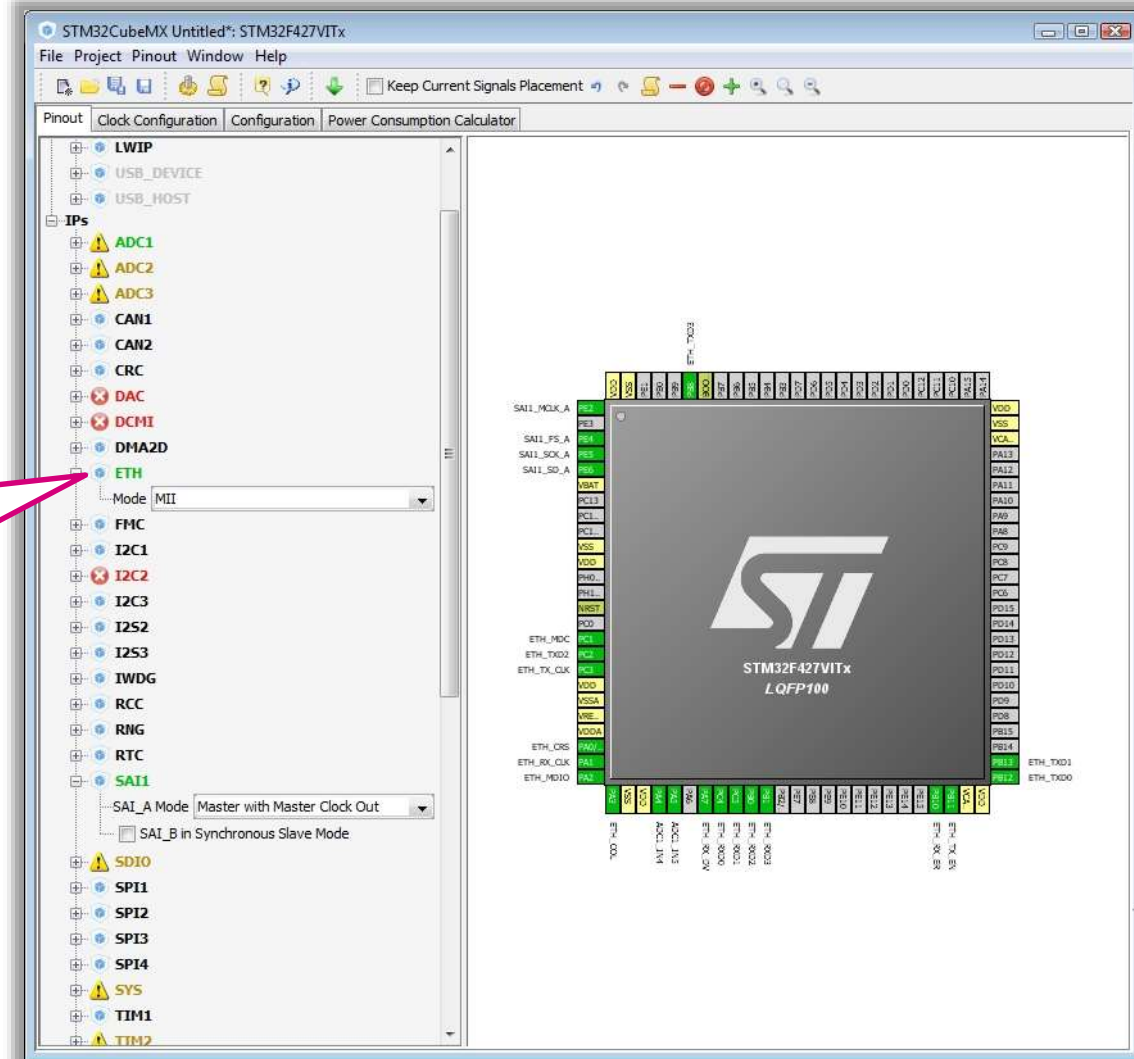


STM32CubeMX: Pinout configuration

27

- Different possible states for a peripheral modes
 - Green:
Peripheral is assigned to pinout

Green:
Peripheral will
be functional



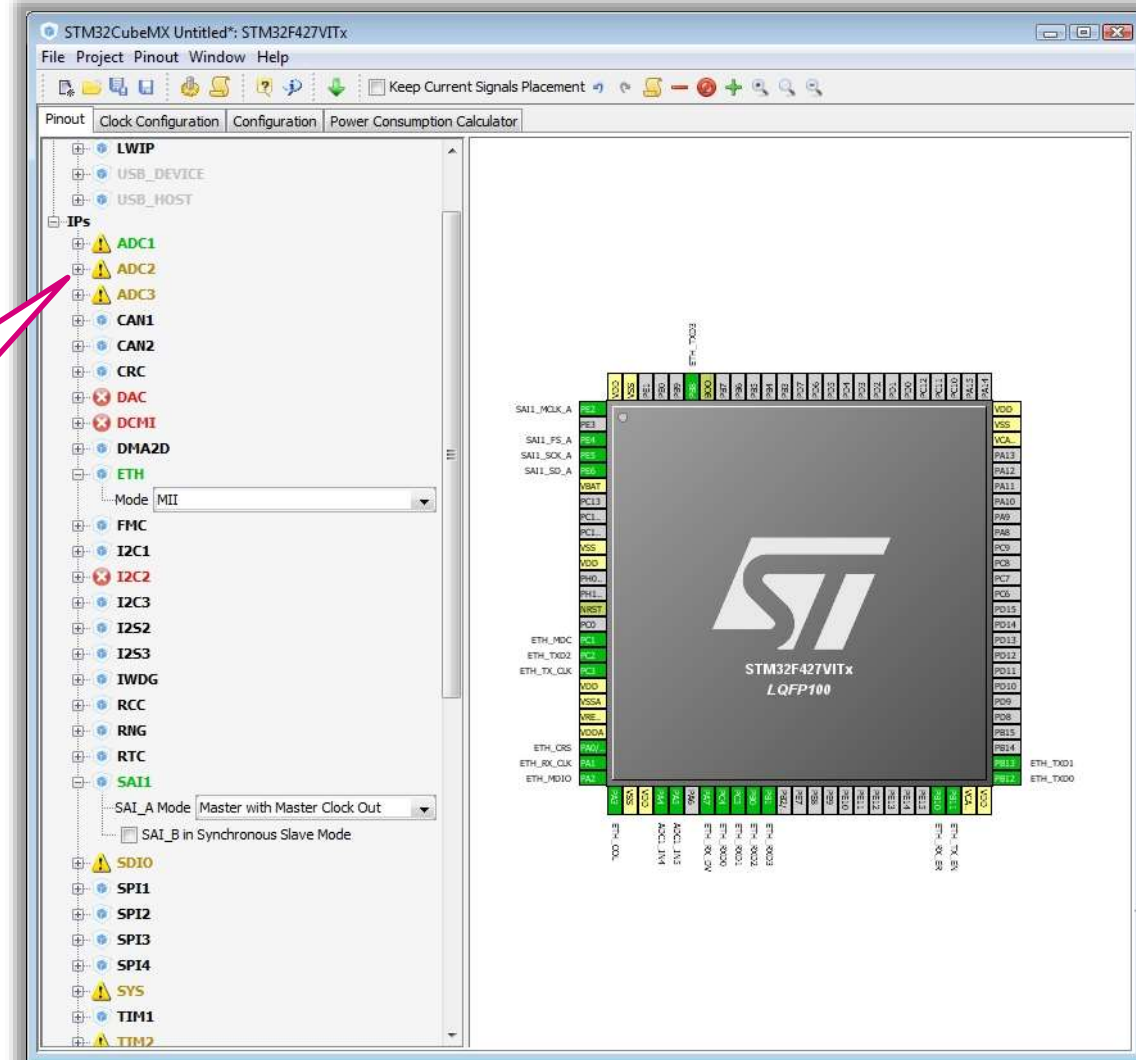
STM32CubeMX: Pinout configuration

28

- Different possible states for a peripheral modes

- Yellow:
Only some functionalities of
periphery can be used

Yellow:
On ADC only
some channels
can be used



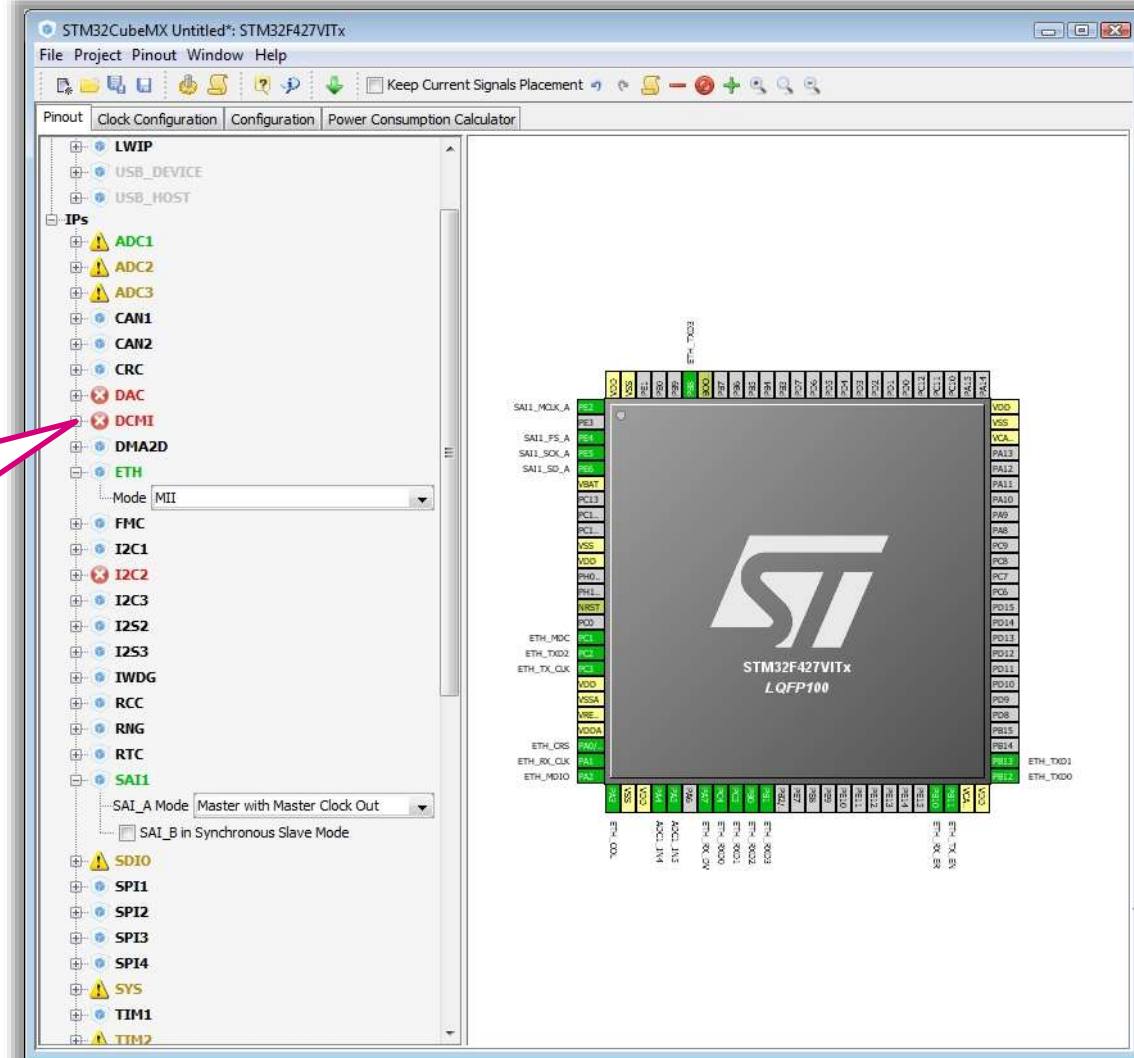
STM32CubeMX: Pinout configuration

29

- Different possible states for a peripheral modes

- Red:
Signals required for this mode
can't be mapped on the pinout
(see tooltip to see conflicts)

Red:
Peripheral
cannot be used
in this pinout
setup



STM32CubeMX: Pinout configuration

30

- Ensure “Keep Current Signal Placement” is unchecked (by default)

1. I2C1 selected

2. I2C1 pin assignment

3. LPTIM1 with external trigger selected

4. Pin conflict between I2C1 and LPTIM1. I2C1_SCL moved to alternative position

31

- Keep Current Signal Placement
checked now CubeMX cannot
move selected signals to
different alternate pin

Pin diagram of the STM32L053C8Tx microcontroller. The chip is shown with its pins labeled. The top pins are I2C1_SDA, I2C1_SCL, and LPTIM1_IN1. The left pins are VDD, VSS, PB9, PB8, BOOT0, PB7, PB6, PB5, PB4, PB3, PA15, and PA14. The bottom pins are VLCD, PC13, PC14, PC15, PH0, PH1, NRST, VSSA, VDDA, PA0, PA1, and PA2. The right pins are VDD, VSS, PA13, PA12, PA11, PA10, PA9, PA8, PB15, PB14, PB13, and PB12. The chip has a central logo and the text 'STM32L053C8Tx' and 'LQFP48'.

STM32CubeMX: Pinout configuration

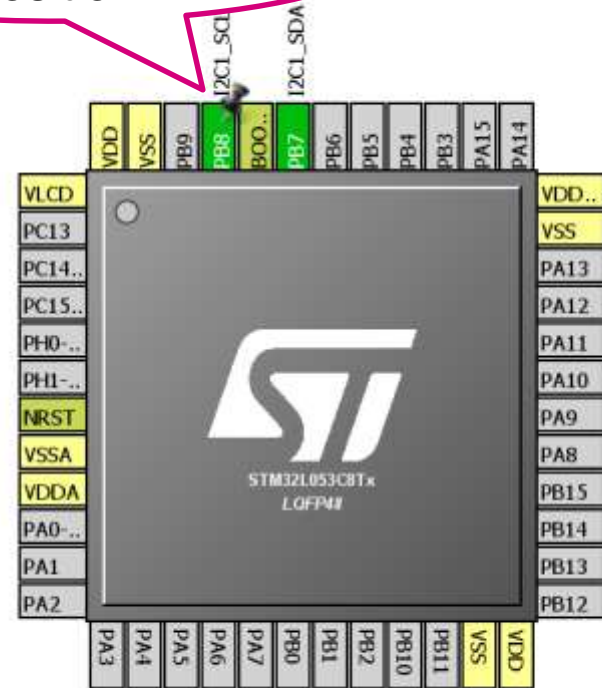
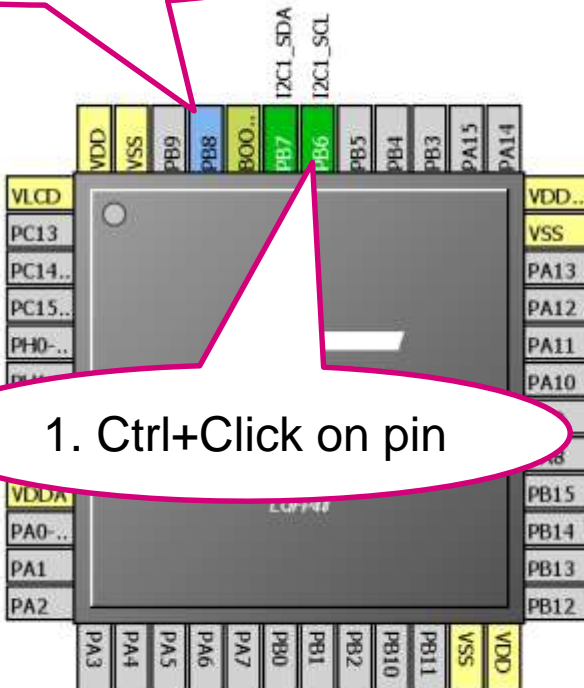
32

- Signals can be set/moved directly from the pinout view
 - To see alternate pins for a signal Ctrl+Click on the signal, you can then drag and drop the signal to the new pin (keep pressing the Ctrl key)

2. Show alternative positions

3. Move pin to new position

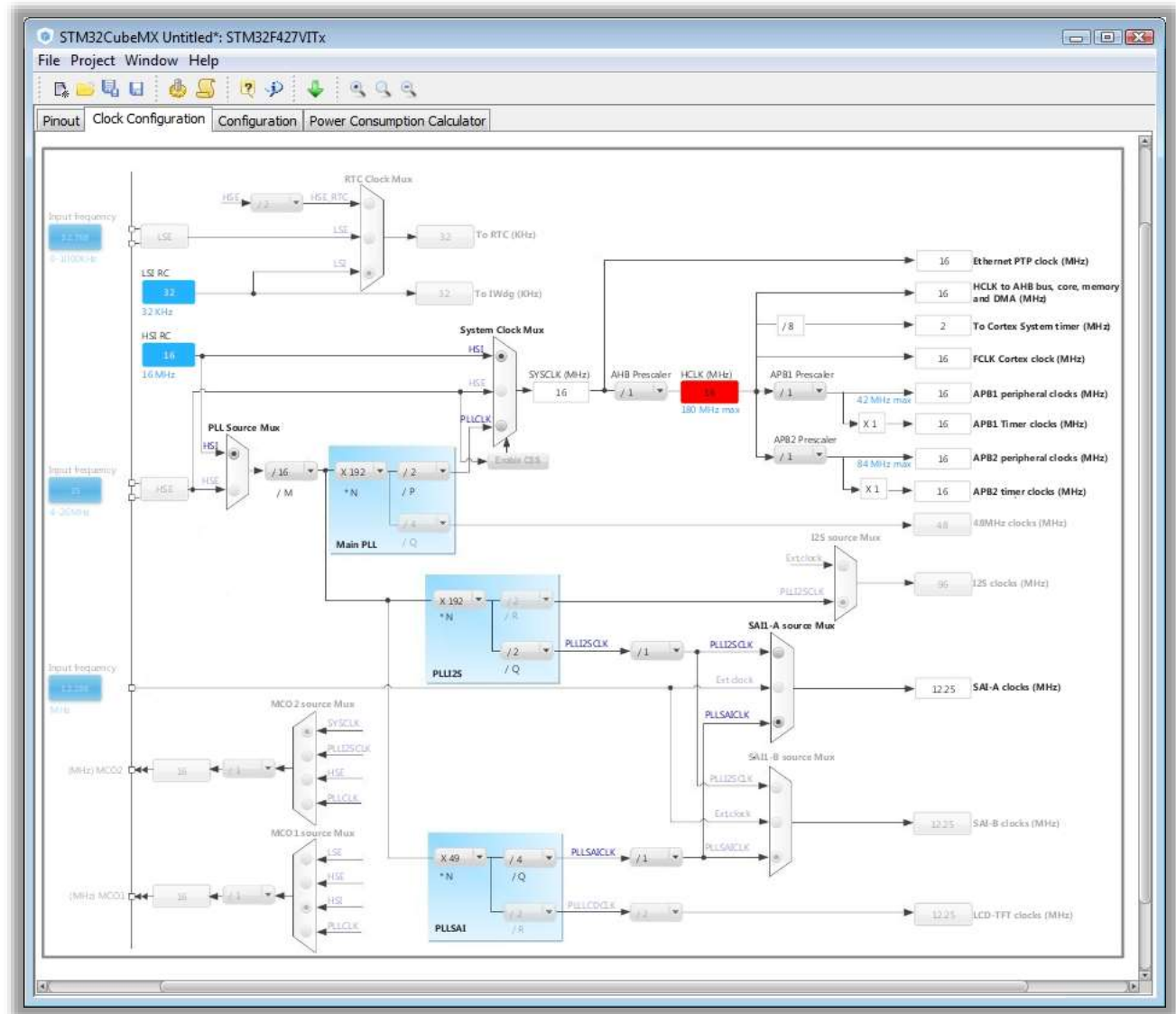
1. Ctrl+Click on pin



STM32CubeMX: Clock tree

33

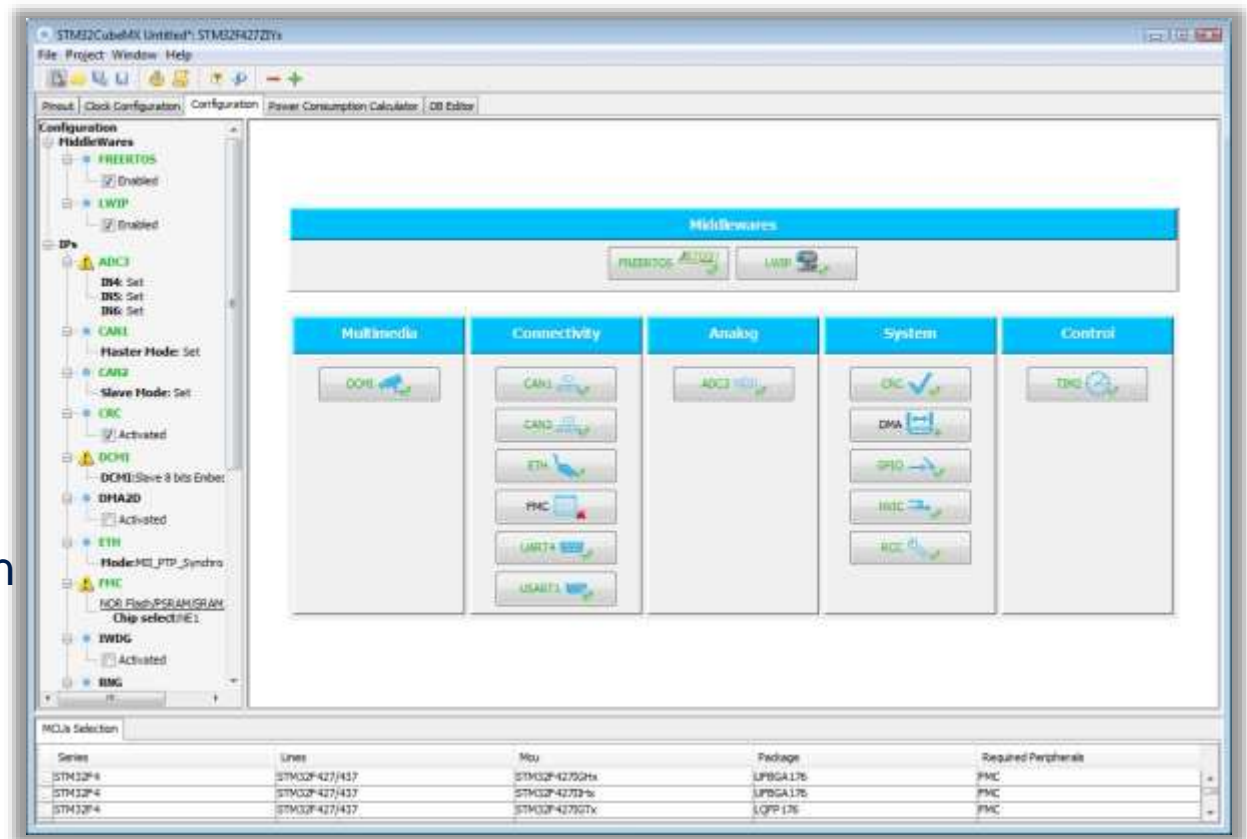
- Immediate display of all clock values
- Management of all clock constraints
- Highlight of errors



STM32CubeMX: Peripheral and middleware configuration

34

- Global view of used peripherals and middleware
- Highlight of configuration errors
 - + Not configured
 - ✓ OK
 - ✗ Error
- Read only tree view on the left with access to IPs / Middleware having no impact on the pinout



STM32CubeMX: Peripheral and middleware configuration

35

- Parameters with management of dependencies and constraints
- Interrupts
- GPIO
- DMA

The screenshot shows the 'SAI Configuration' window in STM32CubeMX. The window has four tabs: 'Parameter Settings' (selected), 'NVIC Settings', 'GPIO Settings', and 'DMA Settings'. Below the tabs, it says 'Configure the below parameters :'. The main area is titled 'SAI A' and contains a table of parameters grouped into sections: Basic Parameters, Frame Parameters, Slot Parameters, and Clock Parameters. The parameters are configured as follows:

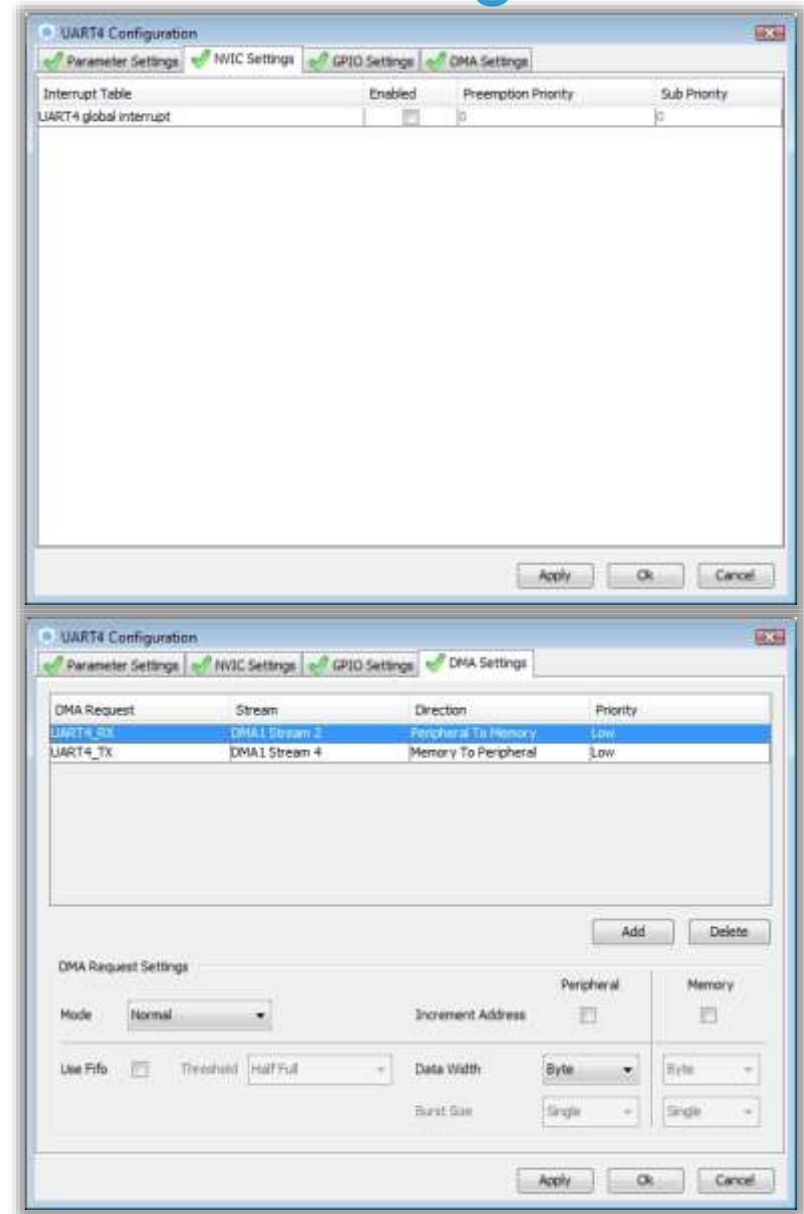
Section	Parameter	Value
Basic Parameters	Protocol	Free
	Audio Mode	Master Transmit
	Frame Length (only Even Values)	24 bits
	Data Size	24 Bits
	Slot Size	DataSize
Frame Parameters	First Bit	MSB First
	Frame Synchro Active Level Length	1
	Frame Synchro Definition	Start Frame
	Frame Synchro Polarity	Active Low
	Frame Synchro Offset	First Bit
Slot Parameters	First Bit Offset	0
	Number of Slots	1
	Slot Active Final Value	0x00000000
	Slot Active	Neither
Clock Parameters	Clock Source	SAI PLL Clock
	Master Clock Divider	Disabled

At the bottom of the window are three buttons: 'Apply', 'Ok', and 'Cancel'.

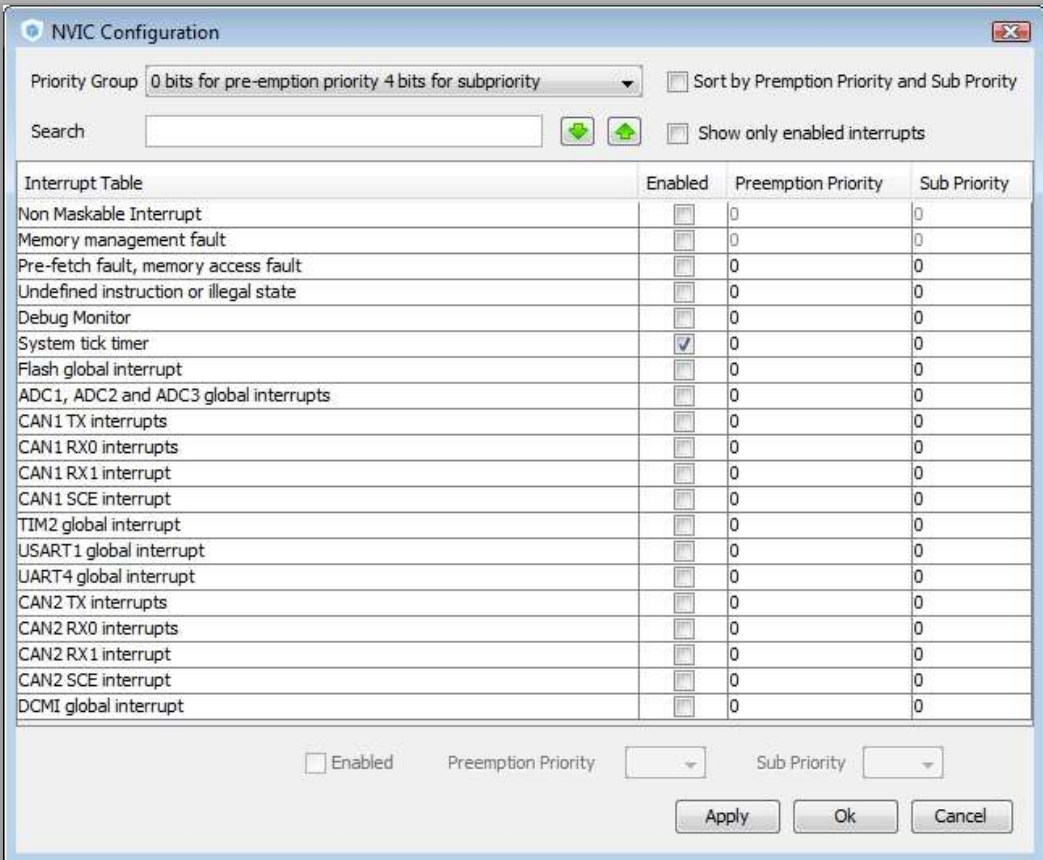
STM32CubeMX: Peripheral and middleware configuration

36

- Manage Interruptions
 - priorities can only be set in the NVIC global view
- Manage GPIO parameters
- Manage DMA
 - Configure all the parameters of the DMA request
 - Runtime parameters (start address, ...) are not managed



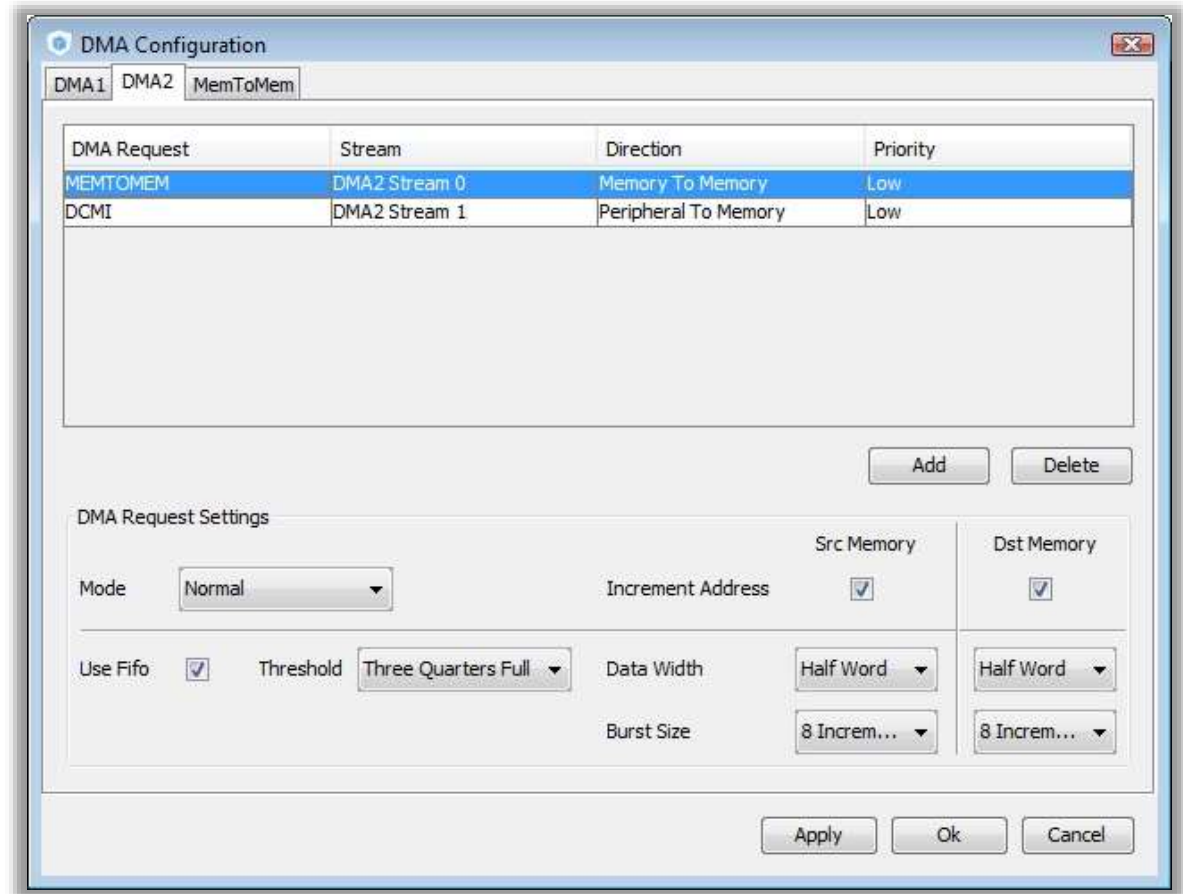
- Manage all interruptions
- Manage priorities and sort by priorities
- Search for a specific interrupt in the list



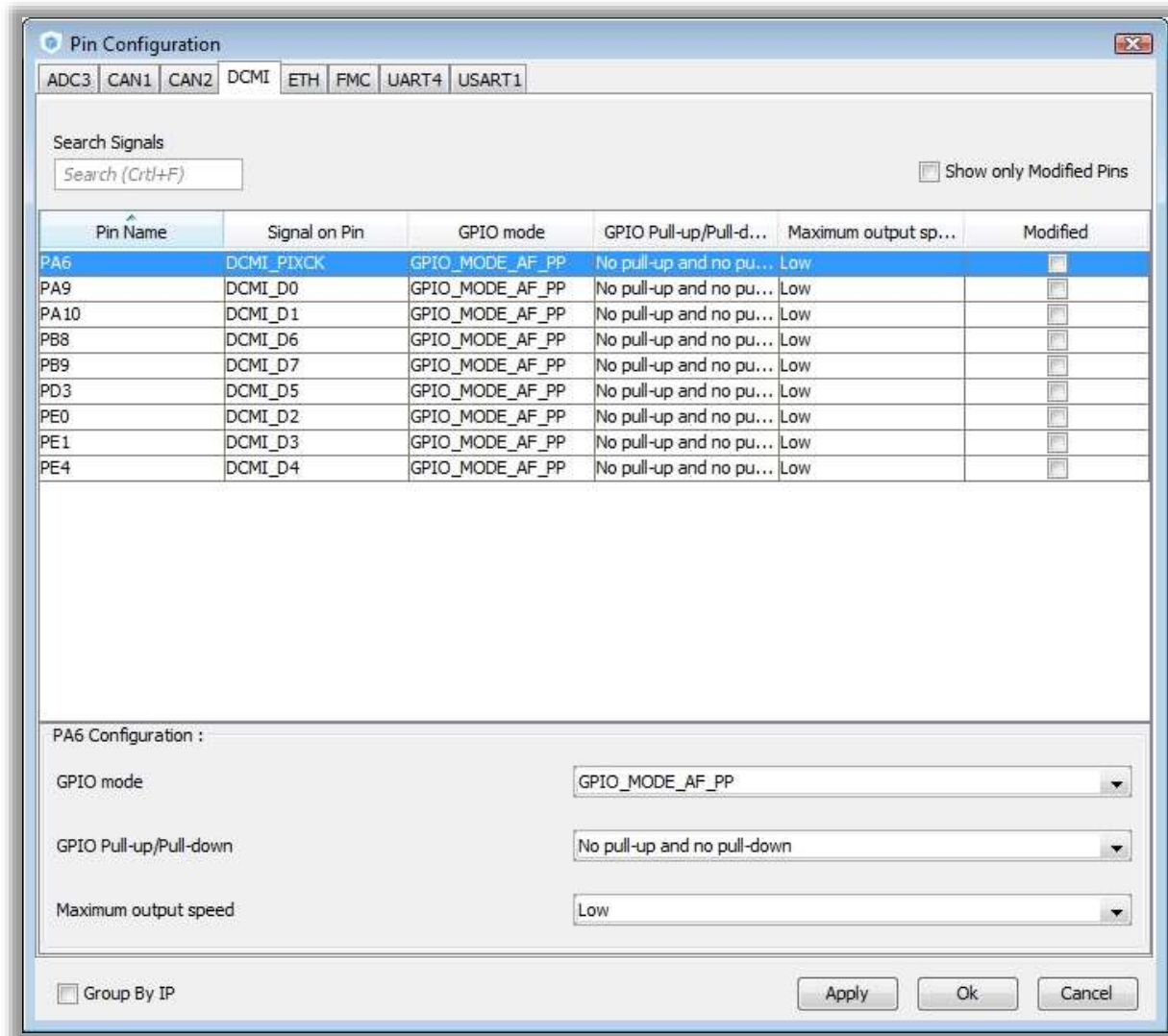
The image shows the 'NVIC Configuration' window from a development tool. It features a search bar at the top, a 'Priority Group' dropdown set to '0 bits for pre-emption priority 4 bits for subpriority', and checkboxes for 'Sort by Preemption Priority and Sub Priority' and 'Show only enabled interrupts'. Below these is a table of interrupts. The 'System tick timer' interrupt is checked as enabled. At the bottom, there are filters for 'Enabled', 'Preemption Priority', and 'Sub Priority', along with 'Apply', 'Ok', and 'Cancel' buttons.

Interrupt Table	Enabled	Preemption Priority	Sub Priority
Non Maskable Interrupt	<input type="checkbox"/>	0	0
Memory management fault	<input type="checkbox"/>	0	0
Pre-fetch fault, memory access fault	<input type="checkbox"/>	0	0
Undefined instruction or illegal state	<input type="checkbox"/>	0	0
Debug Monitor	<input type="checkbox"/>	0	0
System tick timer	<input checked="" type="checkbox"/>	0	0
Flash global interrupt	<input type="checkbox"/>	0	0
ADC1, ADC2 and ADC3 global interrupts	<input type="checkbox"/>	0	0
CAN1 TX interrupts	<input type="checkbox"/>	0	0
CAN1 RX0 interrupts	<input type="checkbox"/>	0	0
CAN1 RX1 interrupt	<input type="checkbox"/>	0	0
CAN1 SCE interrupt	<input type="checkbox"/>	0	0
TIM2 global interrupt	<input type="checkbox"/>	0	0
USART1 global interrupt	<input type="checkbox"/>	0	0
UART4 global interrupt	<input type="checkbox"/>	0	0
CAN2 TX interrupts	<input type="checkbox"/>	0	0
CAN2 RX0 interrupts	<input type="checkbox"/>	0	0
CAN2 RX1 interrupt	<input type="checkbox"/>	0	0
CAN2 SCE interrupt	<input type="checkbox"/>	0	0
DCMI global interrupt	<input type="checkbox"/>	0	0

- Manage All DMA requests including Memory to Memory
- Set Direction and priority
- Set specific parameters



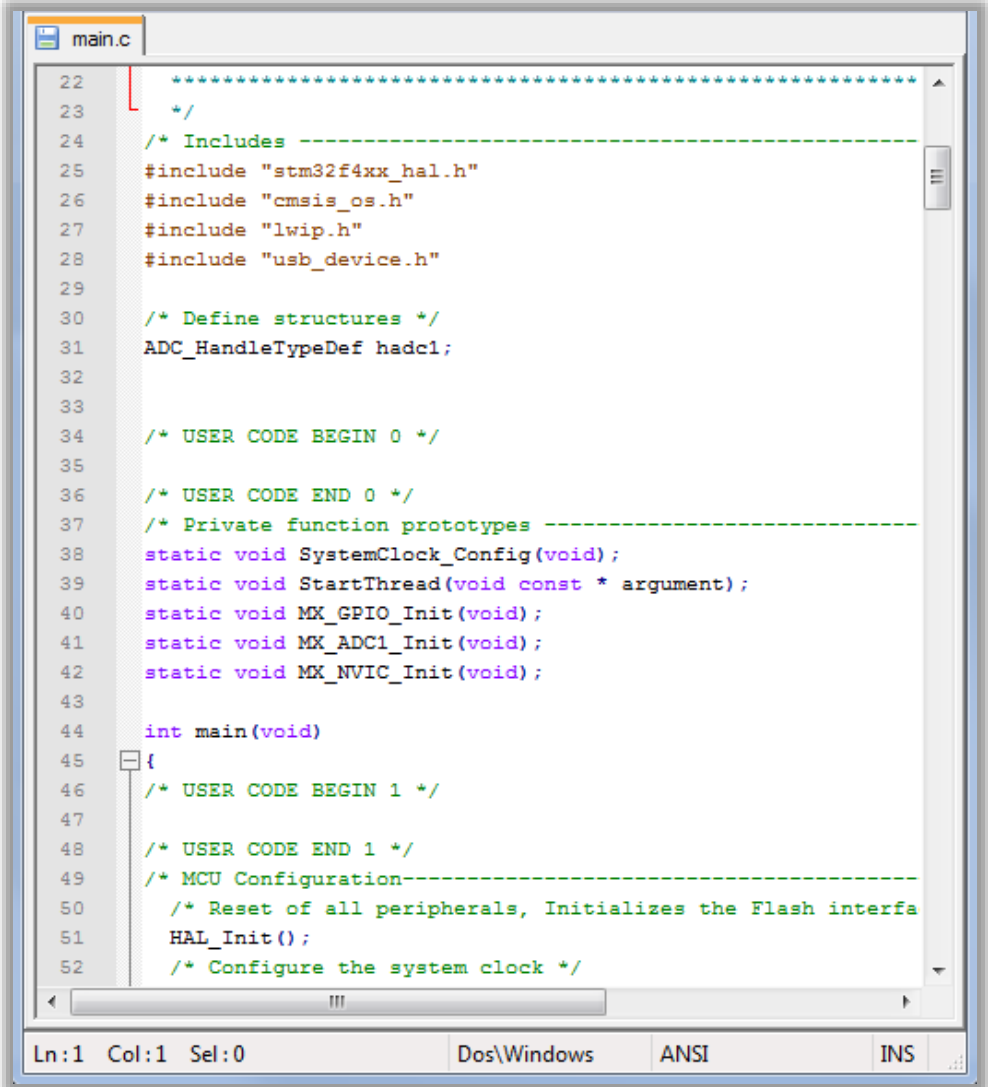
- Most of the GPIO parameters are set by default to the correct value
- You may want to change the maximum output speed
- You can select multiple pin at a time to set the same parameter



STM32CubeMX: Code generation

40

- Generation of all the C initialization code
- Automatic integration with partners toolchains
- User code can be added in dedicated sections and will be kept upon regeneration
- Required library code is automatically copied or referenced in the project (updater)



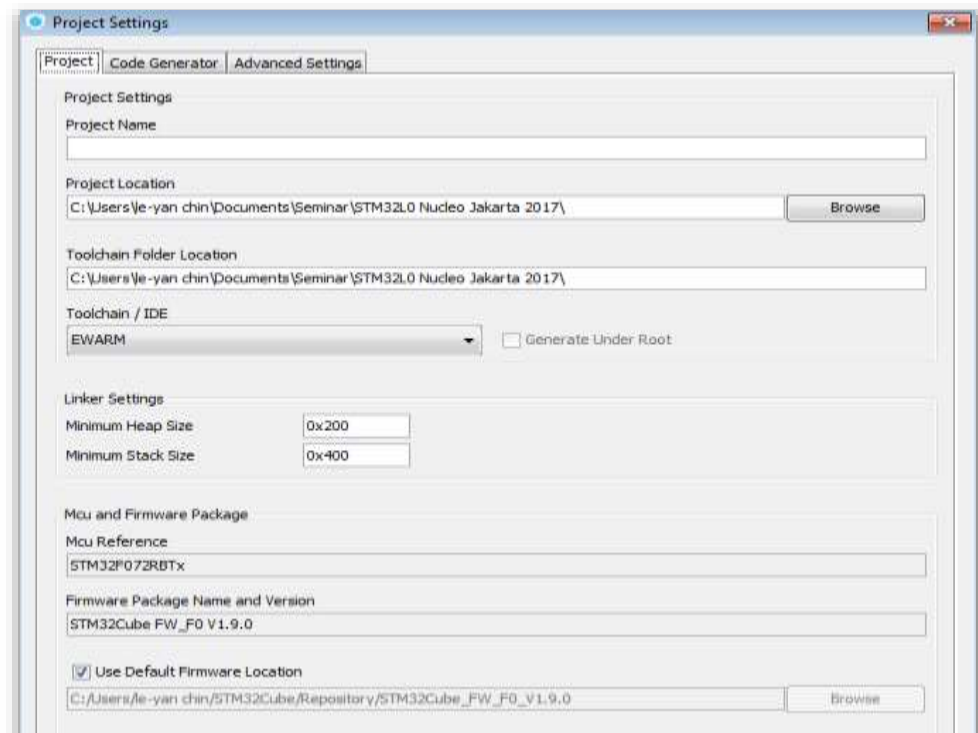
```
main.c
22  /*
23  */
24  /* Includes -----
25  #include "stm32f4xx_hal.h"
26  #include "cmsis_os.h"
27  #include "lwip.h"
28  #include "usb_device.h"
29
30  /* Define structures */
31  ADC_HandleTypeDef hadc1;
32
33
34  /* USER CODE BEGIN 0 */
35
36  /* USER CODE END 0 */
37  /* Private function prototypes -----
38  static void SystemClock_Config(void);
39  static void StartThread(void const * argument);
40  static void MX_GPIO_Init(void);
41  static void MX_ADC1_Init(void);
42  static void MX_NVIC_Init(void);
43
44  int main(void)
45  {
46  /* USER CODE BEGIN 1 */
47
48  /* USER CODE END 1 */
49  /* MCU Configuration-----
50  /* Reset of all peripherals, Initializes the Flash interface
51  HAL_Init();
52  /* Configure the system clock */
```


- Help->Updater settings
 - Choose location of STM32CubeFirmware libraries repository
 - Choose manual or automatic check
 - Configure connection parameters
 - Try to “Use System Proxy Parameters” first
 - If it doesn’t work check with IT department
 - Alternatively, manually check and download from ST website
- Help->Install new libraries : Manage the content of the library repository
 - Click on the check button to see what is available
 - Select the library you want to install and click install now
 - The libraries will be automatically downloaded and unzipped

STM32CubeMX: Project settings

42

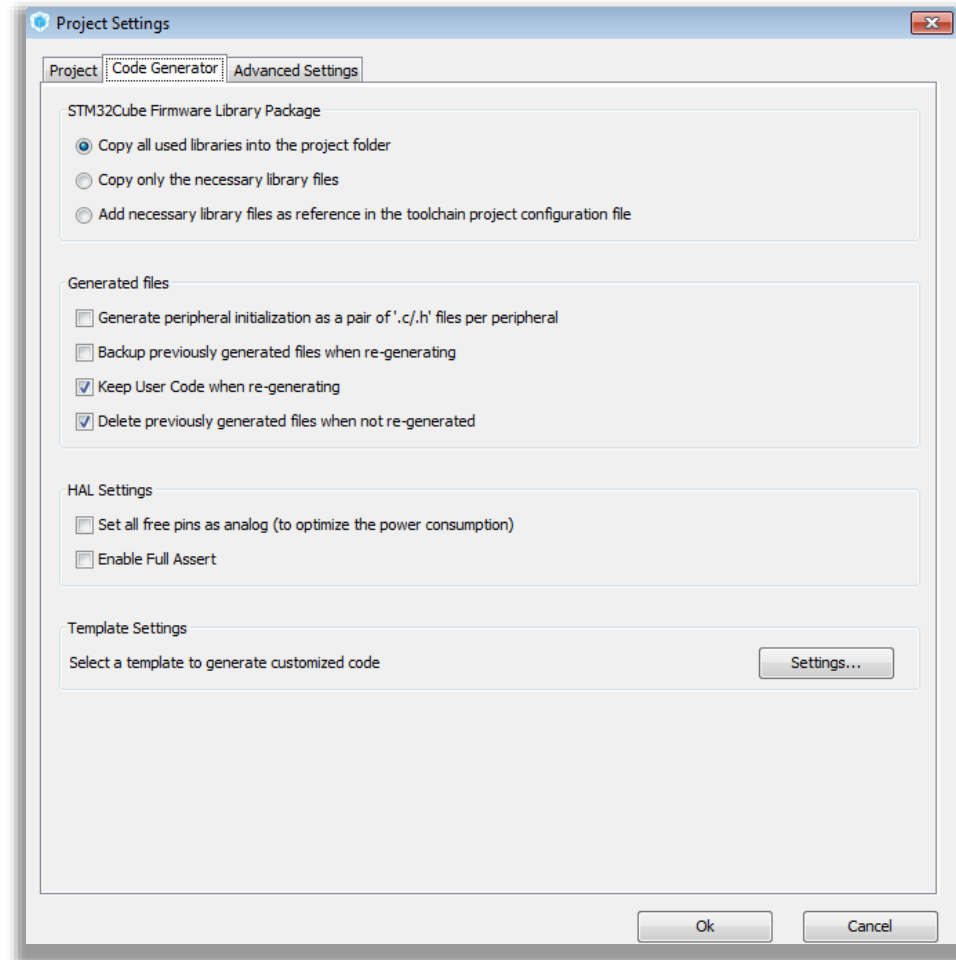
- Project -> Settings
 - Set project name and location
 - A full folder will be created named with the project name.
 - Inside this folder you'll find the saved configuration and all the generated code
 - Select toolchain (Keil, IAR, Atollic, SW4STM32)
 - You can choose to use the latest version of the firmware library or a specific one



STM32CubeMX: Code Generator settings

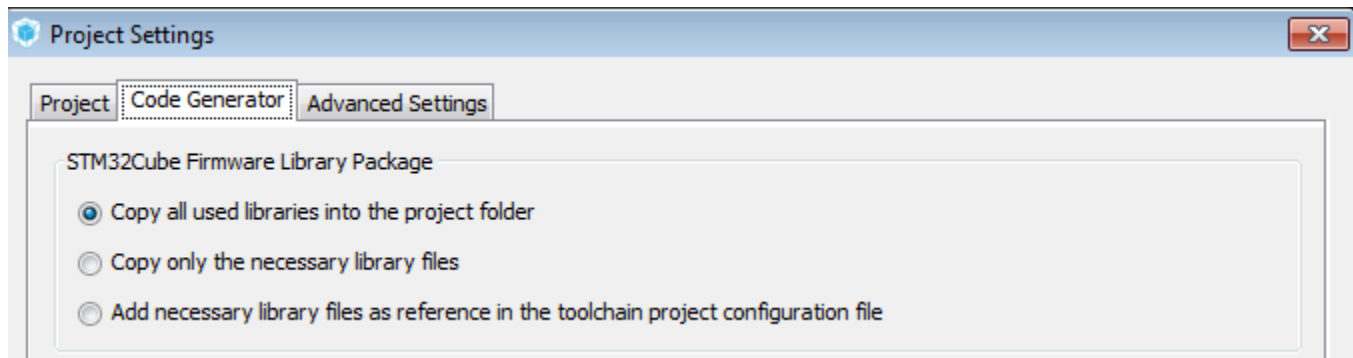
43

- Code generator options
 - Either copy the full library or only the necessary files or just reference the files from the common repository
 - Generate all peripherals initialization in the stm32fYxx_hal_msp.c file or one file per peripheral
 - Keep user code or overwrite it (code between User code comment sections)
 - Delete or keep files that are not useful anymore
 - Set free pins as analog, this settings helps keep low consumption (**if SWD/JTAG is not selected in pinout, this option will disable it**)
 - Enable full assert in project, this help discover incorrect HAL function parameter used in user code

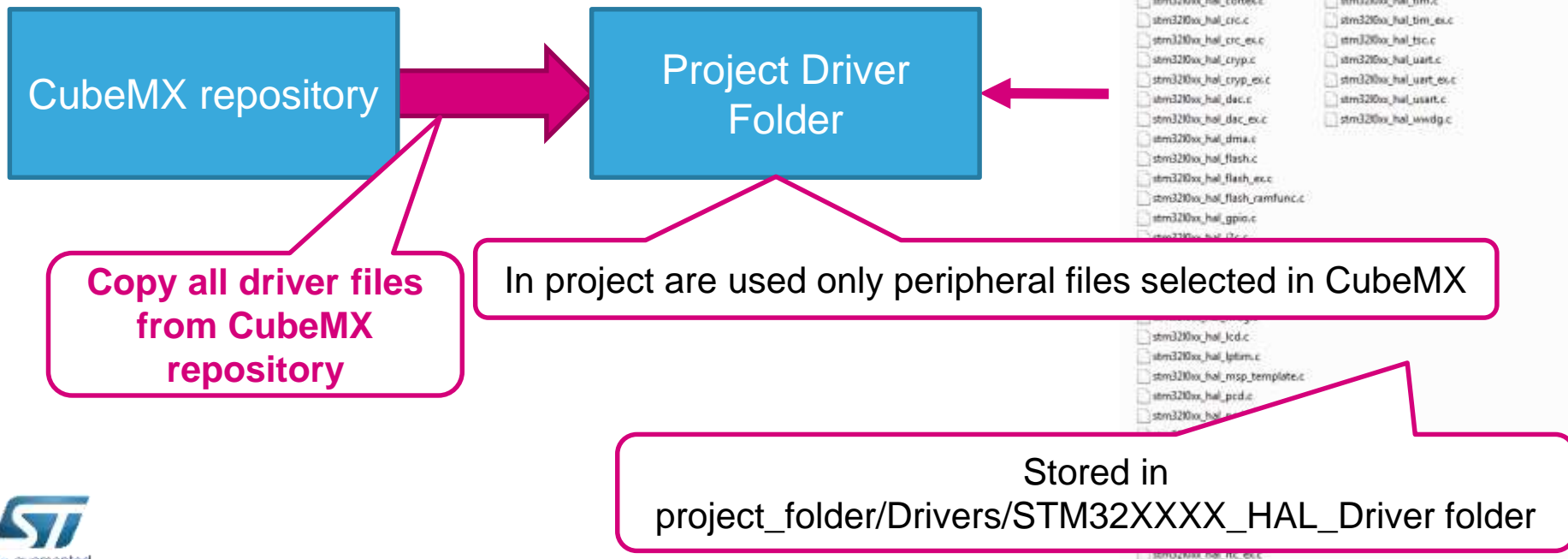


Code Generator options : STM32Cube Firmware Library package

44

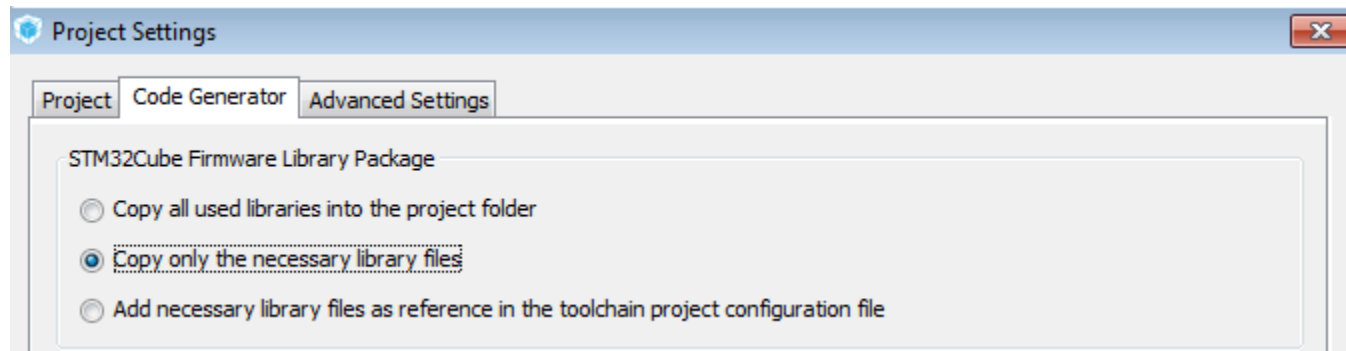


- Copy all used libraries into the project folder

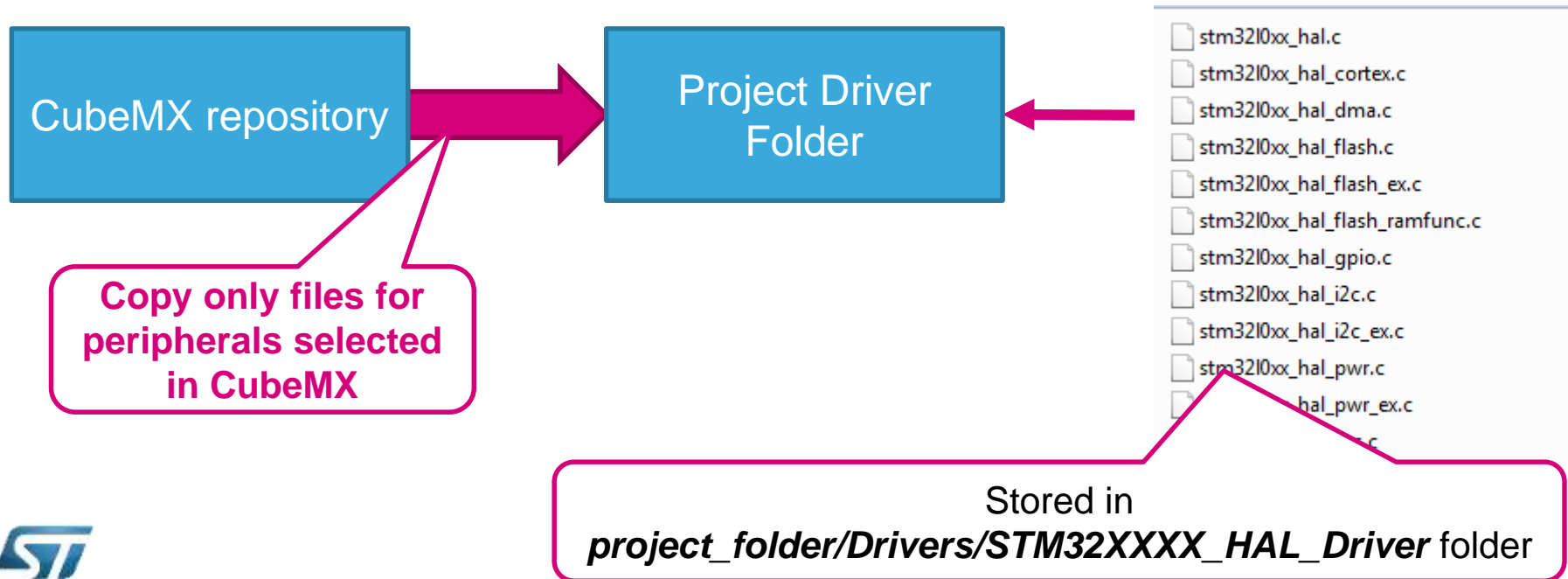


Code Generator options : STM32Cube Firmware Library package

45

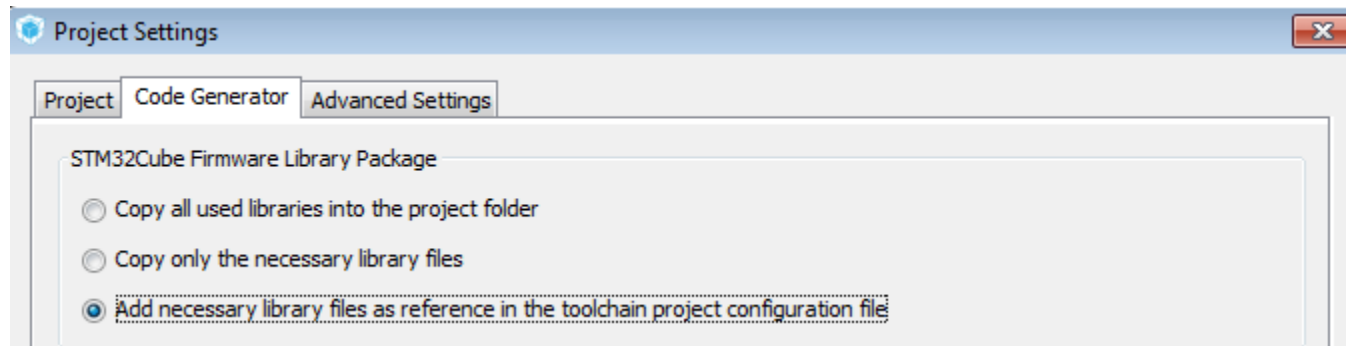


- Copy only the necessary library files

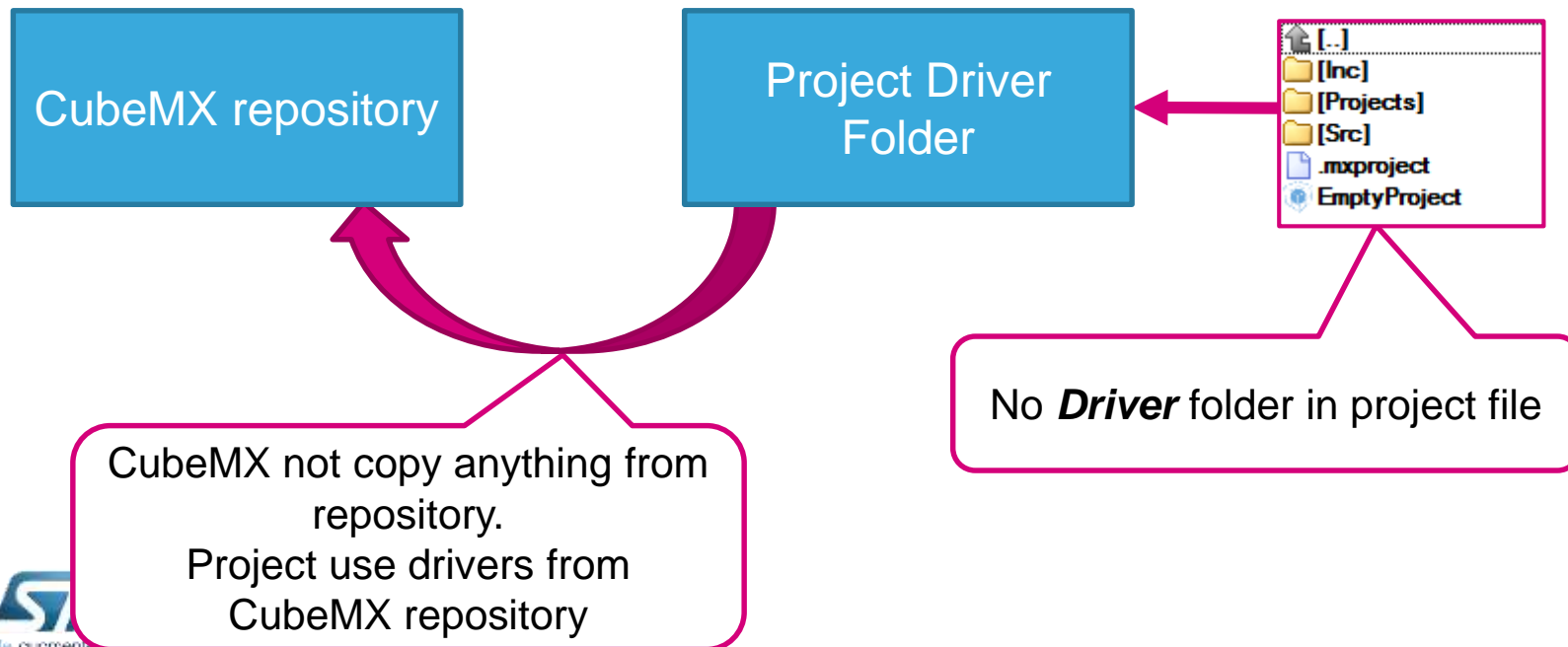


Code Generator options : STM32Cube Firmware Library package

46



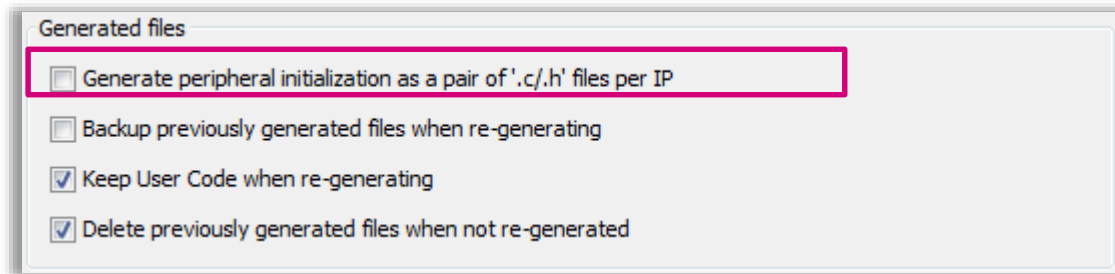
- Add necessary library files as reference in the toolchain project configuration file



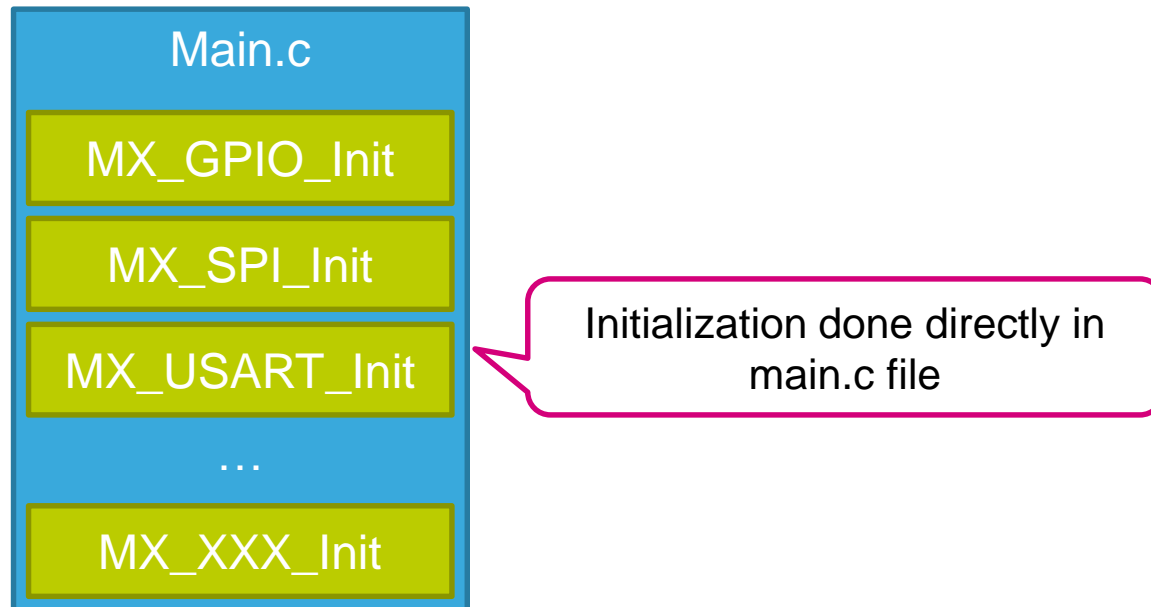
Code Generator options:

Generate peripheral initialization as a pair of '.c/.h' files per IP

47



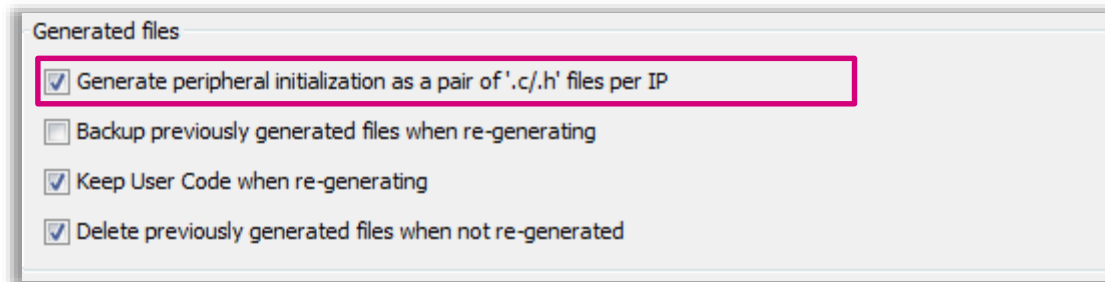
- By default this option is not used. All peripheral initialization code are generated in main.c



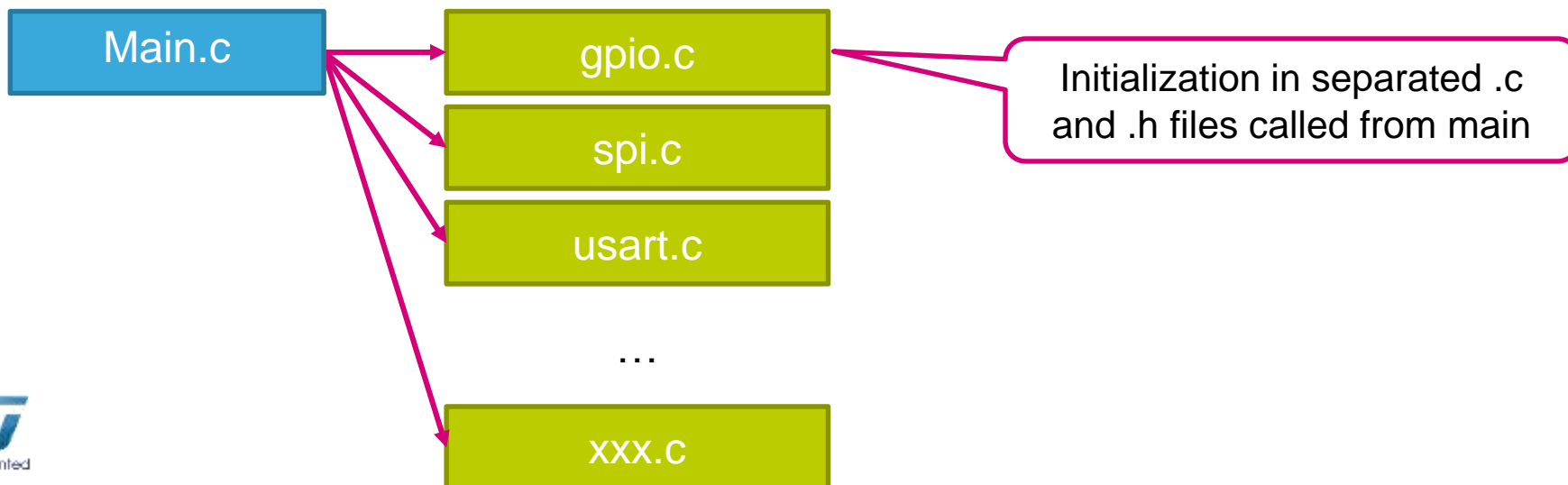
Code Generator options:

Generate peripheral initialization as a pair of '.c/.h' files per IP

48

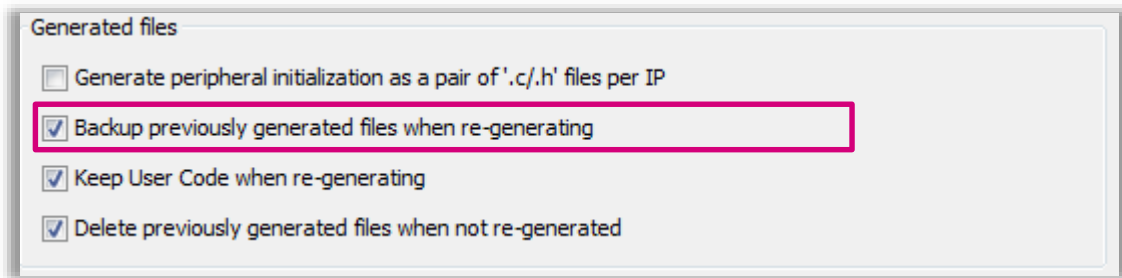


- Generate dedicated initialization .c and .h file for each periphery
- Advantage is that with .h file we can call MX_XXX init functions from every file in project not only from main.c

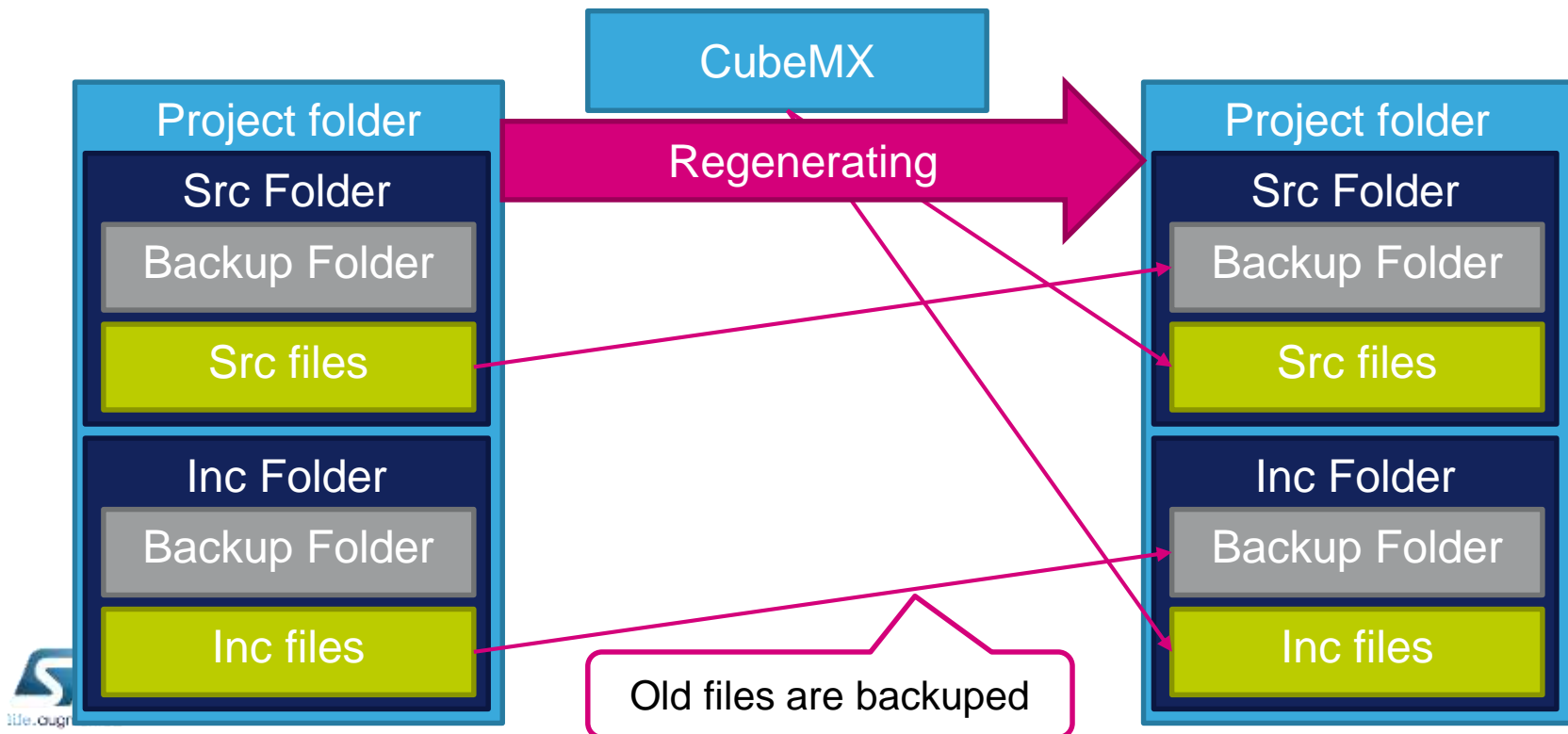


Backup previously generated files when re-generating

49



- Backup old files from **Src** and **Inc** folder into **Backup** folder



Keep User Code when re-generating

50

- Generated code contains USER CODE areas
- These areas are reserved in new code generation, if this option is selected

```
/* USER CODE BEGIN PFP */  
  
/* USER CODE END PFP */  
/* USER CODE BEGIN 0 */  
  
/* USER CODE END 0 */  
int main(void)  
{  
    /* USER CODE BEGIN 1 */  
  
    /* USER CODE END 1 */  
    /* MCU Configuration-----*/  
    /* Reset of all peripherals, Initializes the Flash interface and the Systick. */  
    HAL_Init();  
    /* Configure the system clock */  
    SystemClock_Config();  
    /* Initialize all configured peripherals */  
    /* USER CODE BEGIN 2 */  
  
    /* USER CODE END 2 */  
    /* USER CODE BEGIN 3 */  
    /* Infinite loop */  
    while (1)  
    {  
  
    }  
    /* USER CODE END 3 */  
}
```

Here can user put his code,
code will be preserved during
project generation

Generated files

- ☐ Generate peripheral initialization as a pair of '.c/.h' files per IP
- ☐ Backup previously generated files when re-generating
- ☒ Keep User Code when re-generating
- ☒ Delete previously generated files when not re-generated

Keep User Code when re-generating

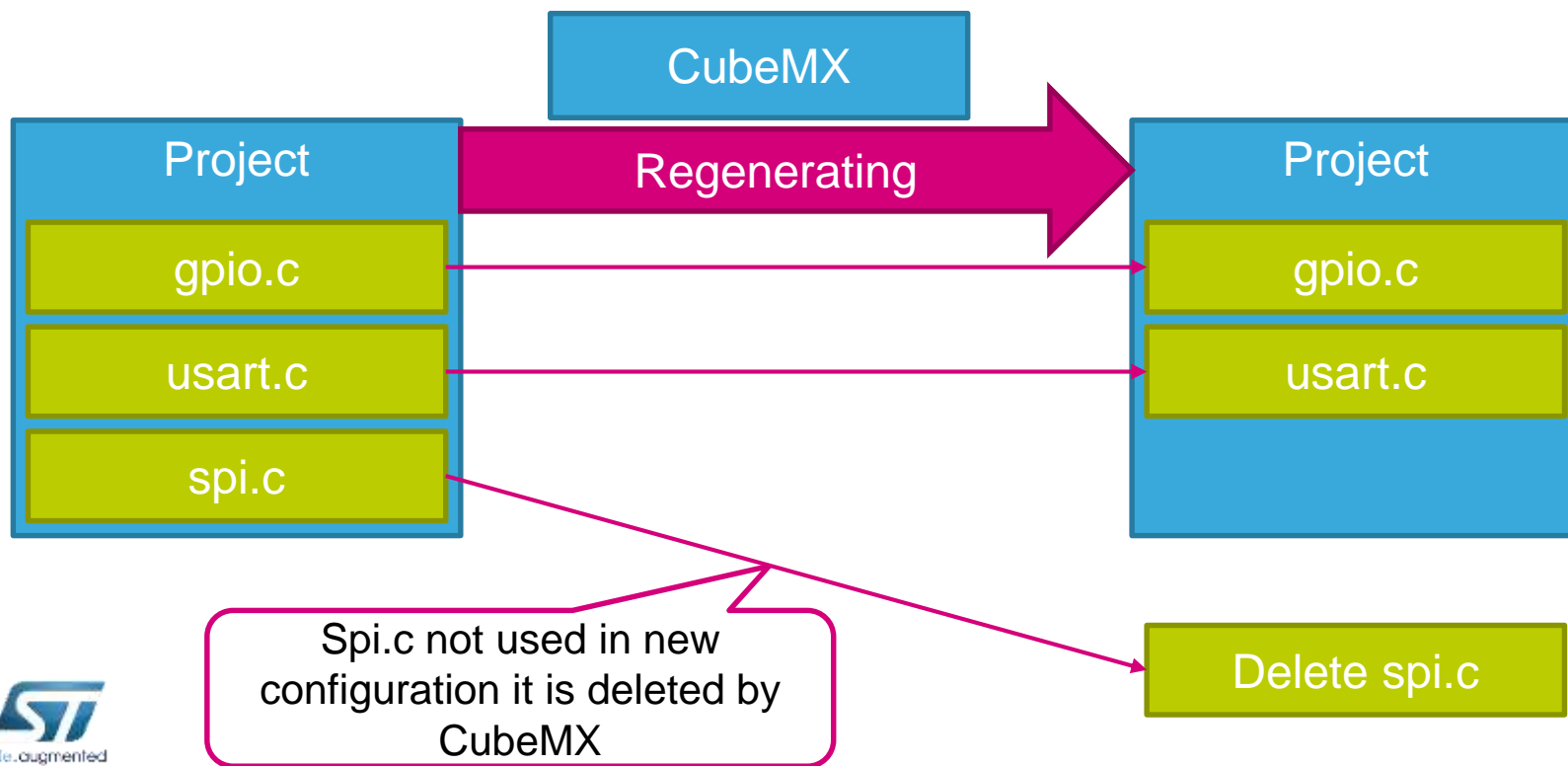
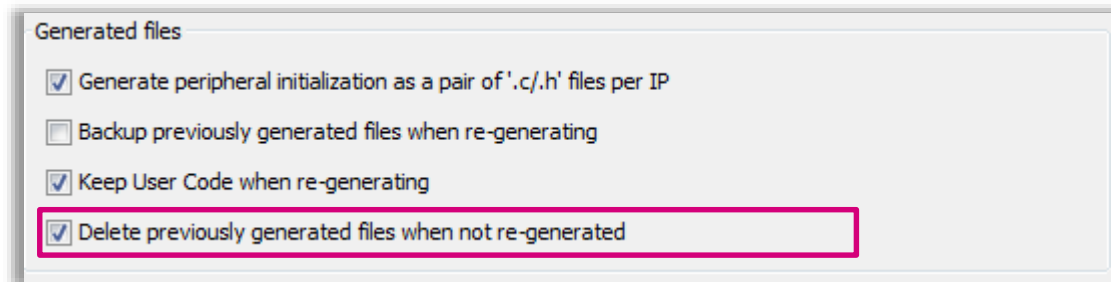
51

- Generated code contains USER CODE areas
- These areas are reserved in new code generation, if this option is selected
- Areas present in files generated by CubeMX
 - Main.c
 - Stm32l0xx_it.c
 - Stm32l0xx_hal_msp.c
- Areas cover important areas used for:
 - Includes
 - Variables
 - Function prototypes
 - Functions

```
/* USER CODE BEGIN PFP */  
  
/* USER CODE END PFP */  
/* USER CODE BEGIN 0 */  
  
/* USER CODE END 0 */
```

Code Generator options: Delete previously generated files when re-generating

52



Set all free pins as analog

53

- This settings optimize power consumption of unused pins

HAL Settings

☒ Set all free pins as analog (to optimize the power consumption)

☐ Enable Full Assert

Not used pins(grays)
will be in project
configured as analog

STM32F429ZITx
LQFP144

CubeMX

Generating

Project

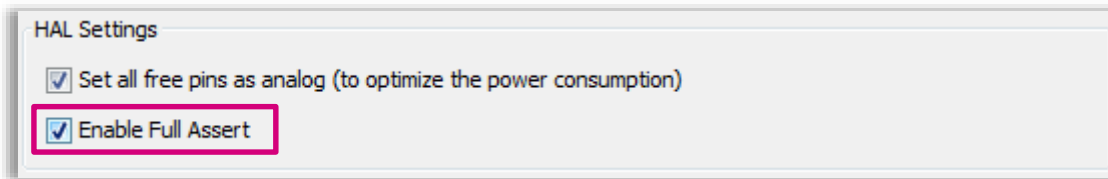
MX_GPIO_Init

Initialization of unused
pins is in MX_GPIO_Init

- If the **JTAG/SWD is not selected** in CubeMX, MX_GPIO_Init reconfigure JTAG/SWD pins to analog and this **disable debug possibilities**

Enable Full Assert

54



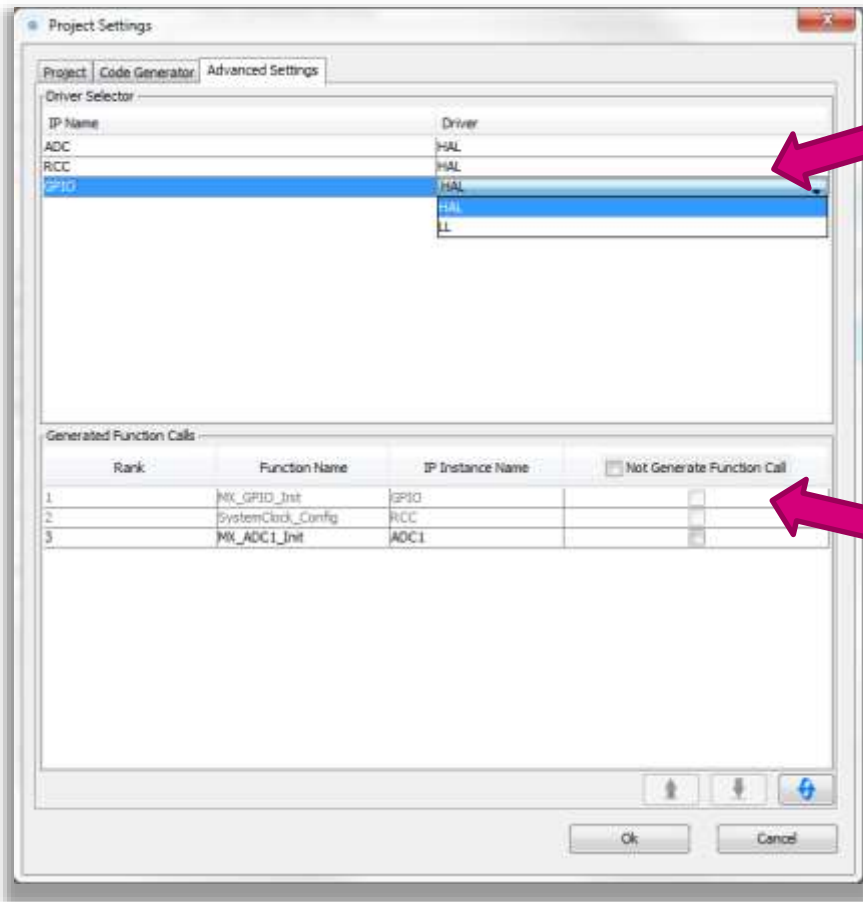
- Feature very useful during debugging
- Function input parameters are checked if they are in correct range, if not application jump into `assert_failed` function in `main.c`

```
/* USER CODE BEGIN 2 */  
HAL_GPIO_TogglePin(GPIOA, (0x1<<17));  
/* USER CODE END 2 */
```

This function trying to configure not existing pin PA17

```
void assert_failed(uint8_t* file, uint32_t line)  
{  
    /* USER CODE BEGIN 6 */  
    /* User can add his own implementation to report the file name and line number,  
       ex: printf("Wrong parameters value: file %s on line %d\r\n", file, line) */  
    /* USER CODE END 6 */  
}
```

If parameter is not in valid range program jump into `assert_failed` function



- API Driver Selector

- Hardware Abstract Layer –use a high abstraction level based on standalone processes
- Low Layer – deeply knowledge Hardware and process flow

- Generated function Call

- The option to generate Initialization function Call of each periphery or not.

Warning and disclaimer

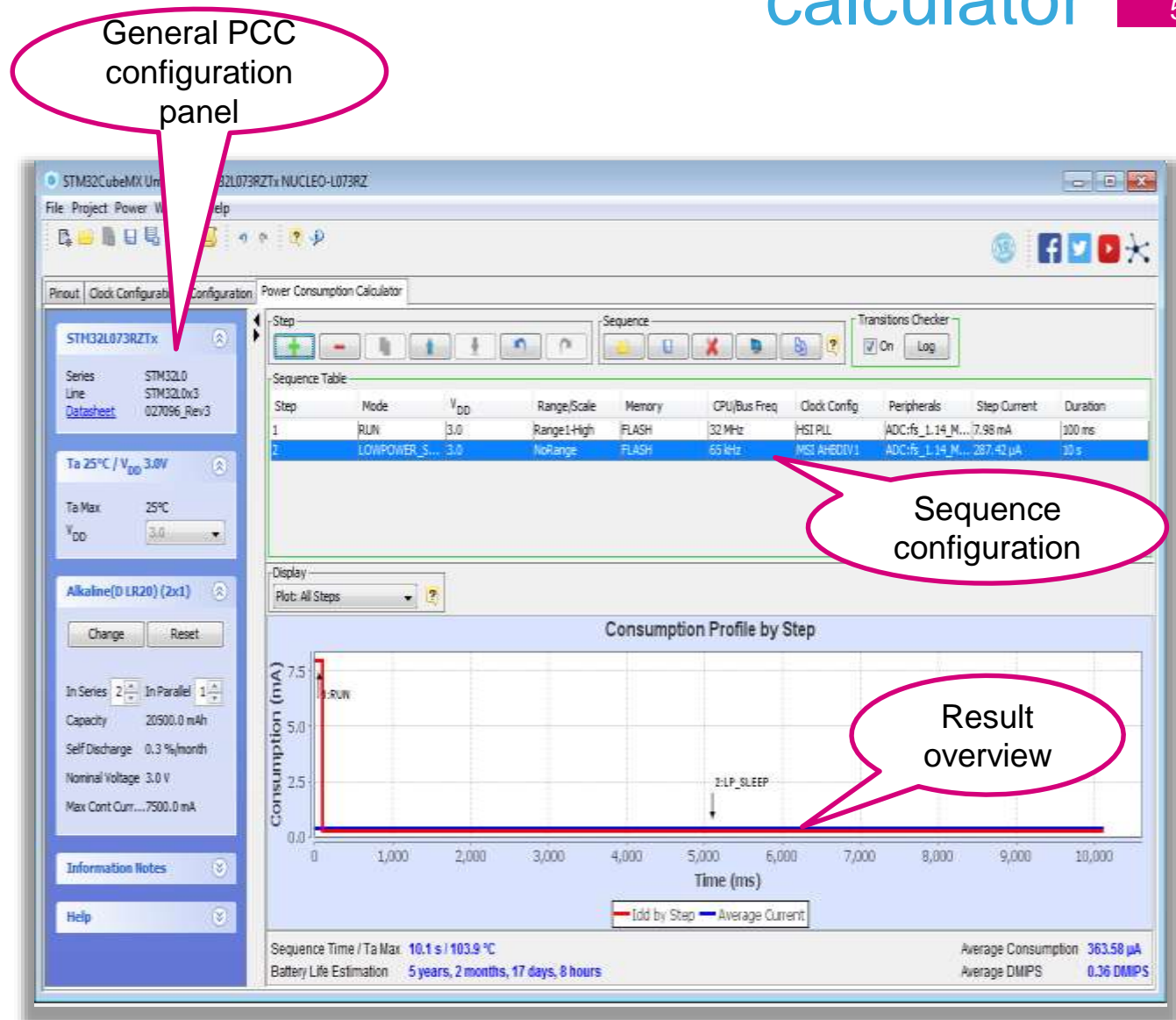
56

- Universal design for the entire STM32 family range at times prevents the tool from focusing on specific features of a particular product.
- **The STM32CubeMX GUI tool is not a replacement for the reference manual or datasheet**
 - Always refer to written documentation for further information!
 - Important features are often available on the product or in the HAL but not in the GUI.
- The GUI helps start a project and initialize a working starting configuration – but the configuration can be dynamically changed at runtime (i.e. GPIO, NVIC priority or clock settings).

STM32CubeMX: Power consumption calculator

57

- Power step definitions
- Battery selection
- Creation of consumption graph
- Display of
 - Average consumption
 - Average DMIPS
 - Battery lifetime



General PCC parameters

58

- MCU selection inherited from STM32CubeMX
 - Use the direct link to the datasheet to get more detailed information.
- Parameter selection
 - Temperature and voltage choice may be limited, depending on the selected MCU.
- Battery selection – select typical or define your own
 - Battery is defined by capacity, voltage, self discharge and current limitations.
- Information notes
 - Purpose is to warn about estimation limitations.

The screenshot shows the 'General PCC parameters' configuration window for the STM32F070RBTx MCU. The window is divided into several sections:

- MCU Selection:** STM32F070RBTx (with an expand/collapse icon).
- Series/Line/Link:** A table showing the selected series (STM32F0), line (STM32F0x0 V...), and a link to the datasheet (027114_Rev2).
- Temperature/Voltage:** Ta 25°C / V_{DD} 3.6V (with a dropdown icon).
- Battery Selection:** Alkaline(D LR20) (2x1) (with an expand/collapse icon).
- Buttons:** 'Change' and 'Reset' buttons.
- Configuration Parameters:**
 - In Series: 2 (with a spinner icon)
 - In Parallel: 1 (with a spinner icon)
 - Capacity: 20500.0 mAh
 - Self Discharge: 0.3 %/month
 - Nominal Voltage: 3.0 V
 - Max Cont Curr...: 7500.0 mA
- Information Notes:** A section with a dropdown icon.
- Help:** A section with a dropdown icon.

Building a sequence

59

- A sequence is a set of ordered steps.

Load existing sequences and adapt them.

Compare sequences, even with different MCUs.

Check automatically if proposed power step transitions are valid.

Create new steps by adding or duplicating existing ones.

The screenshot displays the ST Studio Power Manager interface. At the top, there are buttons for 'Load', 'Save', 'Delete', and 'Compare' under the 'Sequence' tab, and a 'Transitions checker' section with a checked 'Enabled' checkbox and a 'Show log' button. Below this is the 'Sequence Table' with the following data:

Step	Mode	Vdd	Range/Scale	Memory	Clock Config	Src Freq	CPU/Bus...	Periphe...	Add. Cur...	Step Cur...	Duration	DMIPS	Voltage ...
1	RUN	3.6	Range1-High	FLASH	HSEBYP PLL	16.0 MHz	32.0 MHz		0 mA	9.6 mA	0.5 ms	33.0	Battery
2	LOWPOWER_RUN	3.6	NoRange	FLASH	MSI AHBDIV1	131.0 kHz	131.0 kHz		0 mA	48 µA	1 ms	0.13509375	Battery
3	STOP	3.6	NoRange	n/a	LSI RTC	37.0 kHz	0 Hz		0 mA	1.4 µA	3 ms	0.0	Battery
4	WU_FROM_STOP	3.6	NoRange	n/a	MSI	65.0 kHz	65.0 kHz		0 mA	1.45 mA	210.0 µs	0.0	Battery
5	RUN	3.6	Range1-High	FLASH	HSEBYP	8.0 MHz	8.0 MHz						

At the bottom, there are buttons for 'Add', 'Delete', 'Duplicate', 'Up', 'Down', 'Undo', and 'Redo' under the 'Step' tab, and a 'Display' section with a 'Plot' button. A log window titled 'Log for current sequence' is open, showing the results of the transitions checker for the selected MCU (STM32L151C8Tx). The log contains the following text:

```
Results for the current sequence (selected MCU: STM32L151C8Tx)

Check transition between step 1 (RUN, Range1-High) and step 2 (LOWPOWER_RUN, NoRange)
Possible next step(s): RUN (Range1-High, Range2-Medium, Range3-Low)
Possible next step(s): LOWPOWER_RUN (NoRange)
***** Transition allowed !

Check transition between step 2 (LOWPOWER_RUN, NoRange) and step 3 (STOP, NoRange)
Possible next step(s): RUN (Range1-High, Range2-Medium, Range3-Low)
Possible next step(s): LOWPOWER_RUN (NoRange)
Possible next step(s): SLEEP (Range1-High, Range2-Medium, Range3-Low)
Possible next step(s): LOWPOWER_SLEEP (NoRange)
***** Transition allowed !

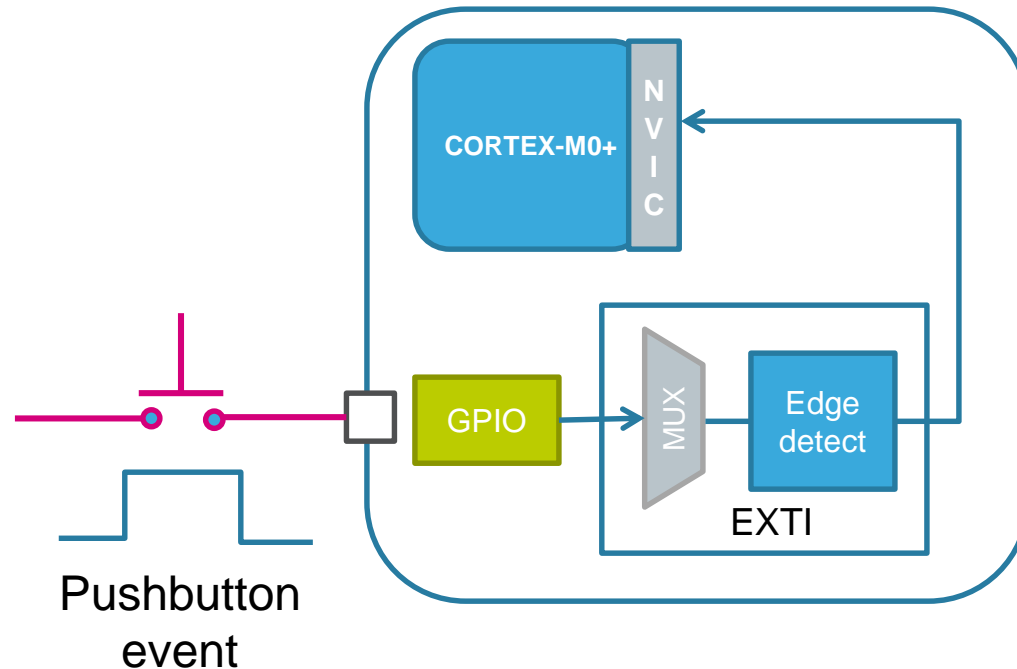
Check transition between step 3 (STOP, NoRange) and step 4 (RUN, Range1-High)
Possible next step(s): WU_FROM_STOP (NoRange)
***** Transition not possible !
```



Hands-on Demo : GPIO and EXTI with STM32CubeMX

GPIO and EXTI Hands-on Demo

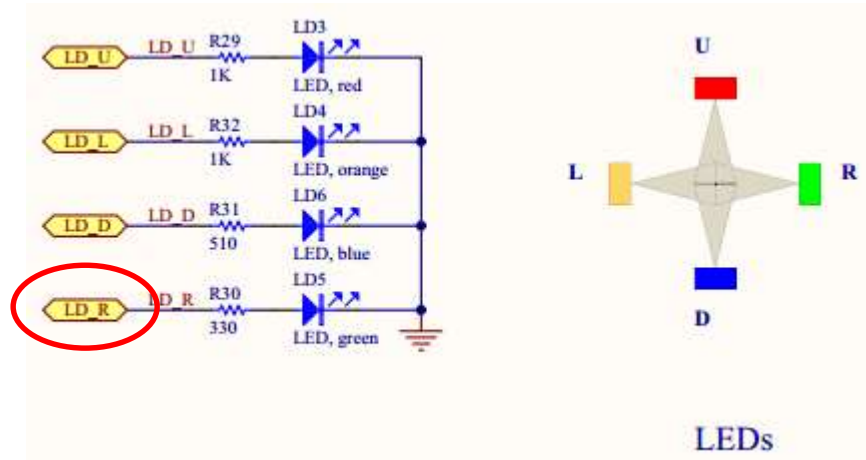
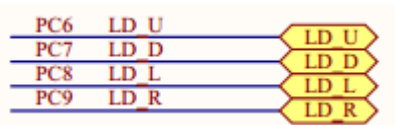
- Part 1: Configure a GPIO in External Interrupt mode.



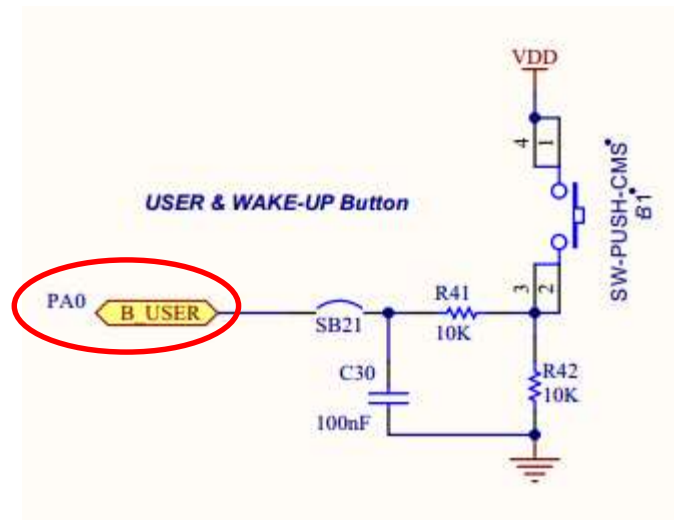
STM32 Nucleo User Pushbutton and LEDs

62

Active High



Active Low



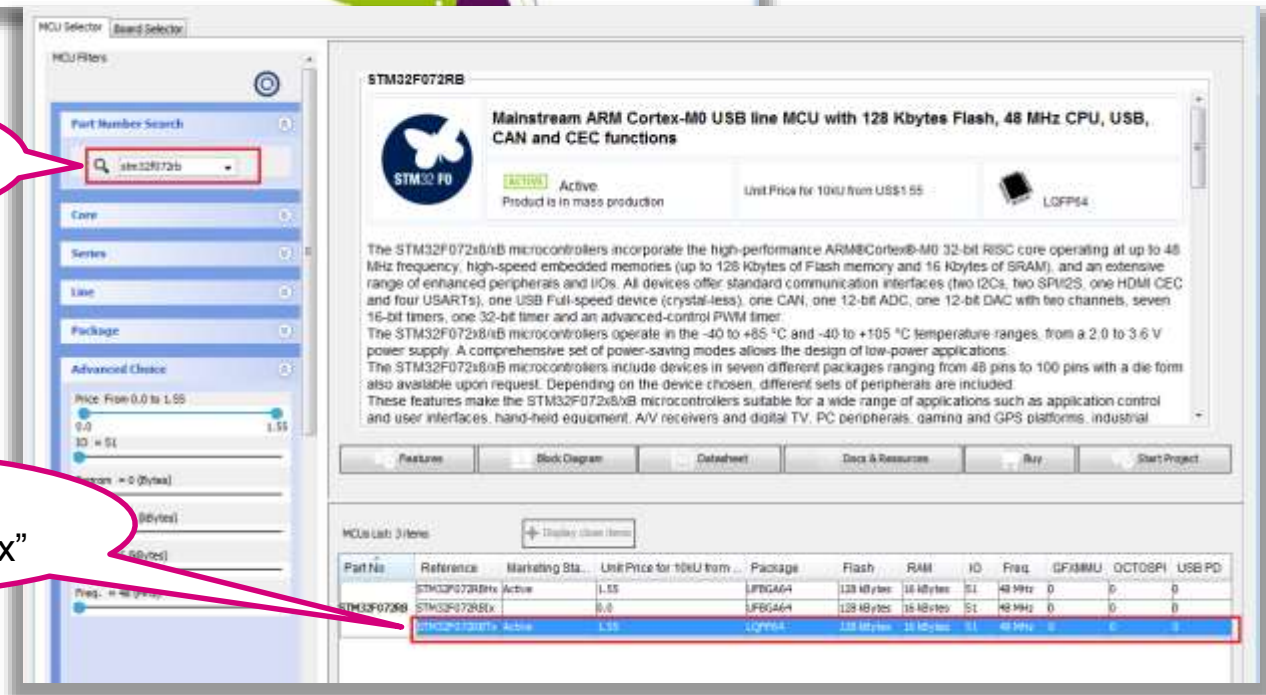
- This hands-on describes how to use the GPIO HAL APIs.
The User pushbutton, configured as input with interrupt, will be used to change the states of the LEDs.
- For this hands-on, the STM32CubeMX will be used to generate the initialization codes for the GPIOs and System clock. This process will speed up the development as the initialization codes are generated by the STM32CubeMX tool. The user then will only need to add the user codes as per application. Recommended especially for first time users of the STM32.
 - Create an new project
 - Target MCU: STM32F072RBT6
 - Save this project in folder below with project name: **Lab-GPIO_EXTI**
 - C:\.\STM32F0 Discovery Exercises**Lab-GPIO_EXTI**
 - In the Project->Settings, same as before, make sure that the following are set:
 - Project
 - Toolchain/IDE: MDK-ARM V5
 - Firmware Package Name and Version: STM32Cube FW_F0 V1.9.0 (or download the STM32CubeF0 latest version)
 - Code Generator
 - Copy only the necessary library files (to reduce the size of the project folder)
 - Keep User Code when re-generating
 - Delete previously generated files when not re-generated

Screenshots

64



Step 2. Type
"STM32F072RB"



Lab-GPIO_EXTI: STM32CubeMX Config

65

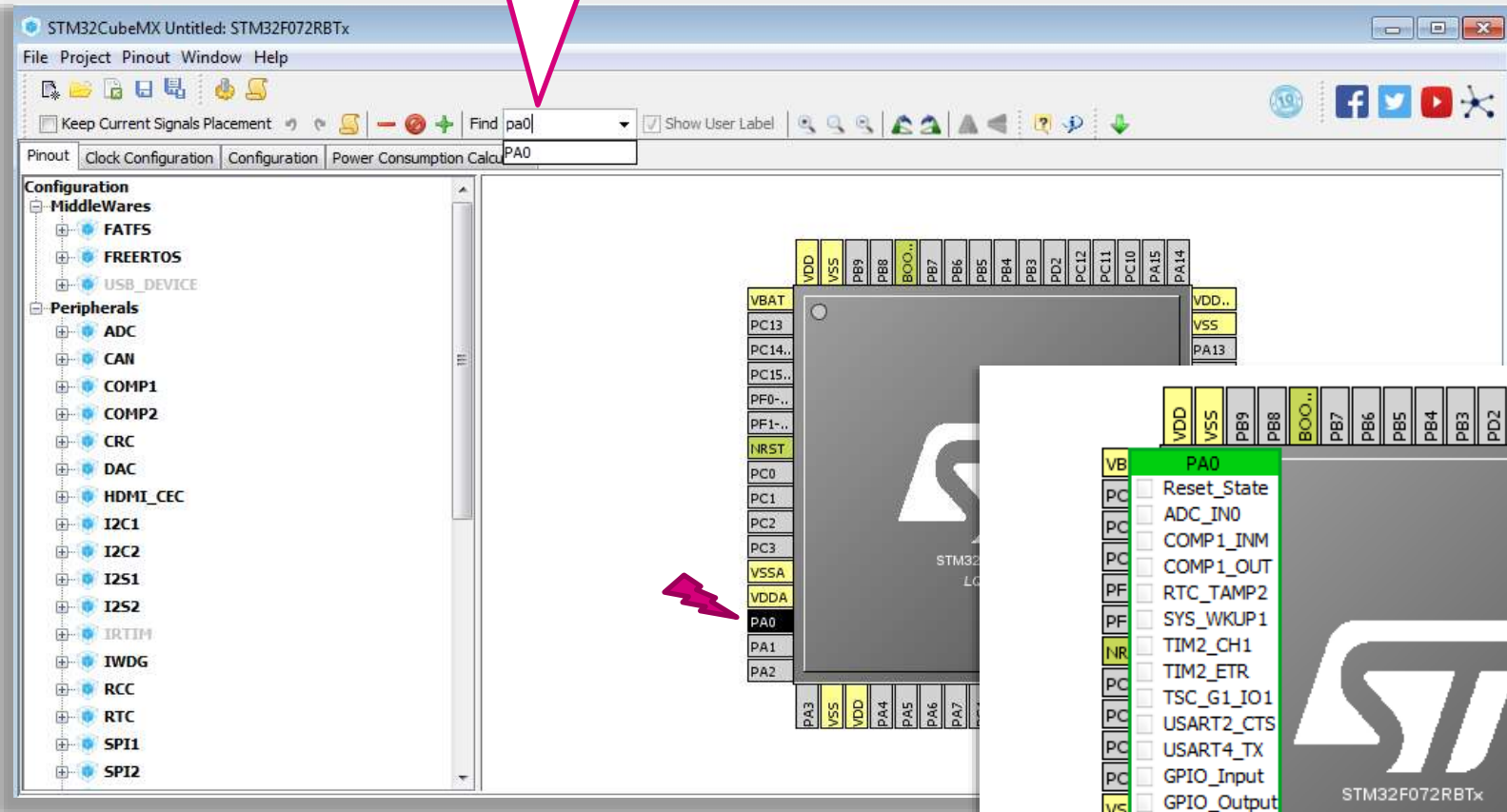
- Objective:
 - Configure the GPIOs for LEDs
 - Configure the GPIO for the User pushbutton as input with interrupt(EXTI).
- Use the STM32CubeMX to configure the GPIOs accordingly:
 - Pinout Tab
 - GPIOs
 - PA0 (User pushbutton) – GPIO EXTI0
 - PC9 (LD_R - Green) – GPIO output
 - Sys (System)
 - Enable Serial Wire Debug (SWD)

Although the SWD debug pins are active after reset, it is a good practice to make sure the debug pins are reserved for debug purposes while assigning pins for your application. This avoids assigning it for other alternate function by mistake while still in firmware development stage

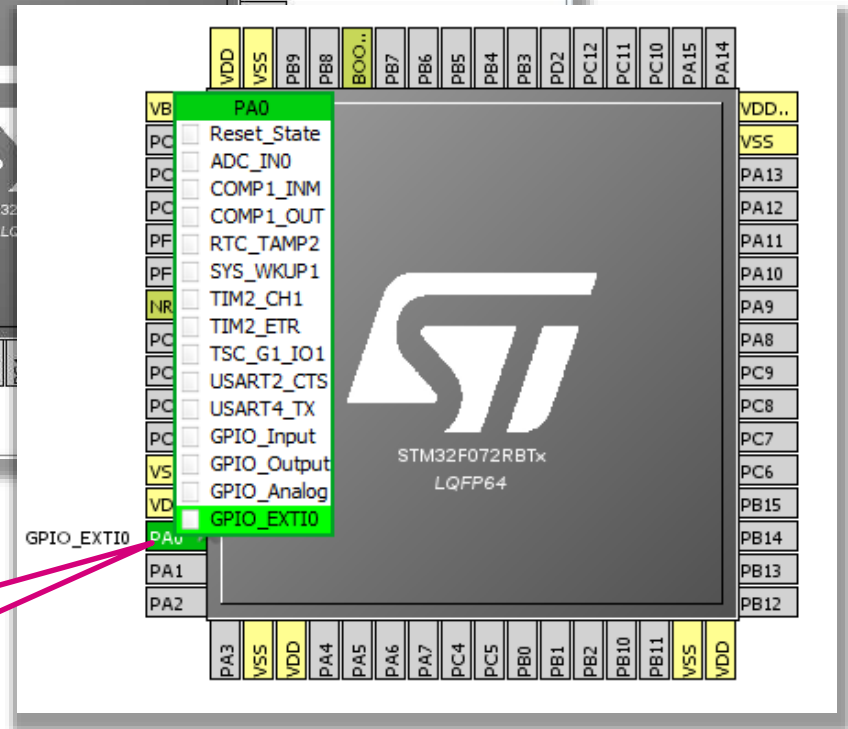
Screenshots

66

Step 3. Type
"pa0" in
Find column



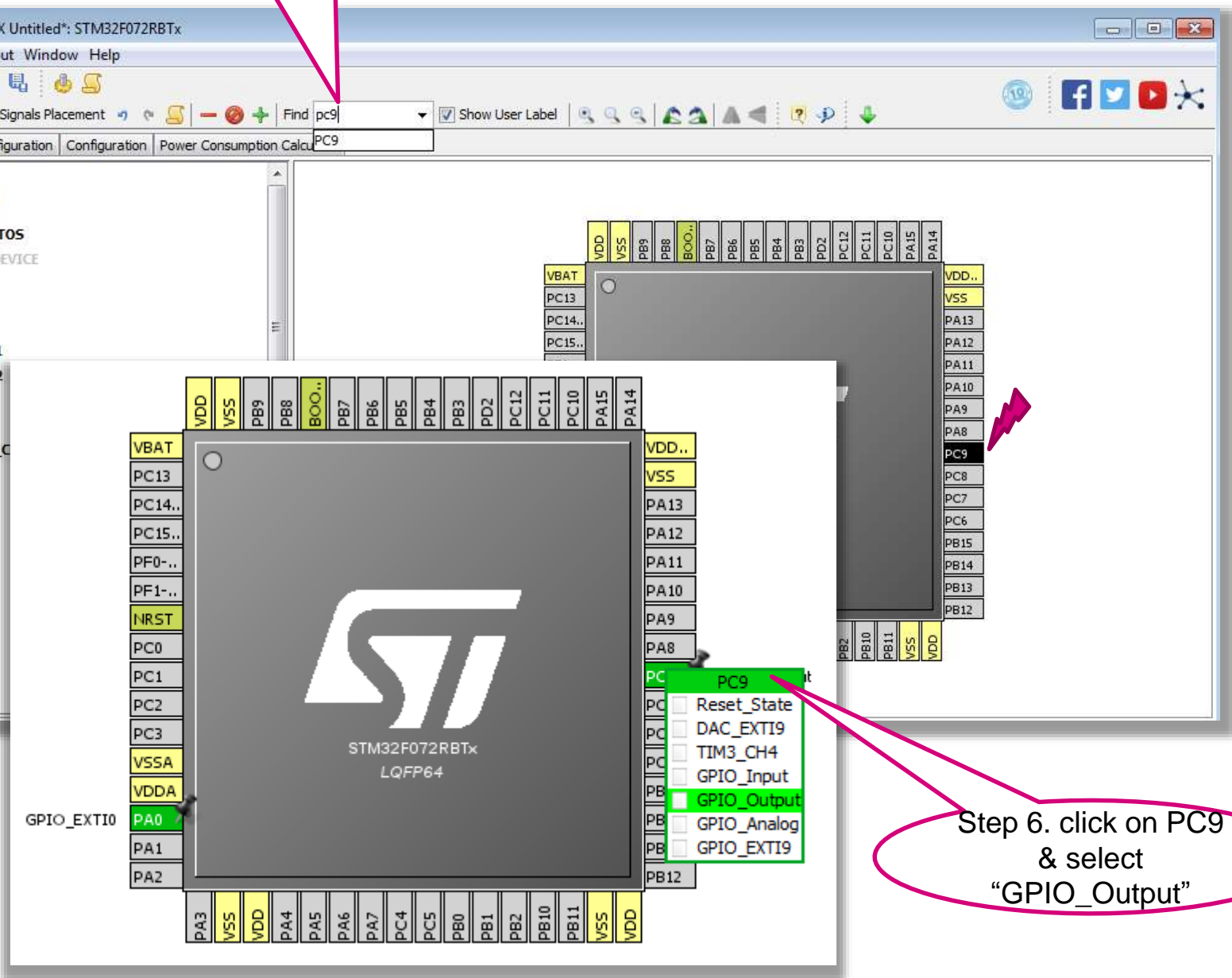
Step 4. click on PA0
& select
"GPIO_EXTI0"

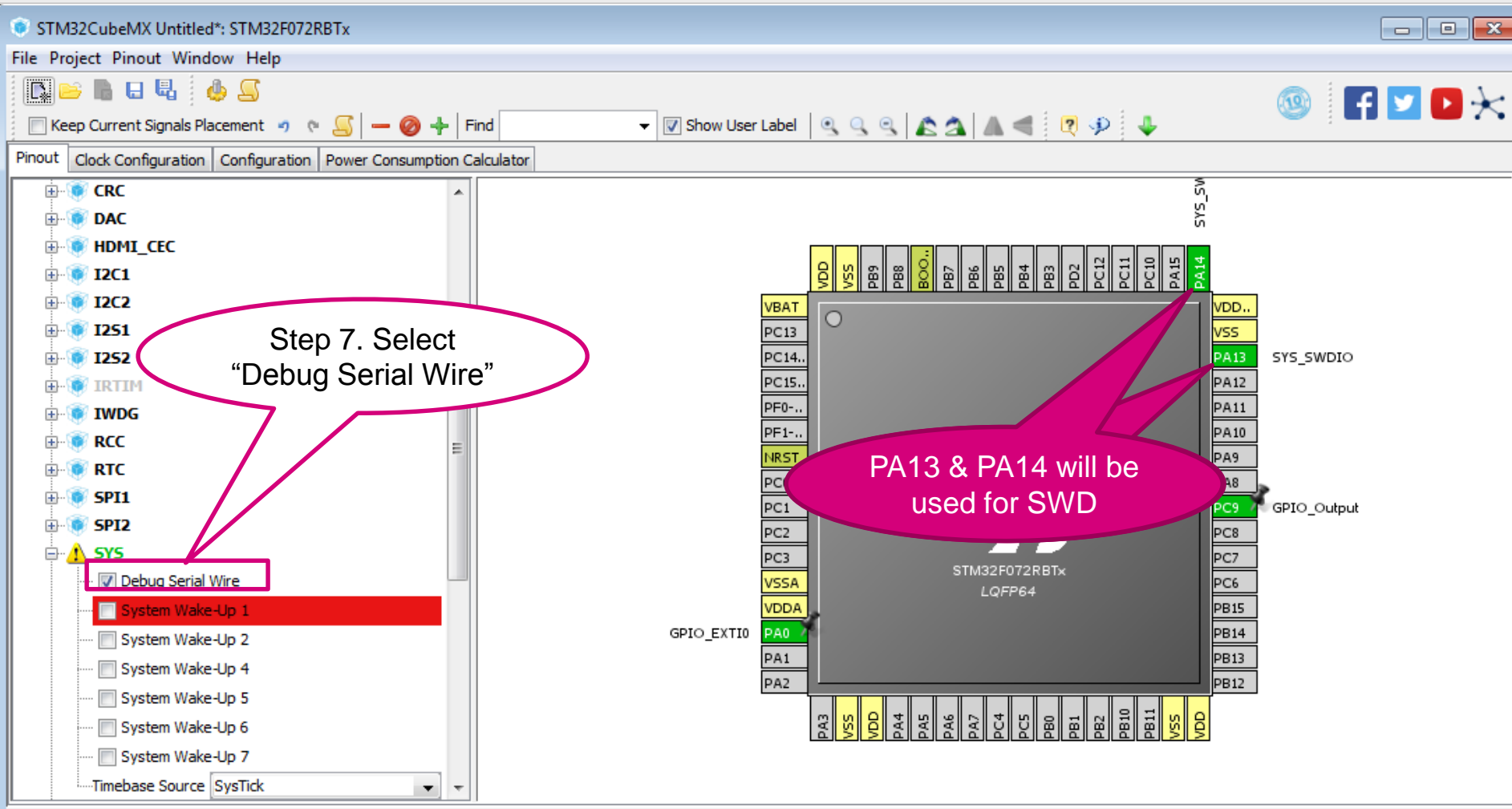


Screenshots

67

Step 5. Type
"pc9" in
Find column



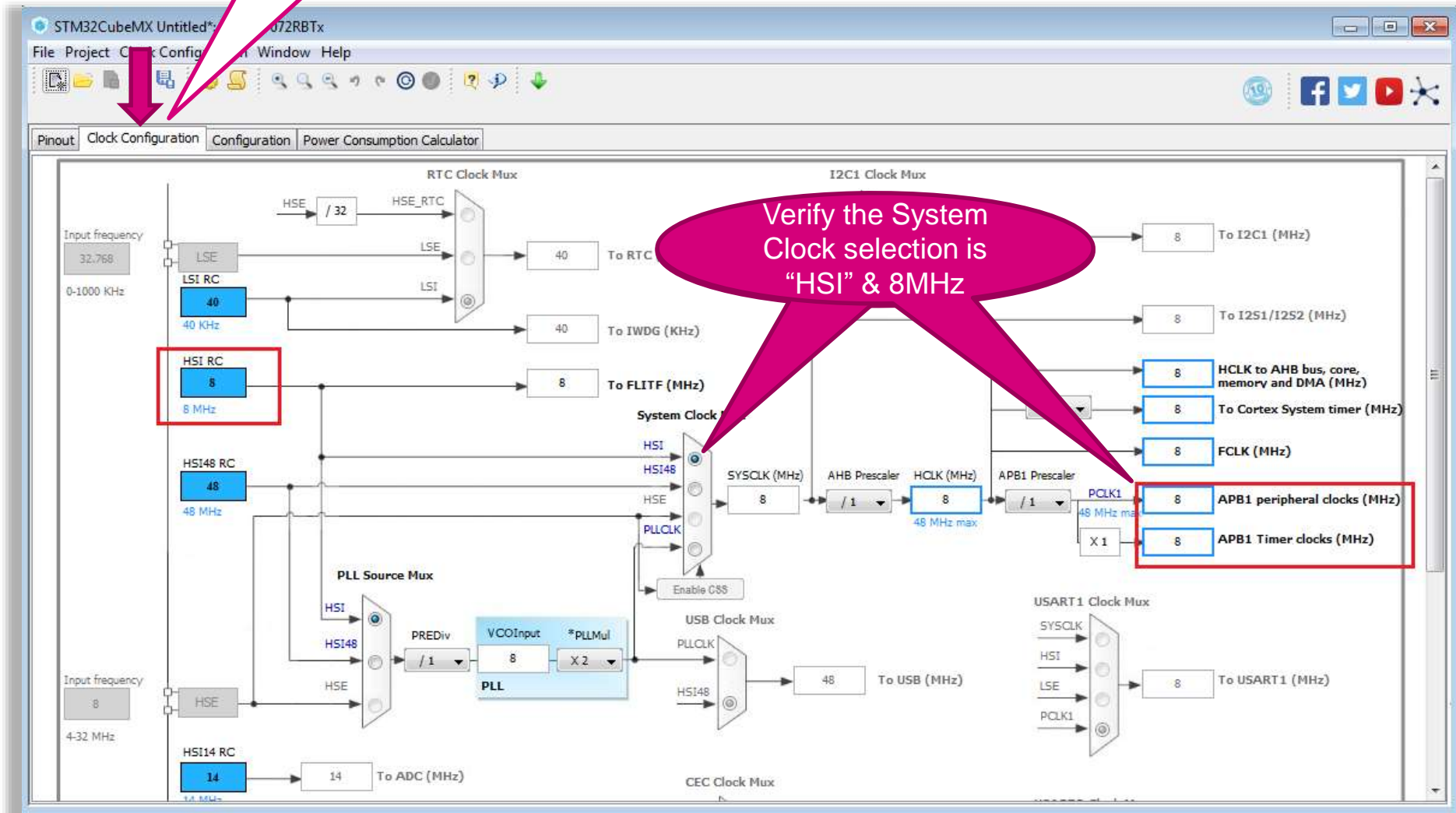


Lab-GPIO_EXTI: STM32CubeMX Config

69

- Clock Configuration Tab
 - System Clock using HSI (8MHz) as clock source:
 - HSI as SYSCLK clock source
 - SYSCLK = HCLK(AHB) = 8MHz
 - APB1(PCLK1) = 8MHz
 - APB2(PCLK2) = 8MHz

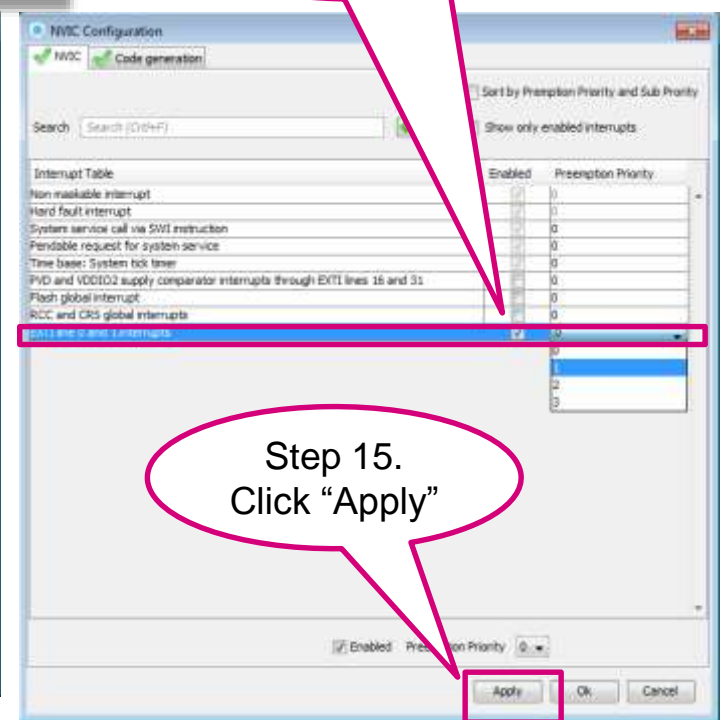
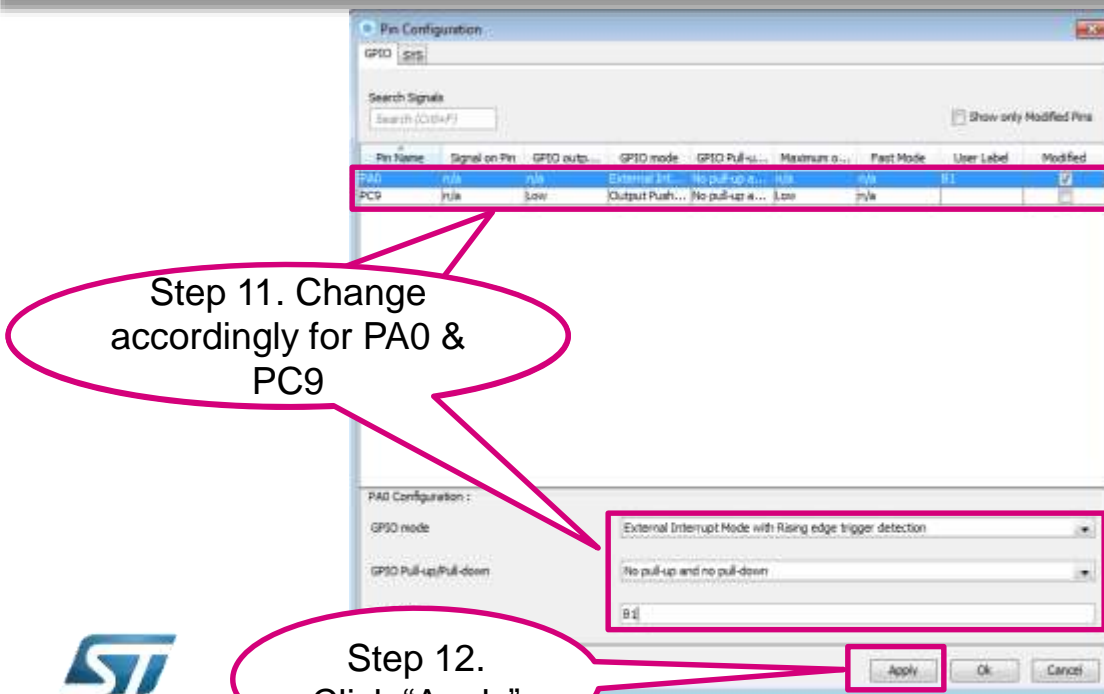
Step 8. Click on
"Clock Configuration"
tab



- STM32CubeMX configuration cont.:
 - Configuration Tab
 - GPIO
 - PC9 (Output Push Pull mode, no pull-up/down, Fast output speed, User Label: LD_R (green))
 - PA0 (External Interrupt mode with the correct edge detection, no pull-up/down, User Label: B1 User) . Refer to schematics for the correct edge trigger.
 - PA13 (Set as SWD pins. No further action. User Label: SWDIO)
 - PA14 (Set as SWD pins. No further action. User Label: SWCLK)
 - NVIC
 - Enable External Line 4 to Line 15 interrupt with Software priority (Preemption Priority) set to 1.
 - System tick timer - Care must be taken when using HAL_Delay(), this function provides accurate delay (in milliseconds) based on variable incremented in SysTick ISR. This implies that if HAL_Delay() is called from a peripheral ISR process, then the SysTick interrupt must have higher priority (numerically lower) than the peripheral interrupt. Otherwise the caller ISR process will be blocked.
 - RCC – no further changes needed for this particular discovery board and exercise

Screenshots

72



Lab GPIO_EXTI: STM32CubeMX Project Setting

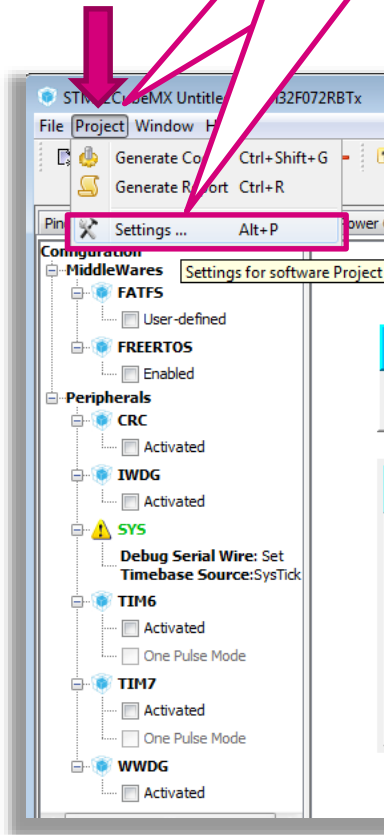
73

- **Code Generator tab**
 - STM32Cube Firmware Library Package
 - Select “Copy only the necessary library files”
 - Generated files
 - Select “Keep User Code when re-generating” & “Delete previously generated files when not re-generated”
- **Project tab**
 - Project name
 - Enter the project name and the subdirectory
 - Toolchain/IDE
 - Select “MDK-ARM V5” for Keil V5 compiler

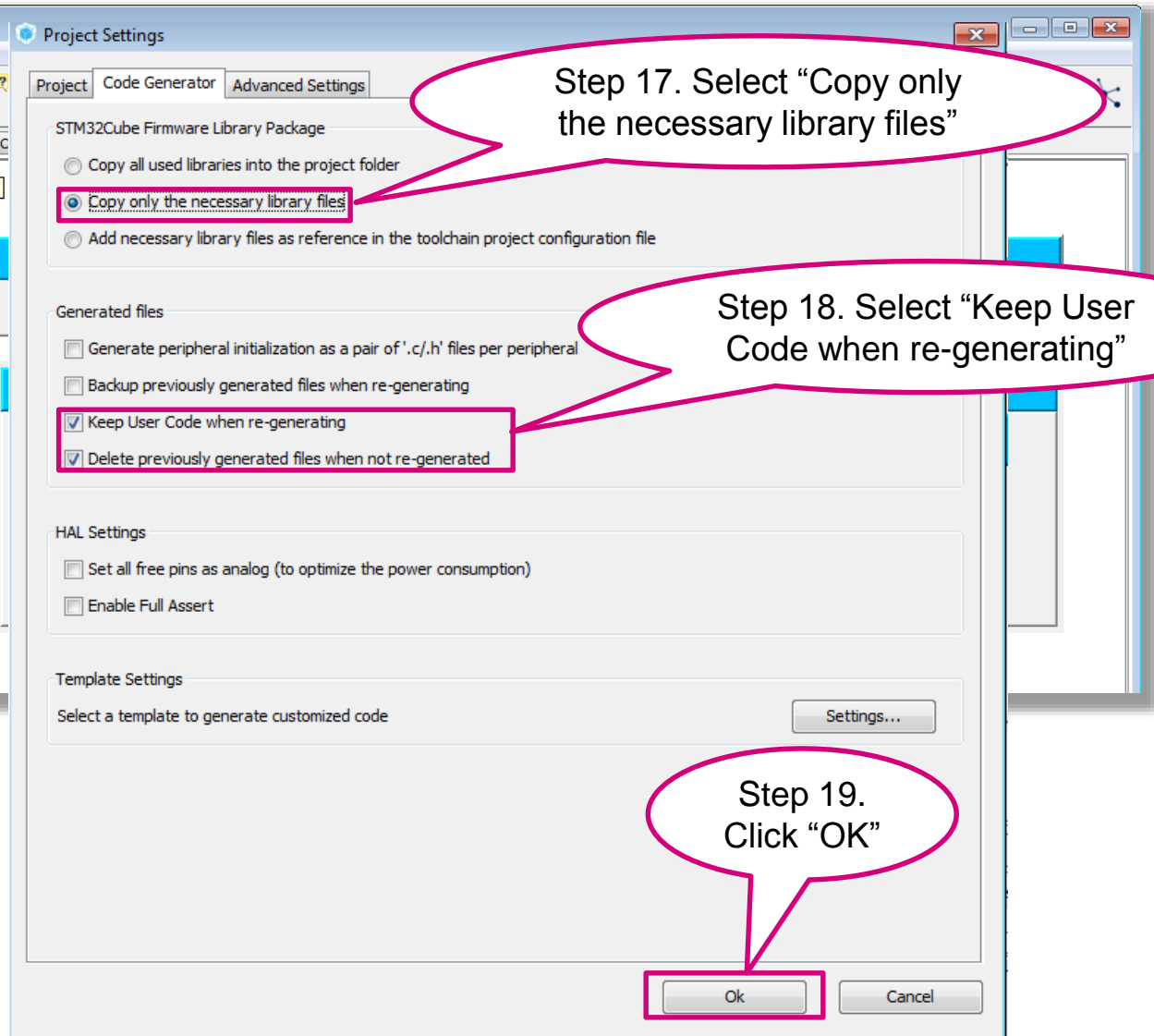
Screenshots

74

Step 16. Click
"Project" and
select "Setting"

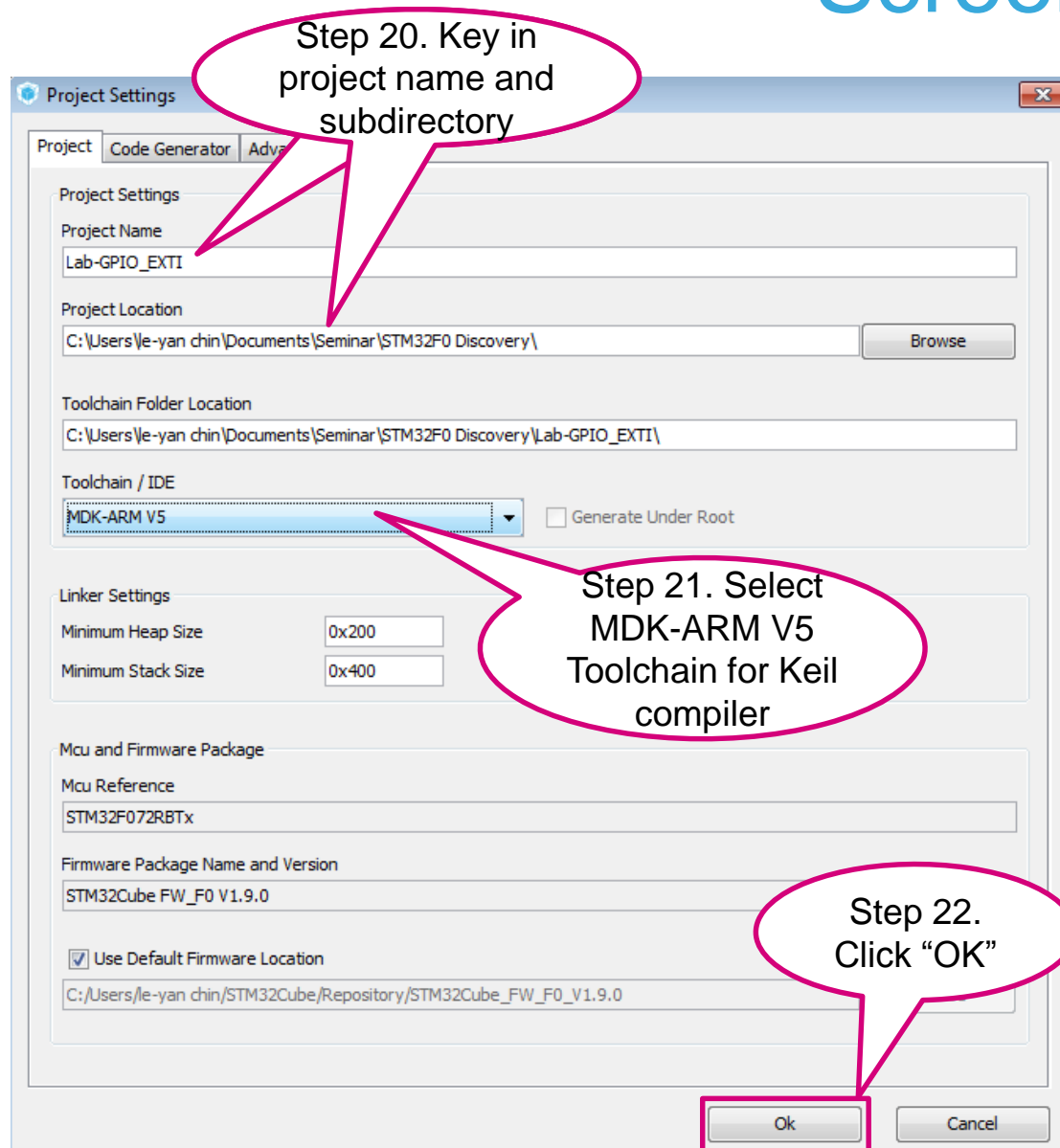


Step 17. Select "Copy only the necessary library files"



Step 18. Select "Keep User Code when re-generating"

Step 19.
Click "OK"



Lab GPIO_EXTI: STM32CubeMX Project Setting

76

- Save the project once all configuration are done.
- To complete, perform the following:
 - Generate Report (optional)
 - This will create a .pdf, .txt, and .jpg file
 - Generate Code
 - This will generate a project based on the Toolchain/IDE selected and all the necessary user and library files.
- Open the KEIL MDK-ARM 5 Project (Lab-GPIO_EXTI.uvprojx)
 - When the Code Generation is done, just click “Open Project”. Or you can manually open from the specified folder.
 - \.\STM32F0 Discovery Exercises\Lab-GPIO_EXTI\MDK-ARM
- Now you are ready to write some codes.

Lab GPIO_EXTI: Firmware Modification

77

- In KEIL environment, open main.c file.
 - Study the generated GPIO configuration. Verify if the configurations done by the STM32CubeMX tool are correct.
 - In Main.c file -> MX_GPIO_Init ()
 - In the STM32CubeMX Pinout configuration, you have only configured PA0(User PB), PC9(LD_R), PA13(SWDIO) and PA14(SWCLK). How come there are configurations for the other pins? What are these configurations for?
- main.c
 - The STM32CubeMX tool only generates the initialization code, further modifications of the user files (e.g. main.c, stm32F0xx_hal_msp.c, stm32l0xx_it.c) are needed to complete the implementation.
 - In the main.c file, you will find sections for user code. Copy the highlighted codes below to the corresponding **USER CODE** sections in the main.c file.
 - It is important the codes are copied within the **USER CODE** sections. This will allow you to regenerate another initialization code using STM32CubeMX tool without deleting the user codes.

Lab GPIO_EXTI: Firmware modification cont.

78

- For USER CODE BEGIN 0/USER CODE END 0

```
/* USER CODE BEGIN 0 */
```

```
uint8_t MODE_SELECTION;
```

```
/* USER CODE END 0 */
```

- For USER CODE BEGIN 3 / USER CODE END3

```
/* Infinite loop */
```

```
/* USER CODE BEGIN WHILE */
```

```
while (1)
```

```
{
```

```
/* USER CODE END WHILE */
```

```
/* USER CODE BEGIN 3 */
```

```
if(MODE_SELECTION==0){
```

```
/* Toggle LEDs - Use the HAL functions from stm32l0xx_hal_gpio.c file */
```

```
HAL_GPIO_TogglePin(GPIOC, GPIO_PIN_9); //LD_R (green) – PC9
```

```
HAL_Delay(100); //100ms
```

```
}
```

```
else if(MODE_SELECTION==1){
```

```
/* Turn OFF the LEDs */
```

```
/* - Use the HAL functions from stm32f0xx_hal_gpio.c file */
```

```
/* Hint: Highlight + right click on the function and use “Go to definition...” */
```

```
HAL_GPIO_WritePin(GPIOC, GPIO_PIN_9, GPIO_PIN_RESET); //Turn off LD_R(green)
```

```
HAL_Delay(100); //100ms
```

```
}
```

Lab GPIO_EXTI : Firmware modification

cont.

79

- Cont. For USER CODE BEGIN 3 / USER CODE END3

```
else if(MODE_SELECTION==2){
    /* Turn ON the LED */
    /* - Use the HAL functions from stm32f0xx_hal_gpio.c file */
    /* Hint: Highlight + right click on the function and use "Go to definition..." */
    HAL_GPIO_WritePin(GPIOC, GPIO_PIN_9, GPIO_PIN_SET);          //LD_R (green) – PC9

    /* Delay - Use the HAL delay function from stm32l0xx_hal.c file */
    HAL_Delay(1000);          //1secs
}
}
/* USER CODE END 3 */
```

Lab GPIO_EXTI : Firmware modification cont.

80

- For USER CODE BEGIN 4/ USER CODE END 4

```
/* USER CODE BEGIN 4 */
```

```
/**
```

```
 * @brief EXTI line detection callback. The function will be call by EXTI0_IRQHandler in “stm32f0xx_it.c” .
```

```
 * @param GPIO_Pin: Specifies the pins connected EXTI line
```

```
 * @retval None
```

```
 */
```

```
void HAL_GPIO_EXTI_Callback(uint16_t GPIO_Pin)
```

```
{
```

```
  if(GPIO_Pin == GPIO_PIN_0)
```

```
  {
```

```
    MODE_SELECTION++;
```

```
    if(MODE_SELECTION > 2) MODE_SELECTION=0;
```

```
    /* Debounce - wait until the button is released . Read the GPIO to get the state. Refer to the schematics. */
```

```
    /* - Use the HAL functions from stm32l0xx_hal_gpio.c file */
```

```
    /* Hint: Highlight + right click on the function and use “Go to definition...” */
```

```
    while(HAL_GPIO_ReadPin(GPIOA, GPIO_PIN_0) != GPIO_PIN_RESET);    //Blue pushbutton – PA0
```

```
  }
```

```
}
```

```
/* USER CODE END 4 */
```

Lab GPIO_EXTI: Verification

81

- Build, then Download and Debug
- Run the code
- Expected behavior:
 - When User button is pressed an interrupt is triggered and will call the EXTI IRQ handler in `stm32l0xx_it.c` file. The IRQ handler will then call the `HAL_GPIO_EXTI_Callback()` function in `main.c` file where the global variable (`MODE_SELECTION`) will be incremented.
 - `MODE_SELECTION == 0` (Default), Green LED will toggle
 - `MODE_SELECTION == 1`, Green LED will turn off.
 - `MODE_SELECTION == 2`, Green LED will turn on.

Lab GPIO_EXTI: Discussion (Interrupts)

82

- Flow of interrupt

- Pushbutton event occurs
- EXTI detects valid edge
- EXTI generates interrupt request
- If the interrupt channel is enabled, the NVIC will acknowledge the interrupt request and checks the priority
- When priority is higher, NVIC fetches EXTI Line interrupt vector.
- (Otherwise the interrupt will be set as pending until its priority becomes the highest compared to other pending interrupts)
- Core executes EXTI IRQ Handler. Note that the handler will eventually call a callback function where the user will have to add and write the corresponding service routine.

In main.c

```
Main()
{
    ...
    while(1)
    {
        ...
        ...
        ...
    }
}
```

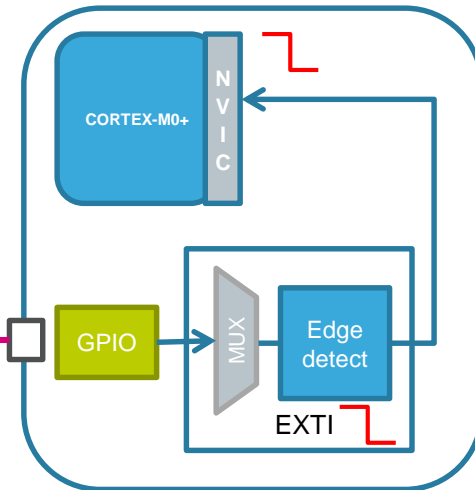
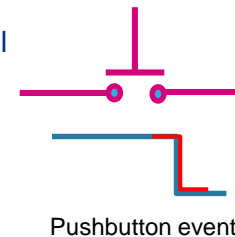
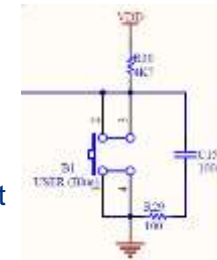
Interrupt trigger

In stm32f10x_it.c

```
void EXTI0_1_IRQHandler(void)
{
    HAL_GPIO_EXTI_IRQHandler(GPIO_PIN_0);
}
```

In main.c

```
HAL_GPIO_EXTI_Callback(uint16_t GPIO_Pin)
{
    ... User Code to manage the interrupt
    ...
}
```



In stm32f0xx_hal_gpio.c

```
void HAL_GPIO_EXTI_IRQHandler(uint16_t GPIO_Pin)
{
    /* EXTI line interrupt detected */
    if(__HAL_GPIO_EXTI_GET_IT(GPIO_Pin) != RESET)
    {
        __HAL_GPIO_EXTI_CLEAR_IT(GPIO_Pin);
        HAL_GPIO_EXTI_Callback(GPIO_Pin);
    }
}
```

This flow of xxx_IRQHandler calls and xxx_Callback calls is similarly implemented for the other peripherals when interrupt request is enabled.



Demo 1: Running Sample code on the STM32F072 Discovery Board

Hands-on sample code: RTC Alarm

84

- **Objective:**

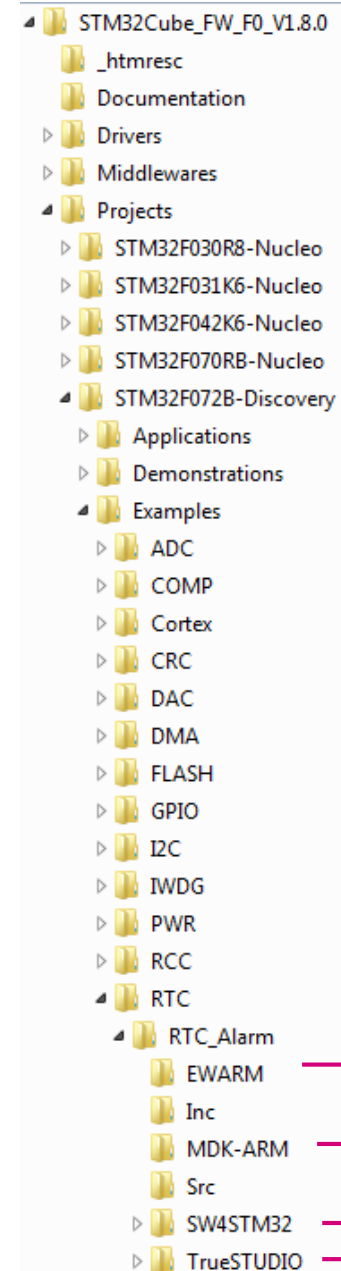
- Understand where to look for example codes in STM32Cube
- Run “RTC_Alarm” example code on STM32F072 Discovery board which trigger turning on LED LD5 when the clock reaches the alarm setting

- **Description:**

- LED LD5 is connected to PC9 and and RTC is set to 00:20:00 at initial
- Alarm will be generated after 30 seconds on 02:20:30 and turns on LED LD5

- **Procedure:**

- Use window explorer to locate \STM32Cube\Repository subdirectory
 - eg> c:\users\le-yan chin\STM32Cube\Repository
- Check for the package F0 firmware
 - eg> STM32Cube_FW_F0_V1.8.0
- Copy the whole directory content to other place to retain the original firmware package
- Go to respective \Project subdirectory you copied and click into \STM32F072-Discovery subdirectory
 - eg>
C:\Users\..\STM32Cube_FW_F0_V1.8.0\Projects\STM32F072B-Discovery
- Select “RTC_Alarm” for Keil toolchain in \..\Examples\RTC\RTC_Alarm\MDK-ARM subdirectory
 - eg>
C:\Users\..\Projects\STM32F072B-Discovery\Examples\RTC\RTC_Alarm\MDK-ARM



For IAR

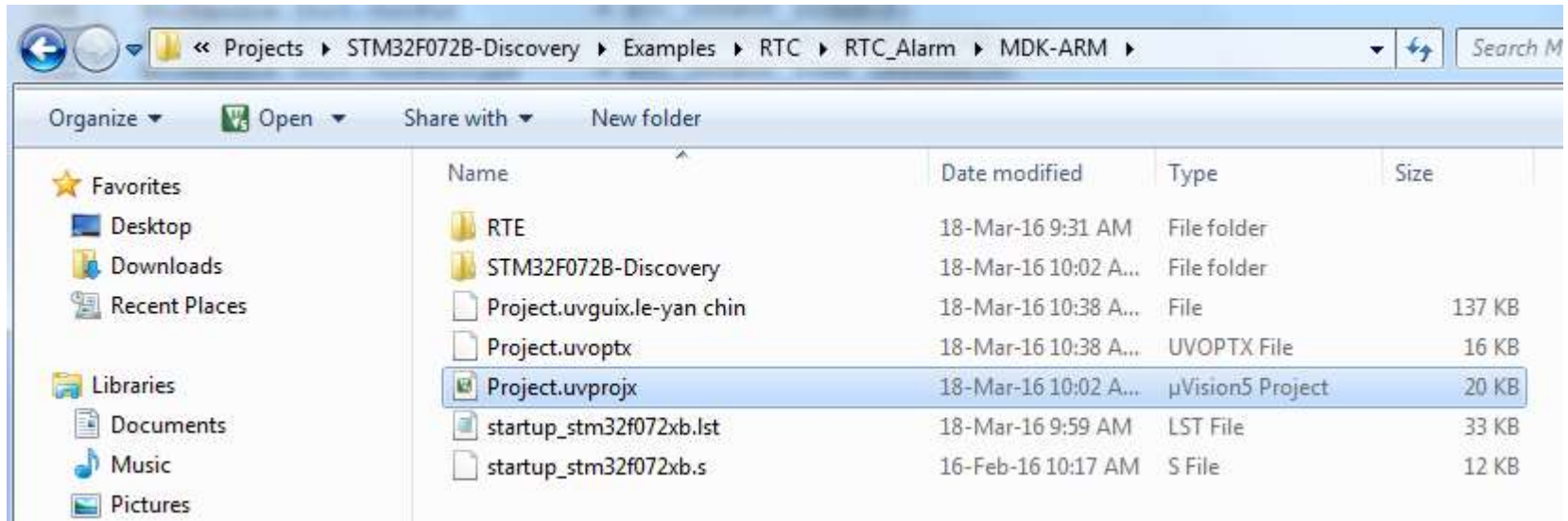
For Keil

For AC6
For Atollic

Hands-on sample code: RTC Alarm (cont'1)

85

- Procedure:
 - Click to run the “Project.uvprojx” for Keil toolchain platform

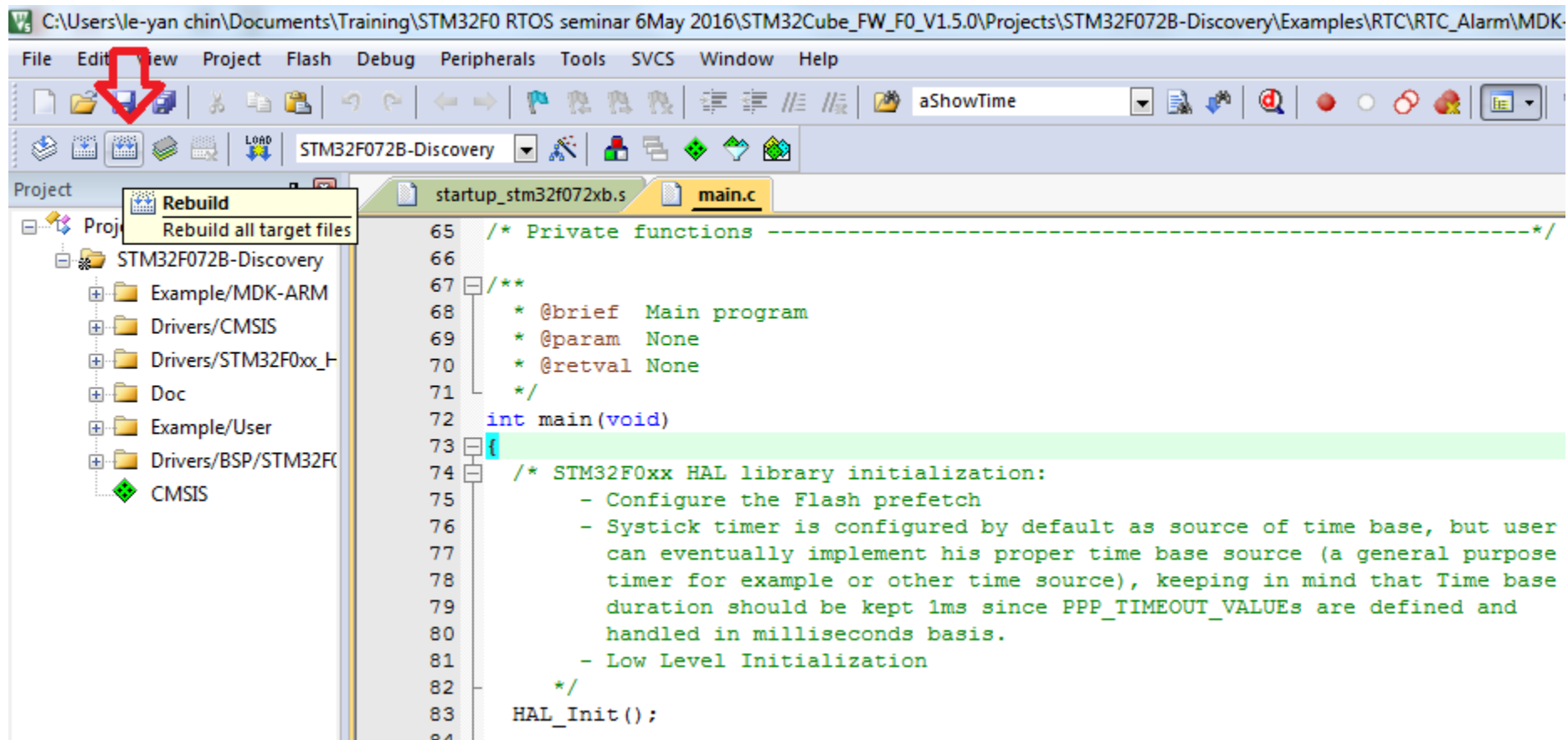


Hands-on sample code: RTC Alarm (cont'2)

86

- Procedure:

- In Keil IDE, click the “Rebuild” () icon to rebuild all the target files in the project

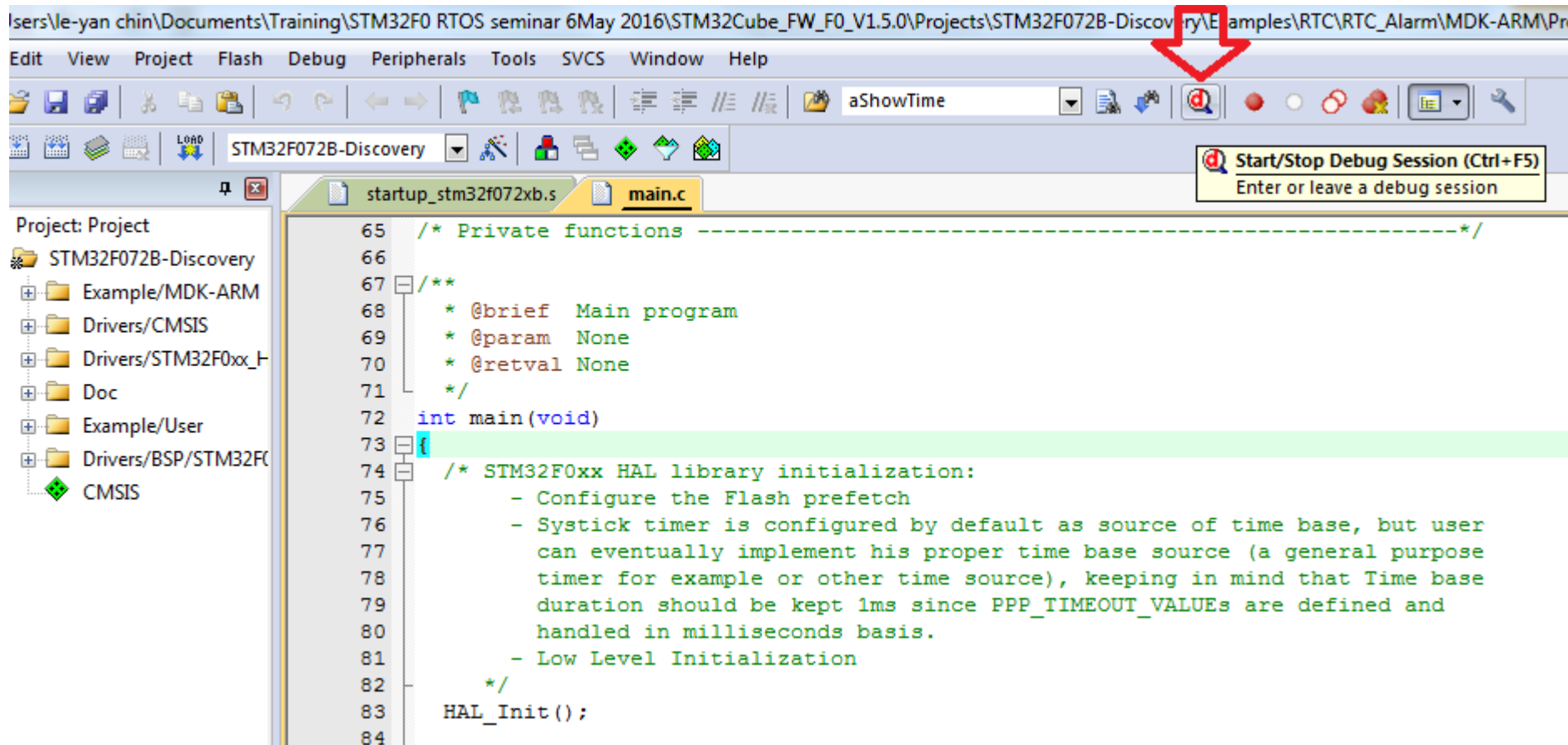


Hands-on sample code: RTC Alarm (cont'3)

87

- Procedure:

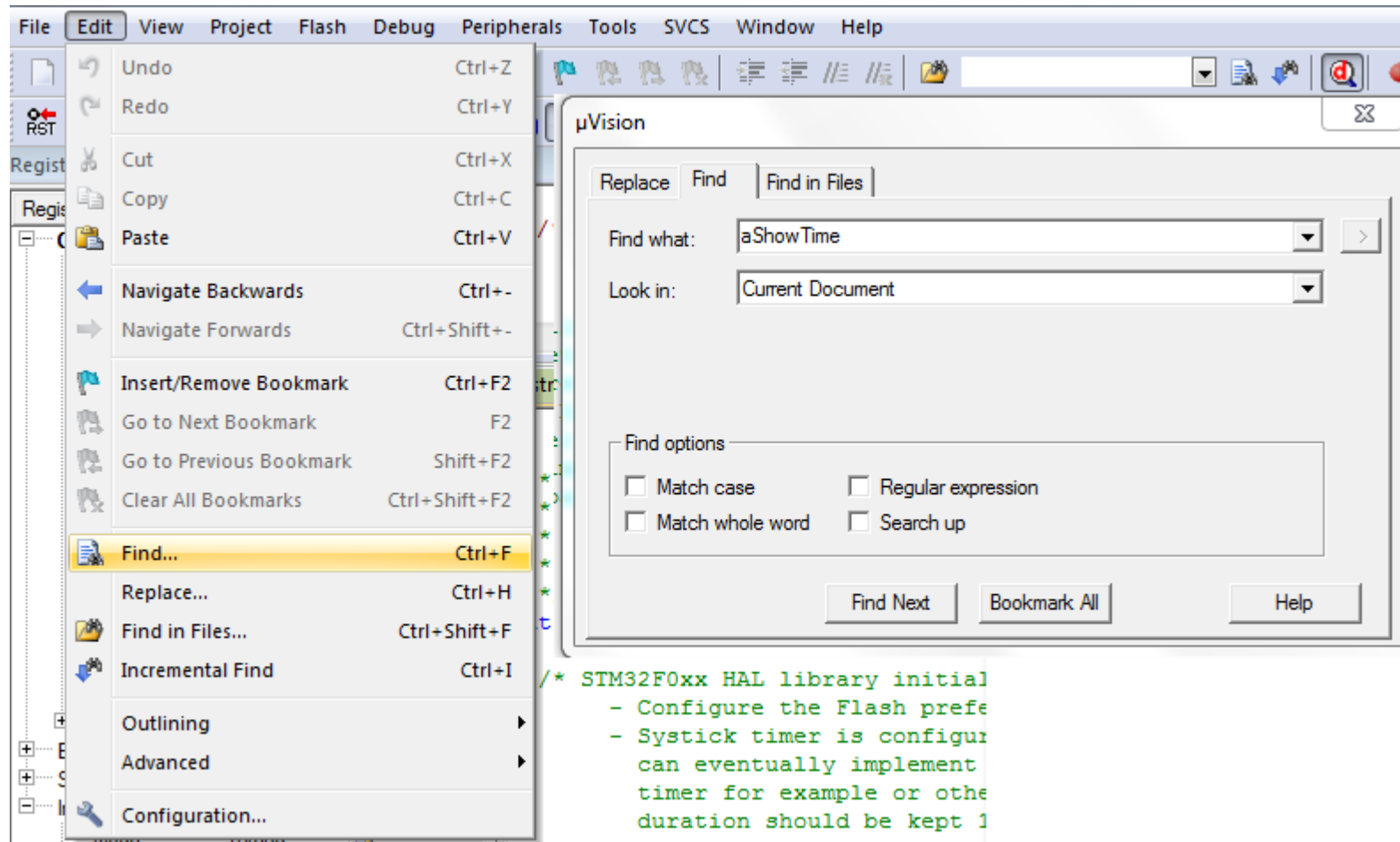
- When build finish without error, click the “Start/Stop Debug” () icon to go into debug mode



Hands-on sample code: RTC Alarm (cont'4)

88

- Procedure:
 - In Debug mode use the “Find” command to locate “aShowTime” variable

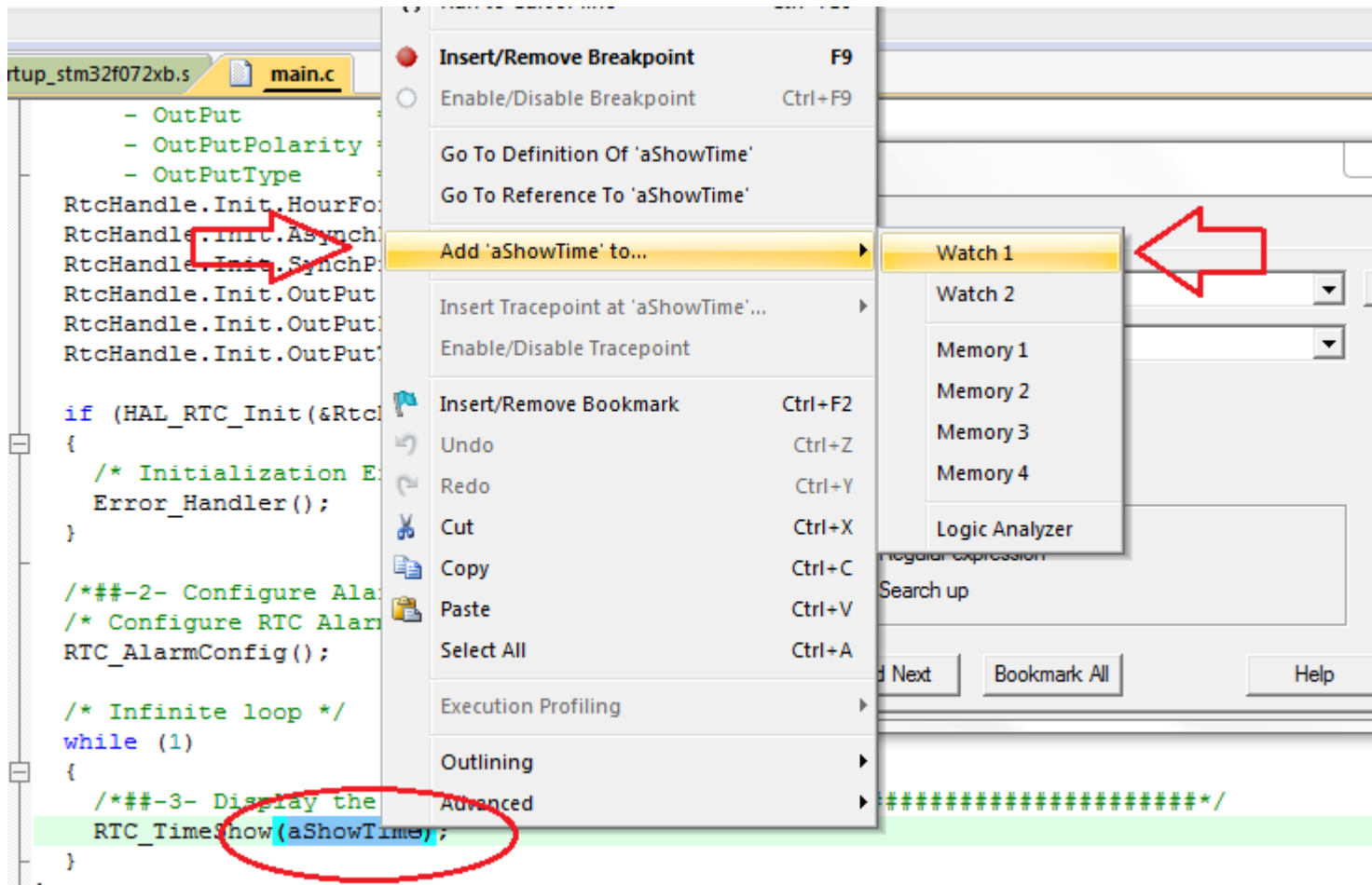


Hands-on sample code: RTC Alarm (cont'5)

89

- Procedure:

- Move the cursor pointer to the variable “aShowTime”, right click the mouse and select {Add “aShowTime” } to “Watch 1”

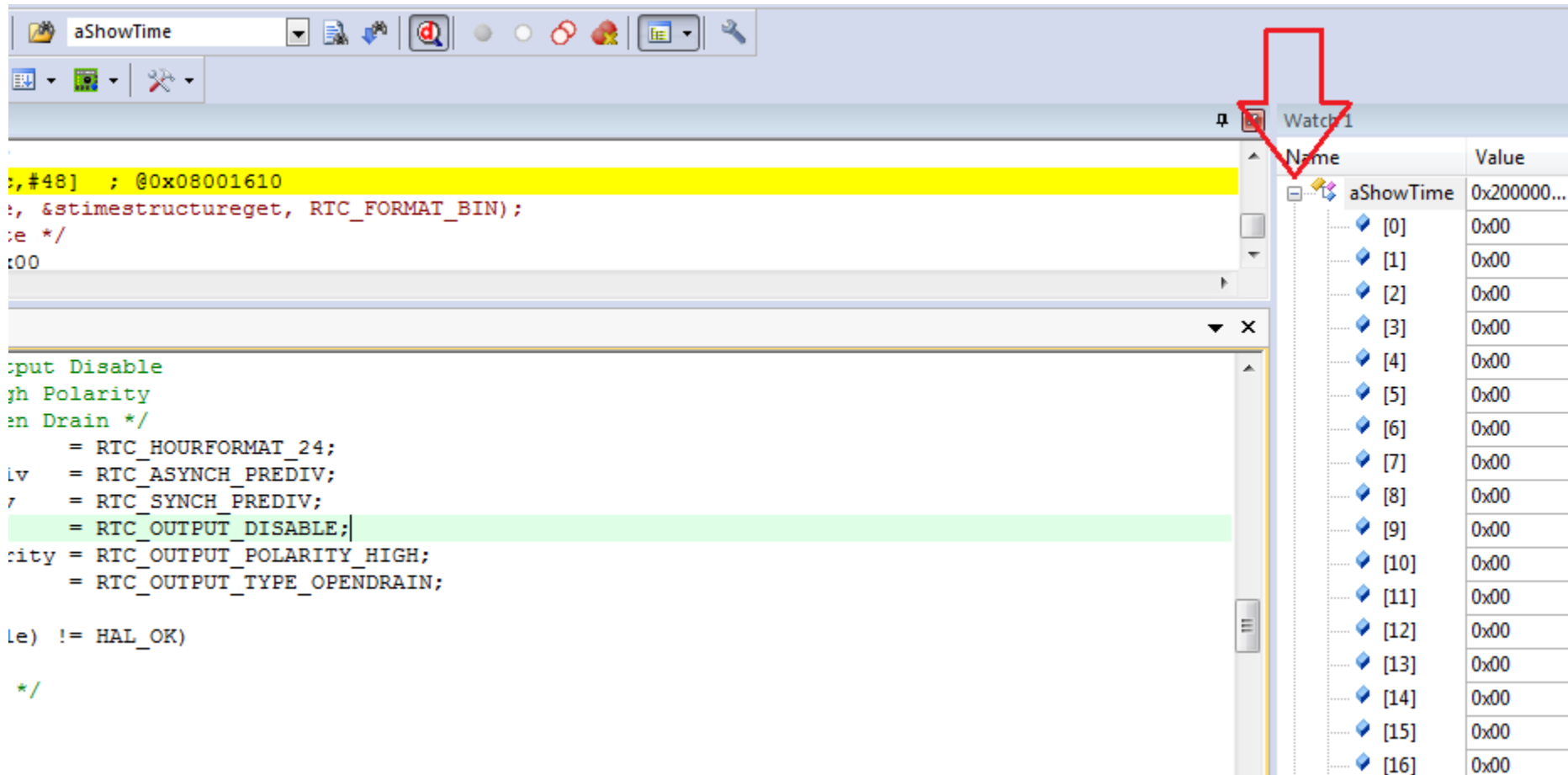


Hands-on sample code: RTC Alarm (cont'6)

90

- Procedure:

- Expand the variable “aShowTime” in the Watch 1 to see detail value



The screenshot shows an IDE with a C code file named 'aShowTime'. The code is partially highlighted in yellow and green. The Watch window on the right shows the variable 'aShowTime' expanded into an array of 17 elements, all with a value of '0x00'. A red arrow points to the 'aShowTime' variable in the Watch window.

```
/*, #48] ; @0x08001610
*, &stimestructureget, RTC_FORMAT_BIN);
/*e */
/*00

/*put Disable
/*h Polarity
/*n Drain */
/* = RTC_HOURFORMAT_24;
/*v = RTC_ASYNC_PREDIV;
/* = RTC_SYNC_PREDIV;
/* = RTC_OUTPUT_DISABLE;
/*ity = RTC_OUTPUT_POLARITY_HIGH;
/* = RTC_OUTPUT_TYPE_OPENDRAIN;

/*le) != HAL_OK)

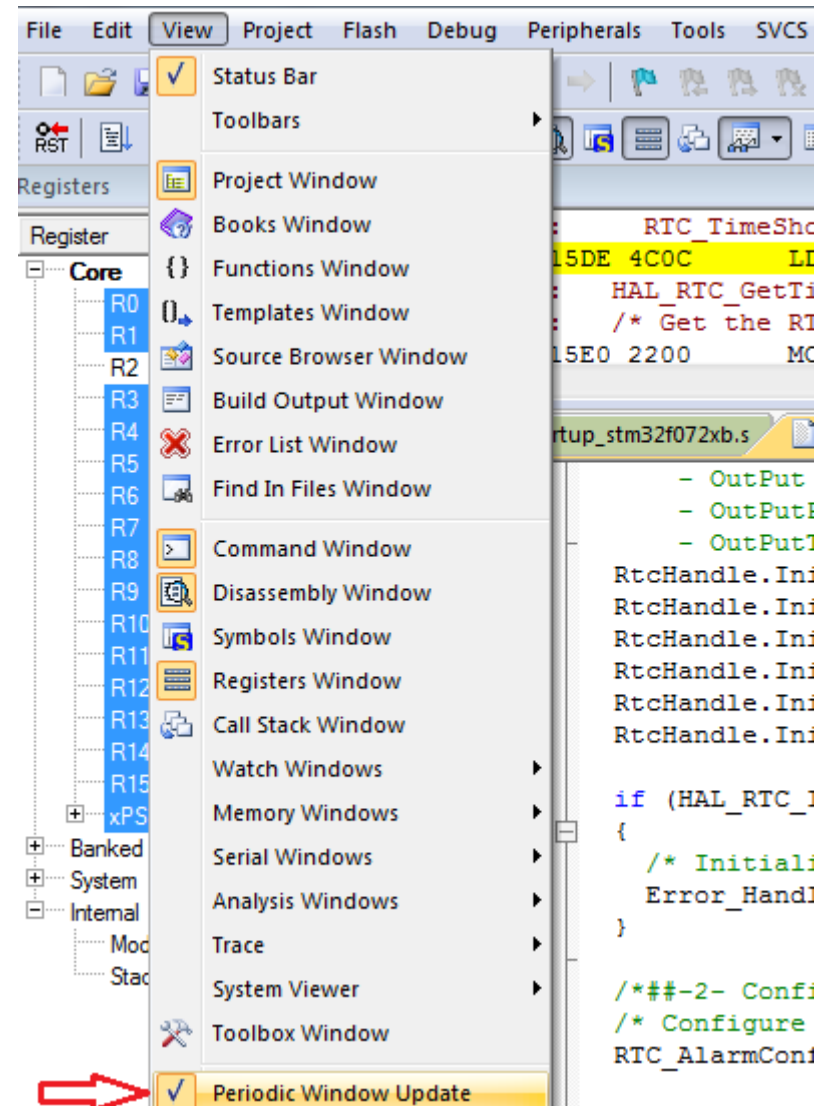
/*
```

Name	Value
aShowTime	0x200000...
[0]	0x00
[1]	0x00
[2]	0x00
[3]	0x00
[4]	0x00
[5]	0x00
[6]	0x00
[7]	0x00
[8]	0x00
[9]	0x00
[10]	0x00
[11]	0x00
[12]	0x00
[13]	0x00
[14]	0x00
[15]	0x00
[16]	0x00

Hands-on sample code: RTC Alarm (cont'7)

91

- Procedure:
 - Click on “View” menu and check the “Periodic Window Update”

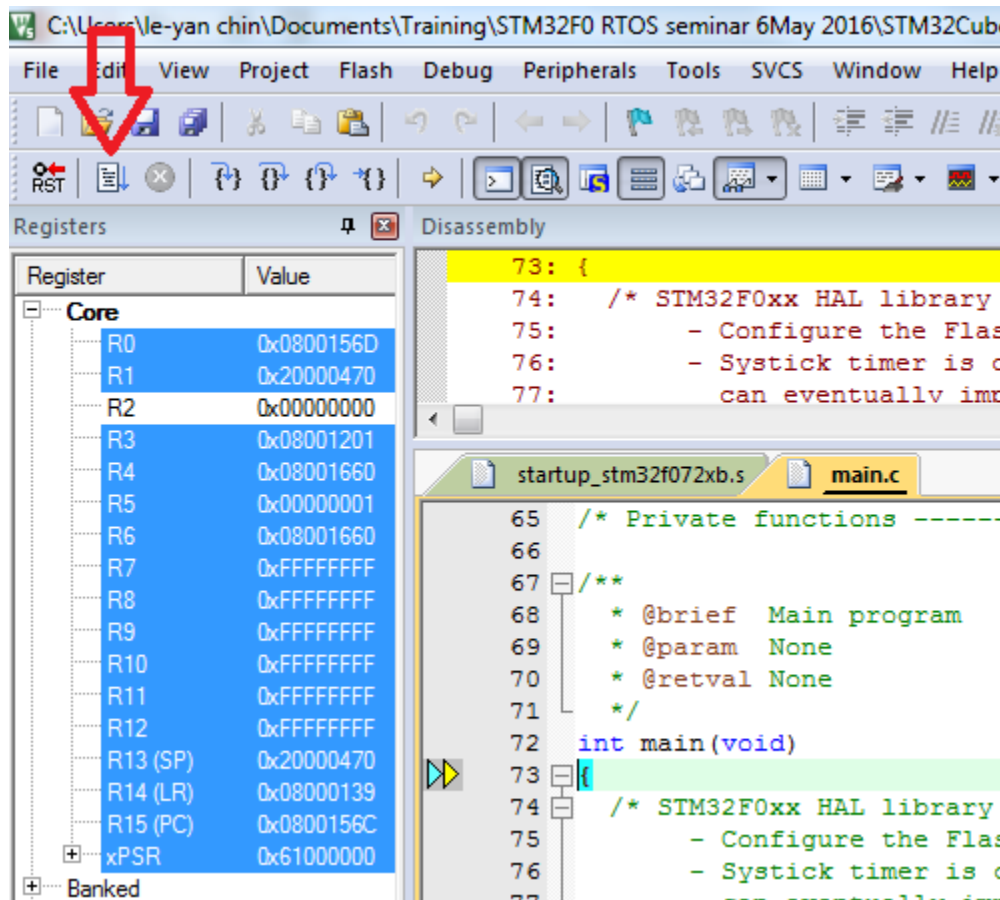


Hands-on sample code: RTC Alarm (cont'8)

92

- Procedure:

- Click the “Run” () icon to run the project, observe the eShowTime variable change in Watch 1 window



Watch 1		
Name	Value	Type
aShowTime	0x200000...	unsigned...
[0]	0x30 '0'	unsigned...
[1]	0x32 '2'	unsigned...
[2]	0x3A ':'	unsigned...
[3]	0x32 '2'	unsigned...
[4]	0x30 '0'	unsigned...
[5]	0x3A ':'	unsigned...
[6]	0x30 '0'	unsigned...
[7]	0x34 '4'	unsigned...
[8]	0x00	unsigned...
[9]	0x00	unsigned...
[10]	0x00	unsigned...
[11]	0x00	unsigned...
[12]	0x00	unsigned...
[13]	0x00	unsigned...
[14]	0x00	unsigned...
[15]	0x00	unsigned...
[16]	0x00	unsigned...
[17]	0x00	unsigned...

Hands-on sample code: RTC Alarm (cont'9)

93

- Procedure:
 - a) Try to modify the code only to turn on the LED LD5 when eShowTime is 02:20:20
 - Hint : look for “salarmstructure.AlarmTime.Seconds”
 - b) Try to change the start up time from 12:00:00
 - Hint : look for “stimestructure”



Demo 2: Running the Demonstration project on the STM32F072 Discovery Board

Hands-on sample code: Demonstrations

95

- **Objective:**

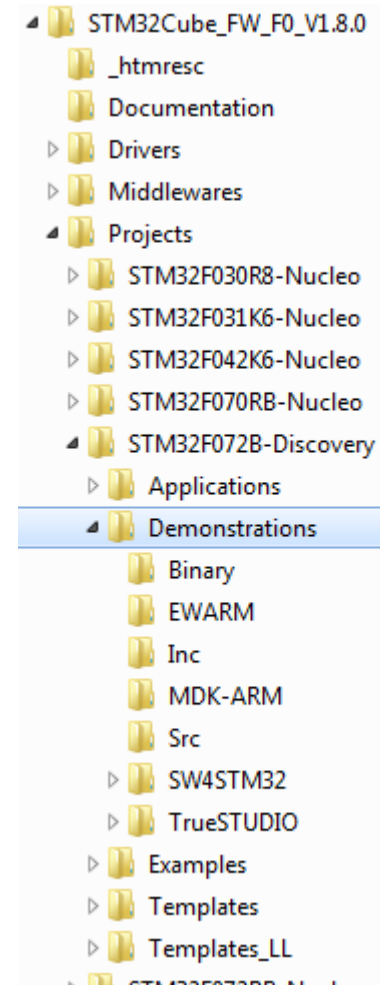
- Understand where to look for example codes in STM32Cube
- Run “Demonstrations” example code of STM32F072 on Discovery board to test the touchsense button, USB HID interface and Gyro sensor.

- **Description:**

- LED LD5 is connected to PC9 and 4 touchsense buttons are connected to TS_G1_IO3, TS_G1_IO4, TS_G2_IO3, TS_G2_IO4, TS_G3_IO2, TS_G3_IO3
- Using User button to select different application options in the project such as Sliding position, HID, Gyro movement.

- **Procedure:**

- Use window explorer to locate \STM32Cube\Repository subdirectory
 - eg> c:\users\le-yan chin\STM32Cube\Repository
- Check for the package F0 firmware
 - eg> STM32Cube_FW_F0_V1.8.0
- Copy the whole directory content to other place to retain the original firmware package
- Go to respective \Project subdirectory you copied and click into \STM32F072-Discovery subdirectory
 - eg>
C:\Users\...\STM32Cube_FW_F0_V1.8.0\Projects\STM32F072B-Discovery
- Select “Demonstrations” subdirectory in \STM32F072-Discovery subdirectory
 - eg>
C:\Users\...\STM32Cube_FW_F0_V1.8.0\Projects\STM32F072B-Discovery\Demonstrations



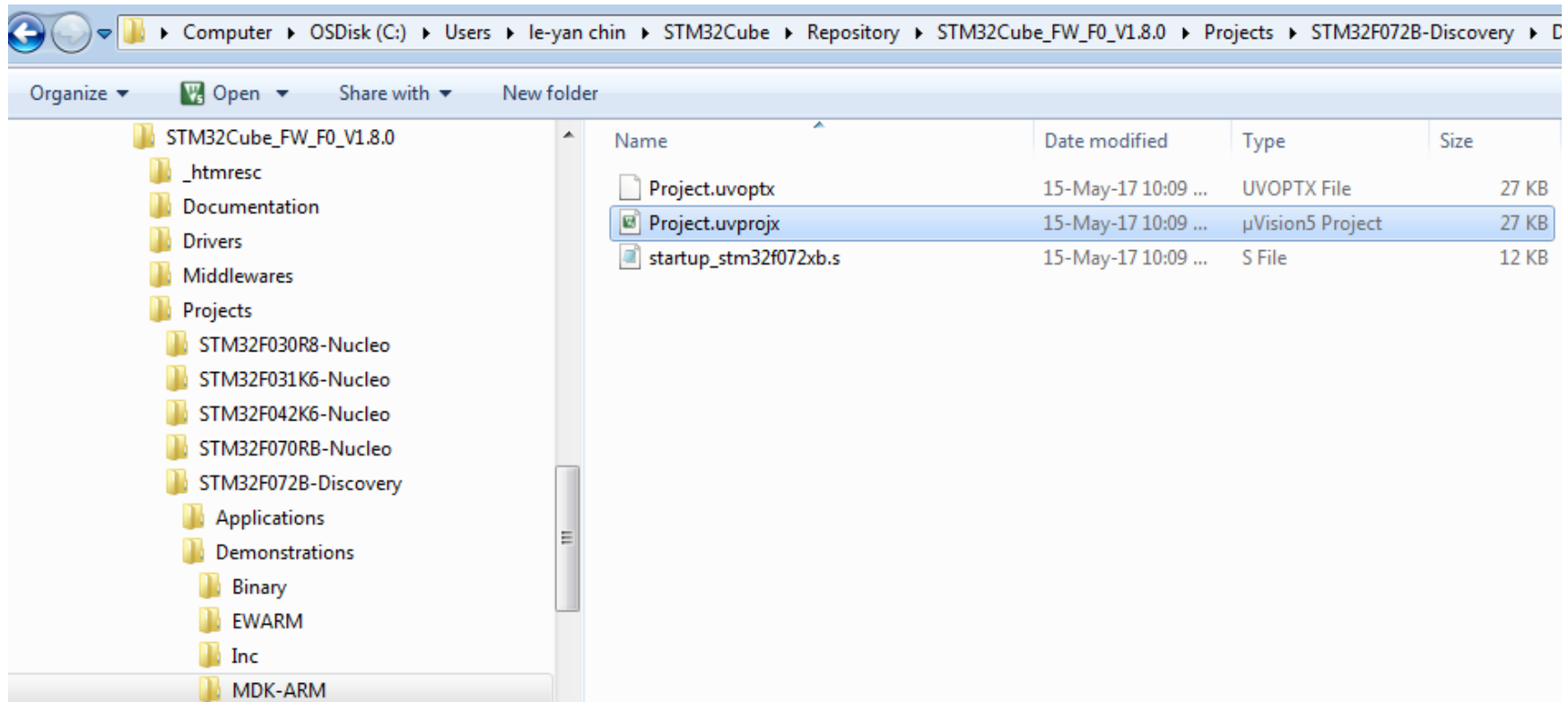
Hands-on sample code: Demonstrations (cont'1)

96

- Procedure:

- Select project file “Project.uvprojx” to run on Keil toolchain

eg> C:\Users\...\STM32Cube_FW_F0_V1.8.0\Projects\STM32F072B-Discovery\Demonstrations\MDK-ARM\project.uvprojx

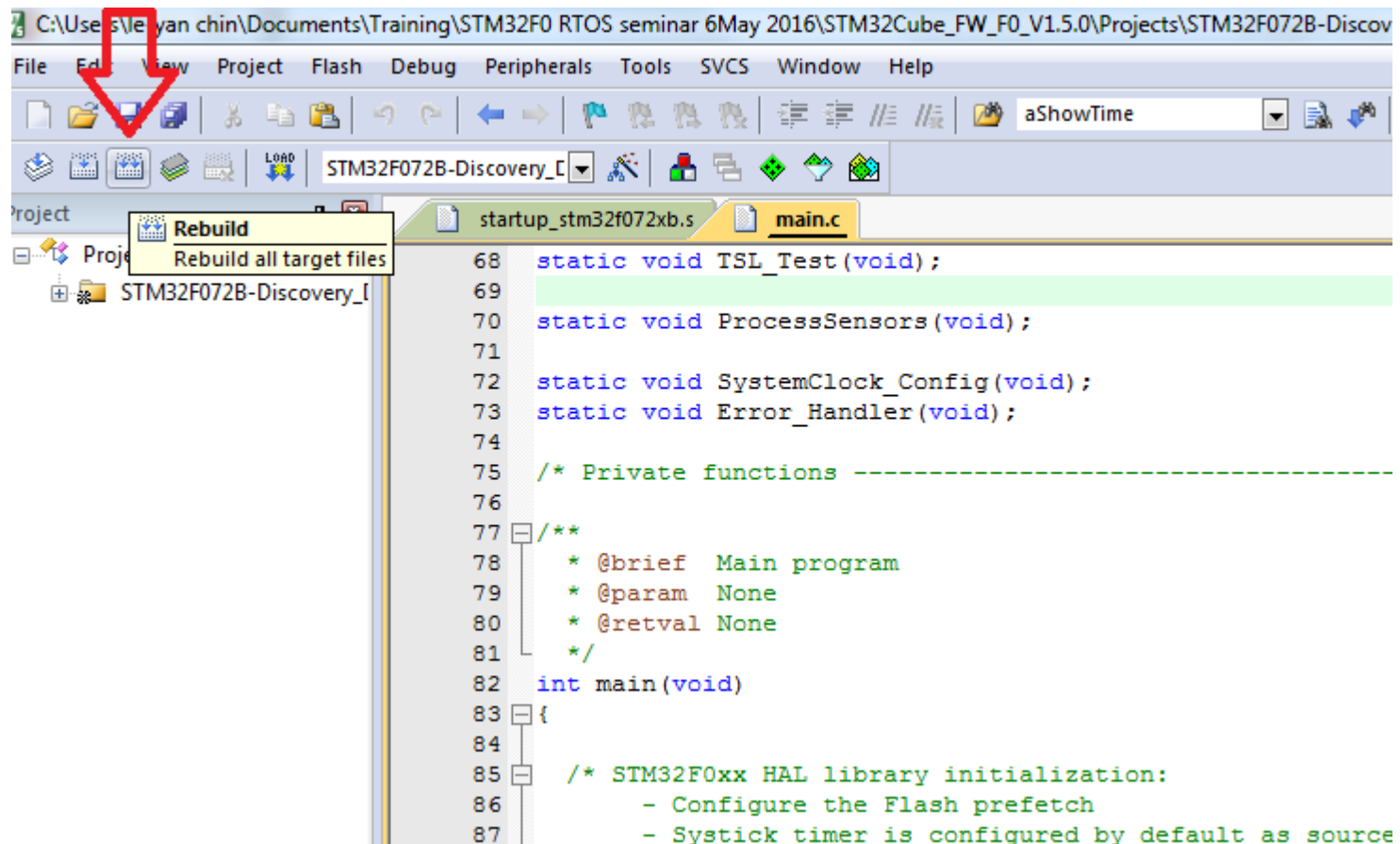


Hands-on sample code: Demonstrations (cont'2)

97

- Procedure:

- In Keil IDE, click the “Rebuild” () icon to rebuild all the target files in the project.

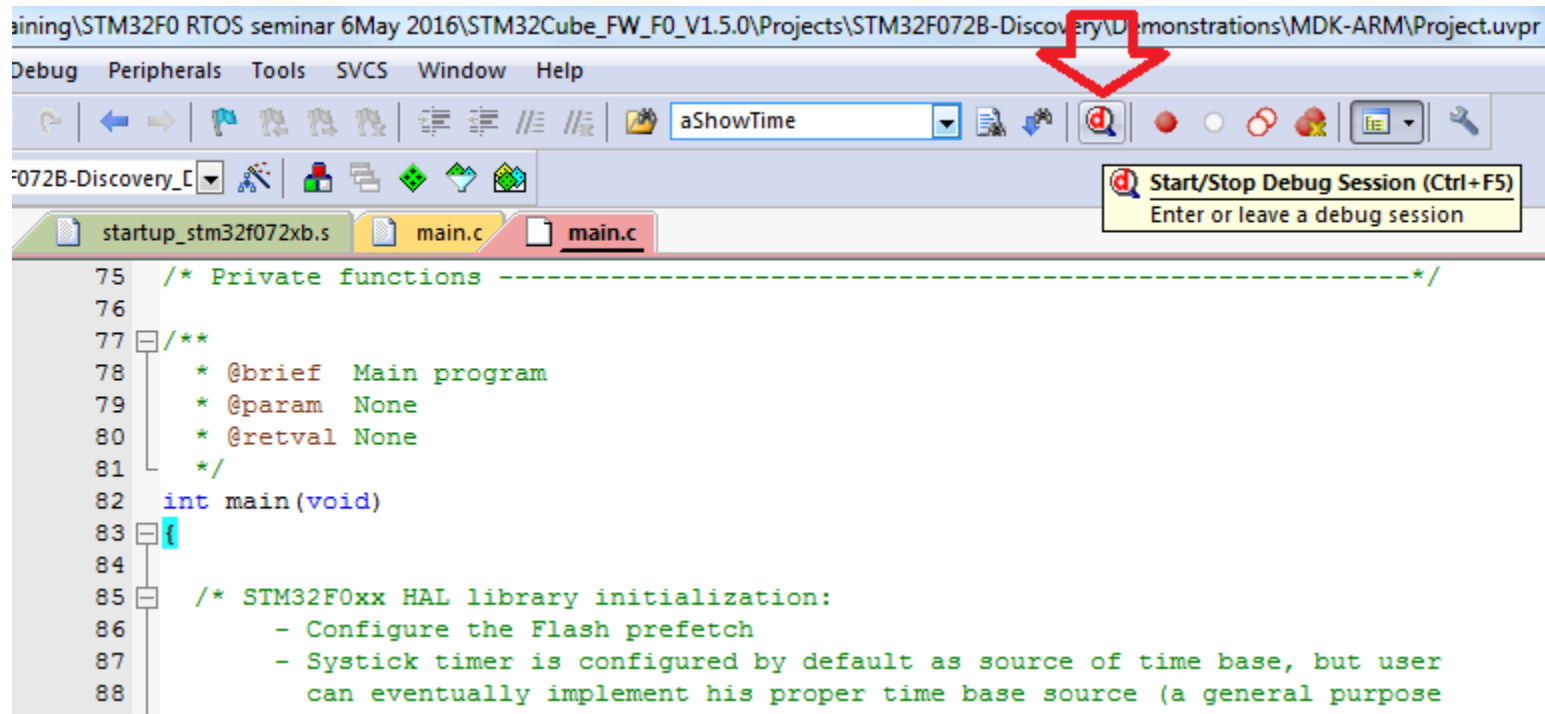


Hands-on sample code: Demonstrations (cont'3)

98

- Procedure:

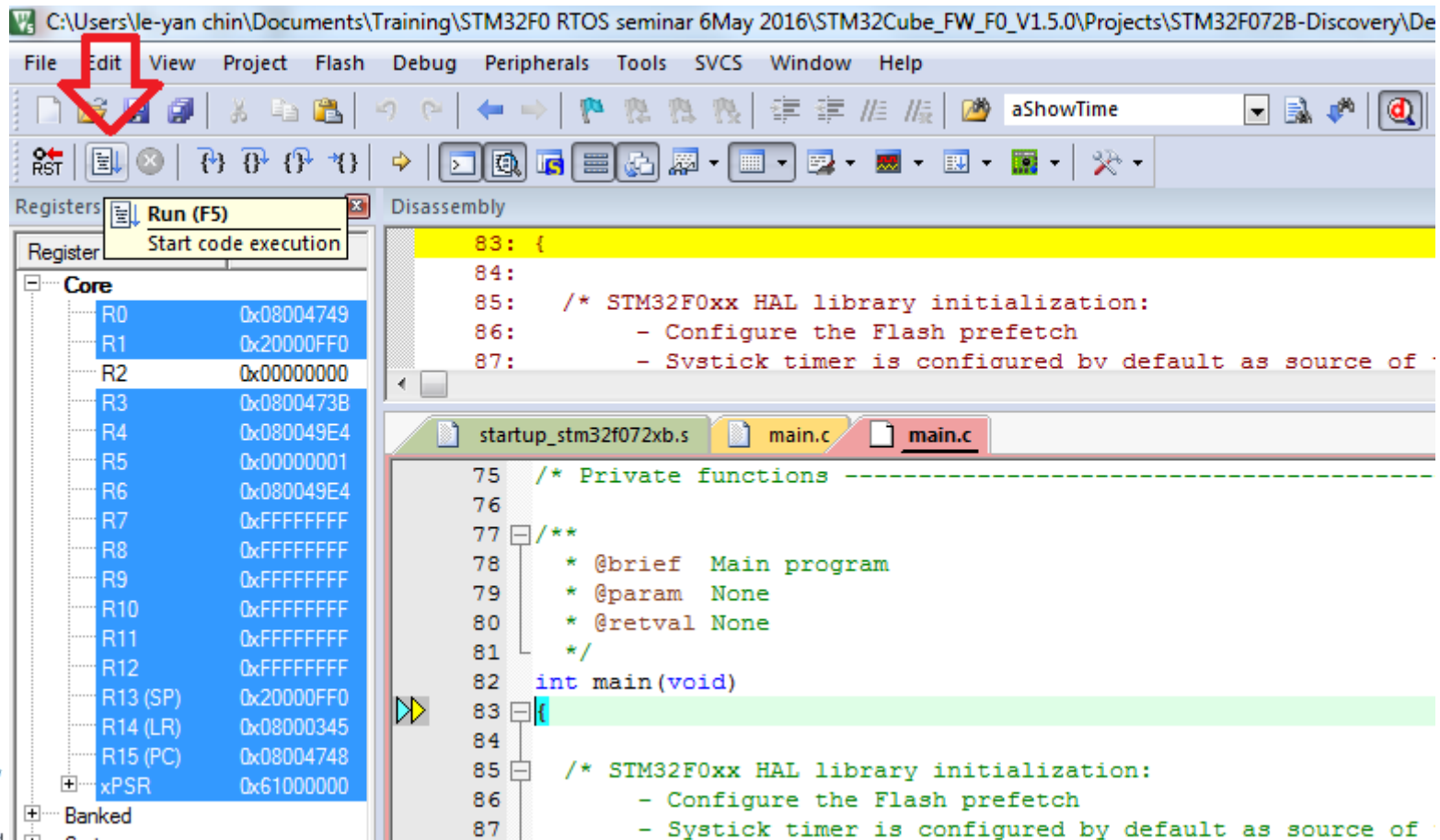
- When build finish without error, click the “Start/Stop Debug” () icon to go into debug mode



Hands-on sample code: Demonstrations (cont'4)

99

- Procedure:
 - Click the “Run” () icon to run the project.



Hands-on sample code: Demonstrations (cont'5)

100

- Procedure:

- Press User button B1 1st time
- Change the Discovery board level position to see the LEDs on change.
 - eg LED LD4 turns on shows the board level swing to left, opposite swing direction will turn on LED LD5; similarly LED LD3 turns on shows board level swing to front and opposite direction will turn on LED LD6
- Press User button B1 2nd time, LED LD3 and LD6 turns on
- Connect a mini-USB cable at the USB User socket
- The movement of the Discovery board will take control of the PC mouse pointer
- Press User button B1 3rd time, all LED turns off
- Slide the touchsense buttons and observe the LEDs on/off changes; indicating the position of the finger sliding